

3-Leibniz bialgebras (3-Lie bialgebras)

A. Rezaei-Aghdam^{a*} L. Sedghi-Ghadim^{b†}

^a*Department of Physics, Azarbaijan Shahid Madani University , 51745-406, Tabriz, Iran.*

^b*Department of Mathematics, Azarbaijan Shahid Madani University , 51745-406, Tabriz, Iran.*

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Abstract

In this paper by use of cohomology complex of 3-Leibniz algebras, the definitions of Leibniz bialgebras (and Lie bialgebras) are extended for the case of 3-Leibniz algebras. Many theorems about Leibniz bialgebras are extended and proved for the case of 3-Leibniz bialgebras (3-Lie bialgebras). Moreover a new theorem on the correspondence between 3-Leibniz bialgebra and its associated Leibniz bialgebra is proved. 3-Lie bialgebra as particular case of the 3-Leibniz bialgebra is investigated. Finally, some simple examples are discussed in detail.

1 Introduction

From historical point of view Kurosh introduced the notion on multilinear operator algebra for the first time in Refs[1, 2]. However, for this algebras one of the most important consequences of Jacobi identity is overlooked i.e., the derivation property of ad_x for an element x of the algebra. Later in [3] Filippov introduced the n -Lie algebra which preserves main properties of Jacobi identity. In Ref[4] the n -Lie modules and representation of n -Lie algebras, generalization of Engel's and Lie's theorems and also Cartan's criterion for solvability of n -Lie algebra have been studied by Kasymov. In the past two decades the study of the n -Leibniz, its cohomology [5], their classifications [6, 7] and deformation of n -Leibniz algebras (see for instance [8]) are under investigation (for a review see [9]). Recently the application of 3-Lie algebra in the M theory [10, 11] has led this branch of

*e-mail:rezaei-a@azaruniv.edu

†e-mail:e-mail:m.sedghi88@azaruniv.edu

mathematics to receive the most attention among physicists [9]. One of the most applicable objects in mathematical physics especially in integrable systems is the Lie bialgebra. In this manner the generalization of the concept of Lie bialgebra to the n -Lie bialgebra (in general) and especially 3-Lie bialgebra is a good problem from the abstract point of view. Indeed there are some attempts in this directions from the co-algebra point of view (see [13] and [14]). Here we will study this facts by use of the cohomology of n -Leibniz algebra [5] for 3-Leibniz algebra in general and then for 3-Lie algebra in particular¹. The outline of the paper is as follows.

In section 2 for self containing of the paper we review the basic definitions and theorems about n -Leibniz [18], n -Lie, its associated Leibniz algebra [19] and Leibniz bialgebra [20].

In section 3 after the separation of first, second and third 3-Leibniz algebra (acording to related identity and related their actions with $\mathcal{A}^{\otimes 3}$ be 3-Leibniz module and related cohomology complex) we give the definition of 3-Leibniz bialgebra (\mathcal{A}, γ) for different i th 3-Leibniz algebra \mathcal{A} . Then as a proposition we show that the dual space \mathcal{A}^* with μ^t is a 3-Leibiz bialgebra. The investigation of 3-Leibniz bialgebra $(\mathcal{A}, \mathcal{A}^*)$ in terms of structure constants of 3-Leibniz algebra \mathcal{A} and \mathcal{A}^* are given in section 4; and at the end of this section some examples of 3-Leibniz bialgebra are obtained by using matrix calculations. As a theorem the correspondence between 3-Leibniz bialgebra and its associated Leibniz bialgebra is given in section 5. In section 6 the definition of 3-Lie bialgebra as a especial case and the reformulation of this definition in terms of structure constants of 3-Lie algebras \mathcal{A} and \mathcal{A}^* is provided. The matrix form of this reformulation is applied for calculation of some low dimensional 3-Lie bialgebras at the end of section 6. Concluding remarks are given in section 7.

2 Basic definitions and theorems

For self containing of the paper let us recall some basic definitions and theorems about n -Leibniz, n -Lie algebras and also Leibniz bialgebra [20].

Definition 2.1 [18] *An n -Leibniz algebra, is a vector space \mathcal{A} equipped with the an n -linear operation $[\cdot, \dots, \cdot] : \mathcal{A}^{\otimes n} \longrightarrow \mathcal{A}$ such that for all x_1, \dots, x_{n-1} the map $ad_{(x_1, \dots, x_{n-1})} : \mathcal{A} \longrightarrow \mathcal{A}$ given by*

$$ad_{(x_1, \dots, x_{n-1})}(x) = [x, x_1, \dots, x_{n-1}], \quad (2.1)$$

is a derivation with respect to $[\cdot, \dots, \cdot]$ i.e.

$$[[y_1, \dots, y_n], x_1, \dots, x_{n-1}] = \sum_{i=1}^n [y_1, \dots, y_{i-1}, [y_i, x_1, \dots, x_{n-1}], y_{i+1}, \dots, y_n], \quad (2.2)$$

¹Note that the Lie algebra is a special case of Leibniz algebra [17].

above identity is called fundamental identity for n -Leibniz algebra.

