

Solutions

Math 3D Quiz 3 Afternoon - February 23rd

Please put name on front & ID on back for redistribution!

Show all of your work. *There is a question on the back side.*

1. [10pts] Find the general solution to $\vec{y}' = \begin{bmatrix} 0 & 4 & -2 \\ -1 & -4 & 1 \\ 0 & 0 & -2 \end{bmatrix} \vec{y}$ using the eigenvalue method.

① Find Eigenvalues. $\det \begin{bmatrix} -\lambda & 4 & -2 \\ -1 & -4-\lambda & 1 \\ 0 & 0 & -2-\lambda \end{bmatrix} = (-2-\lambda)(-1)^{3+3} \det \begin{bmatrix} -\lambda & 4 \\ -1 & -4-\lambda \end{bmatrix}$

2 pts

$= (-2-\lambda)(\lambda^2 + 4\lambda + 4) = -(\lambda+2)^3$ algebraic
 $\lambda = -2$ (multiplicity 3)

②a) Eigenvectors: $(A+2I)\vec{x} = \vec{0}$

$$\begin{bmatrix} 2 & 4 & -2 & | & 0 \\ -1 & -2 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2+2R_1} \begin{bmatrix} 0 & 0 & 0 & | & 0 \\ -1 & -2 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}, \quad -x_1 - 2x_2 + x_3 = 0$$

So, we can write $x_1 = -2x_2 + x_3$
 $x_2 = \text{free}$
 $x_3 = \text{free}$

4 pts

$\vec{x} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

- 2 e-vectors
- Defective Once.

②b) Generalized Eigenvector: Note: If we tried $(A+2I)\vec{y} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$, no solution!

2 pts

$$\hookrightarrow \begin{bmatrix} 2 & 4 & -2 & | & 1 \\ -1 & -2 & 1 & | & 0 \\ 0 & 0 & 0 & | & 1 \end{bmatrix} \text{ Has } 0=1 \text{ in 3rd row (X)}$$

So solve for $(A+2I)\vec{x} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$

$$\rightarrow \begin{bmatrix} 2 & 4 & -2 & | & -2 \\ -1 & -2 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2+2R_1} \begin{bmatrix} 0 & 0 & 0 & | & 0 \\ -1 & -2 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}, \quad -x_1 - 2x_2 + x_3 = 1.$$

(similar to before)

So, $x_1 = -1 - 2x_2 + x_3$
 $x_2 = \text{free}$
 $x_3 = \text{free}$

$\vec{x} = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

(set x_2, x_3 to 0 because free) \hookrightarrow Have 3 vectors for algebraic multiplicity 3 ✓

③ General Soln: $\vec{x}_{\text{general}} = c_1 e^{-2t} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{-2t} \left(\begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \right)$

2 pts

or, using Fundamental Matrix, $\vec{x}_{\text{general}} = \begin{bmatrix} e^{-2t} & -2e^{-2t} & e^{-2t}(-2t-1) \\ 0 & e^{-2t} & te^{-2t} \\ e^{-2t} & 0 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$

Afternoon #1 Eigenvector Remark:

Following from the solutions, $\lambda = -2$ (mult. 3).

When getting eigenvectors: Solving $(P - (-2)I)\vec{x} = \vec{0}$ had

$$\left[\begin{array}{ccc|c} 2 & 4 & -2 & 0 \\ -1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right], \quad \text{Some people had } x_3 = x_1 + 2x_2 \text{ so } x_1, x_2 \text{ free.}$$

$$\Rightarrow \vec{x} = x_1 \underbrace{\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}}_{\vec{v}_1} + x_2 \underbrace{\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}}_{\vec{v}_2} \quad \text{which is still correct!}$$

↳ Just a different basis of e-vects

⚠ But, neither of these gets the ~~the~~ ^{generalized} eigenvector!

The Best Fix: 1st we can't get the 3rd eigenvector due to the last row

↳ Need new 2nd eigenvector, say $\vec{v}_{2,\text{new}} = \vec{v}_2 - 2\vec{v}_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$

because $\vec{v}_{2,\text{new}}$ has consistent last row for solvability.

↳ Can solve $\left[\begin{array}{ccc|c} 2 & 4 & -2 & -2 \\ -1 & -2 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{array}{l} -x_1 - 2x_2 + x_3 = 1, \\ x_1 = \text{free} \\ x_2 = \text{free} \\ x_3 = 1 + x_1 + 2x_2 \end{array}$

$(P + 2I)\vec{v}_3 = \vec{v}_2$

$$\Rightarrow \vec{x} = \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{\vec{v}_3} + x_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

so that $\vec{x}_{\text{general}} = c_1 e^{-2t} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{-2t} \left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \right)$

↖ (used $\vec{v}_{2,\text{new}}$) ↗

Solution Cont'd

2. (a) [3pts] Find the general solution to $mx'' + cx' + kx = 0$ where $m = 1\text{kg}$, $c = 7\text{kg/s}$ and $k = 12\text{N/m}$. Is the physical system underdamped, critically damped, or overdamped?

$$\hookrightarrow x'' + 7x' + 12x = 0, \quad r^2 + 7r + 12 = 0, \quad r = \frac{-7 \pm \sqrt{49 - 48}}{2} = \frac{-7 \pm 1}{2}$$

$$(r+4)(r+3) = 0$$

$$r = -3, -4 \quad +1$$

\hookrightarrow Overdamped +1

and

$$x_{\text{general}} = c_1 e^{-3t} + c_2 e^{-4t} \quad +1$$

(b) [7pts] Reduce the order and write the equivalent 1st order matrix-vector equation. Then, find its general solution by using the eigenvalue method.

+2 $\hookrightarrow x'' = -7x' - 12x$ so $\begin{bmatrix} x \\ x' \end{bmatrix}' = \begin{bmatrix} 0 & 1 \\ -12 & -7 \end{bmatrix} \begin{bmatrix} x \\ x' \end{bmatrix}$ is our 1st order system.

① Eigenvalues: $\det \begin{bmatrix} -\lambda & 1 \\ -12 & -7-\lambda \end{bmatrix} = \lambda^2 + 7\lambda + 12$, $\lambda = -3, -4$ from (a) +1

② Eigenvectors: $\lambda = -3$: $\begin{bmatrix} 3 & 1 & | & 0 \\ -12 & -4 & | & 0 \end{bmatrix} \xrightarrow{(R_2 = -4R_1)} \begin{matrix} 3x_1 + x_2 = 0 \\ x_1 = \text{free} \\ x_2 = -3x_1 \end{matrix}$

$\hookrightarrow (A - \lambda I)\vec{x} = \vec{0}$.

+3

Gets $\vec{x} = x_1 \begin{bmatrix} 1 \\ -3 \end{bmatrix}$

$\lambda = -4$: $\begin{bmatrix} 4 & 1 & | & 0 \\ -12 & -3 & | & 0 \end{bmatrix} \xrightarrow{(R_2 = -3R_1)} \begin{matrix} 4x_1 + x_2 = 0 \\ x_1 = \text{free} \\ x_2 = -4x_1 \end{matrix}$

Gets $\vec{x} = x_1 \begin{bmatrix} 1 \\ -4 \end{bmatrix}$

+1

③ General Solution: $\vec{x}_{\text{general}} = \begin{bmatrix} x \\ x' \end{bmatrix} = c_1 e^{-3t} \begin{bmatrix} 1 \\ -3 \end{bmatrix} + c_2 e^{-4t} \begin{bmatrix} 1 \\ -4 \end{bmatrix}$

Note: Row 1 gets the general solution from (a) ✓