Definition 2.2 [18] A representation of the n -Leibniz algebra \mathcal{A} is a vector space M equipped with n actions of

$$\rho_j : \mathcal{A}^{\otimes(j-1)} \otimes M \otimes \mathcal{A}^{\otimes(n-j)} \longrightarrow M \quad j = 1, 2, \dots, n,$$

satisfying $2n - 1$ equations, which are obtained from (2.2) by letting exactly one of the variables $x_1, \dots, x_{n-1}, y_1, \dots, y_n$ be in M and all the others in \mathcal{A} . In other word M is an n -Leibniz module. The notion of representation of an n -Leibniz algebra for $n = 2$ coincides with the corresponding notion representation of Leibniz algebra in [17].

Theorem 2.3 [19] Let \mathcal{A} be an n -Leibniz algebra and set $\mathcal{G} := \mathcal{A}^{\otimes(n-1)}$ then there is a Leibniz algebra structure on the space \mathcal{G} with the following bracket:

$$[x_1 \otimes \dots \otimes x_{n-1}, y_1 \otimes \dots \otimes y_n] = \sum_{i=1}^{n-1} y_1 \otimes \dots \otimes y_{i-1} \otimes [x_1, \dots, x_{n-1}, y_i] \otimes y_{i+1} \otimes \dots \otimes y_{n-1}, \quad (2.3)$$

where it is called associated Leibniz algebra.

Definition 2.4 [5, 19] Let \mathcal{A} be an n -Leibniz algebra and $\mathcal{G} := \mathcal{A}^{\otimes(n-1)}$ be its associated Leibniz algebra. The p -cochain of \mathcal{A} ($p \geq 1$) with coefficients in \mathcal{A} is a linear map from $\mathcal{G}^{\otimes(p-1)} \otimes \mathcal{A}$ to \mathcal{A} . Set $\Gamma L^0(\mathcal{A}, \mathcal{A}) := \mathcal{G}$ for the space of 0-cochains and $\Gamma L^p(\mathcal{A}, \mathcal{A})$ for the space of p -cochains. The coboundary map is given by[5]

$$\begin{aligned} d^p : \Gamma L^p(\mathcal{A}, \mathcal{A}) &\longrightarrow \Gamma L^{p+1}(\mathcal{A}, \mathcal{A}) \\ (d^0(x_1 \otimes \dots \otimes x_{n-1}))(x) &= -[x_1, \dots, x_{n-1}, x], \\ (d^p(\alpha)(X_1, \dots, X_{p-1}, Y) &= \sum_{i=1}^{p-2} \sum_{j=i+1}^{p-1} (-1)^i \alpha(X_1, \dots, \widehat{X}_i, \dots, X_{j-1}, [X_i, X_j], X_{j+1}, \dots, X_{p-1}, Y) \\ &+ \sum_{i=1}^{p-1} (-1)^i \alpha(X_1, \dots, \widehat{X}_i, \dots, X_{p-1}, \{X_i, Y\}) \\ &+ (-1)^p \alpha(X_1, \dots, X_{p-1}, [y_1, \dots, y_n]) \\ &+ \sum_{i=1}^{p-1} (-1)^{i+1} \{X_i, \alpha(X_1, \dots, \widehat{X}_i, \dots, X_{p-1}, Y)\} \\ &+ (-1)^{p+1} \sum_{i=1}^n [y_1, \dots, y_{i-1}, \alpha(X_1, \dots, X_{p-1}, y_i), \dots, y_n], \end{aligned} \quad (2.4)$$

where $\alpha \in \Gamma L^p(\mathcal{A}, \mathcal{A})$, $X_i \in \mathcal{G}$ for $i = 1, \dots, p-1$, $Y = y_1 \otimes \dots \otimes y_n \in \mathcal{A}^{\otimes n}$ and for $X \in \mathcal{G}$ of the form $X = x_1 \otimes \dots \otimes x_{n-1}$ we set $\{X, Y\} := \sum_{i=1}^n y_1 \otimes \dots \otimes y_{i-1} \otimes [x_1, \dots, x_{n-1}, y_i] \otimes \dots \otimes y_n$.

Definition 2.5 [20] A Leibniz bialgebra (\mathcal{G}, δ) is a (right or left) Leibniz algebra \mathcal{G} with a linear map (cocommutor) $\delta : \mathcal{G} \longrightarrow \mathcal{G} \otimes \mathcal{G}$ such that

- δ is a 1-cocycle on \mathcal{G} with values in $\mathcal{G} \otimes \mathcal{G}$

$$[X, \delta(Y)]_L + [\delta(X), Y]_R - \delta([X, Y]) = 0, \quad (2.5)$$

where $[\cdot, \cdot]_L$ and $[\cdot, \cdot]_R$ represent the left and right action of \mathcal{G} on $\mathcal{G} \otimes \mathcal{G}$ respectively such that $\mathcal{G} \otimes \mathcal{G}$ becomes a \mathcal{G} -module.

- $\delta^t : \mathcal{G}^* \otimes \mathcal{G}^* \longrightarrow \mathcal{G}^*$ defines a Leibniz bracket on \mathcal{G}^* . If we use the notation $[\xi, \eta]_* = \delta^t(\xi \otimes \eta)$, then $\forall \xi, \eta \in \mathcal{G}^*$ and $\forall X \in \mathcal{G}$ we have

$$\prec [\xi, \eta]_*, X \succ = \prec \delta^t(\xi \otimes \eta), X \succ = \prec \xi \otimes \eta, \delta(X), \succ, \quad (2.6)$$

where \prec, \succ is the natural pairing between \mathcal{G} and \mathcal{G}^* .

Note that with respect to the type of the Leibniz algebra \mathcal{G} and also its actions on the $\mathcal{G} \otimes \mathcal{G}$; the 1-cocycle condition (2.5) can be rewritten in the following forms:

$$\delta([X, Y]) = [X, \delta(Y)]_L + [\delta(X), Y]_R := (ad_X^{(l)} \otimes 1)(\delta(Y)) + (ad_Y^{(r)} \otimes 1)(\delta(X)), \quad (2.7)$$

$$\delta([X, Y]) = [X, \delta(Y)]_L + [\delta(X), Y]_R := (1 \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1)(\delta(X)), \quad (2.8)$$

$$\delta([X, Y]) = [X, \delta(Y)]_L + [\delta(X), Y]_R := (1 \otimes ad_X^{(l)} + ad_X^{(l)} \otimes 1)(\delta(Y)), \quad (2.9)$$

$$\delta([X, Y]) = [X, \delta(Y)]_L + [\delta(X), Y]_R := (1 \otimes ad_X^{(l)})(\delta(Y)) + (1 \otimes ad_Y^{(r)})(\delta(X)). \quad (2.10)$$

that in cases (2.7) and (2.10) \mathcal{G} can be left or right Leibniz algebra and in case (2.8) ((2.9)) \mathcal{G} is a right (left) Leibniz algebra.

Definition 2.6 [3] An n -Lie algebra $(\mathcal{A}, [\cdot, \dots, \cdot])$ is a vector space over a field F together with a skew-symmetric n -linear map $[\cdot, \dots, \cdot] : \mathcal{A}^{\otimes n} \longrightarrow \mathcal{A}$ such that

$$[x_1, \dots, x_{n-1}, [y_1, \dots, y_n]] = \sum_{i=1}^n [y_1, \dots, [x_1, \dots, x_{n-1}, y_i], y_{i+1}, \dots, y_n],$$

for all $x_1, \dots, x_{n-1}, y_1, \dots, y_n \in \mathcal{A}$. This condition is called the fundamental identity or the Filippov identity.

Definition 2.7 [4] If \mathcal{A} is an n -Lie algebra over a field F and V is a vector space over F then a polylinear mapping $\rho : \mathcal{A}^{\otimes n-1} \longrightarrow \text{End}(V)$ is said to be a representation of \mathcal{A} in V if the operators $\rho(x_1, \dots, x_{n-1}), \forall x_i \in \mathcal{A}$ be skew-symmetric functions of their arguments and satisfy the identities

$$[\rho(x_1, \dots, x_{n-1}), \rho(y_1, \dots, y_{n-1})] = \sum_{i=1}^{n-1} \rho(y_1, \dots, y_{i-1}, [x_1, \dots, x_{n-1}, y_i], y_{i+1}, \dots, y_{n-1}), \quad (2.11)$$

$$\rho(x_1, \dots, x_{n-2}, [y_1, \dots, y_n]) = \sum_{i=1}^n (-1)^{i+1} \rho(y_1, \dots, \hat{y}_i, \dots, y_n) \rho(x_1, \dots, x_{n-2}, y_i), \quad (2.12)$$

where $x_1, \dots, x_{n-1}, y_1, \dots, y_{n-1} \in \mathcal{A}$. In this case, V is said to be an (n -Lie) \mathcal{A} -module. For example for $n = 3$ we have

$$[\rho(x_1, x_2), \rho(y_1, y_2)] = \rho([x_1, x_2, y_1], y_2) + \rho(y_1, [x_1, x_2, y_2]), \quad (2.13)$$

$$\rho(x_1, [y_1, y_2, y_3]) = \rho(y_2, y_3)\rho(x_1, y_2) - \rho(y_1, y_3)\rho(x_1, y_2) + \rho(y_1, y_2)\rho(x_1, y_3). \quad (2.14)$$

Definition 2.8 [19] Let \mathcal{A} be a 3-Lie algebra, an \mathcal{A} -valued p -cochain is a linear map $\psi : (\mathcal{A} \otimes \mathcal{A})^{\otimes(p-1)} \otimes \mathcal{A} \longrightarrow \mathcal{A}$ and the coboundary operator is given by:

$$\begin{aligned} d^p \psi(x_1, \dots, x_{2p+1}) &= \sum_{j=1}^p \sum_{k=2j+1}^{2p+1} (-1)^j \psi(x_1, \dots, \hat{x}_{j-1}, \hat{x}_j, \dots, [x_{2j-1}, x_{2j}, x_k], \dots, x_{2p+1}) \\ &+ \sum_{k=1}^p [x_{2k-1}, x_{2k}, \psi(x_1, \dots, \hat{x}_{2k-1}, \hat{x}_{2k}, \dots, x_{2p+1})] \\ &+ (-1)^{p+1} [x_{2p-1}, \psi(x_1, \dots, x_{2p-2}, x_{2p}), x_{2p+1}] \\ &+ (-1)^{p+1} [\psi(x_1, \dots, x_{2p-1}), x_{2p}, x_{2p+1}] \end{aligned}$$

3 3-Leibniz bialgebras

Since $[\cdot, \dots, \cdot]$ in n -Leibniz algebra is not antisymmetric hence we define for all x_1, \dots, x_n in \mathcal{A} the map $ad_{(x_1, \dots, \hat{x}_i, \dots, x_n)} : \mathcal{A} \longrightarrow \mathcal{A}$ as follows:

$$ad_{(x_1, \dots, \hat{x}_i, \dots, x_n)}(x) = [x_1, \dots, x_{i-1}, x, x_{i+1}, \dots, x_n], \quad \text{for } i = 1, \dots, n \quad (3.1)$$

Definition 3.1 An i -th n -Leibniz algebra, is a vector space \mathcal{A} equipped with an n -linear operation $[\cdot, \dots, \cdot] : \mathcal{A}^{\otimes n} \longrightarrow \mathcal{A}$ such that map $ad_{(x_1, \dots, \hat{x}_i, \dots, x_n)}$ is a derivation with respect to $[\cdot, \dots, \cdot]$ i.e.

$$[x_1, \dots, x_{i-1}, [y_1, \dots, y_n], x_{i+1}, \dots, x_n] = \sum_{j=1}^n [y_1, \dots, y_{j-1}, [x_1, \dots, x_{i-1}, y_j, x_{i+1}, \dots, x_n], y_{j+1}, \dots, y_n], \quad (3.2)$$

therefore, for any i we have an identity and n -Leibniz algebra that it is called i -th n -Leibniz algebra.

Remark 3.2 In [18] and [5] $ad_{(x_1, \dots, \hat{x}_i, \dots, x_n)}$ is considered as a derivation with respect to $[\cdot, \dots, \cdot]$ and for the cases $i = n$ and $i = 1$ such that the i -th n -Leibniz algebras for $i = 2, \dots, n-1$ have not been considered.

For $n = 3$ we have three 3-Leibniz identities

- If $ad_{(\hat{x}_1, x_2, x_3)}$ is a derivation with respect to $[\cdot, \cdot, \cdot]$ then we have the first 3-Leibniz identity as follows:

$$[[y_1, y_2, y_3], x_2, x_3] = [[y_1, x_2, x_3], y_2, y_3] + [y_1, [y_2, x_2, x_3], y_3] + [y_1, y_2, [y_3, x_2, x_3]]. \quad (3.3)$$

- If $ad_{(x_1, \widehat{x_2}, x_3)}$ is a derivation with respect to $[., ., .]$ then we have the second 3-Leibniz identity as follows:

$$[x_1, [y_1, y_2, y_3], x_3] = [[x_1, y_1, x_3], y_2, y_3] + [y_1, [x_1, y_2, x_3], y_3] + [y_1, y_2, [x_1, y_3, x_3]]. \quad (3.4)$$

- If $ad_{(x_1, x_2, \widehat{x_3})}$ is a derivation with respect to $[., ., .]$ then we have the third 3-Leibniz identity as follows:

$$[x_1, x_2, [y_1, y_2, y_3]] = [[x_1, x_2, y_1], y_2, y_3] + [y_1, [x_1, x_2, y_2], y_3] + [y_1, y_2, [x_1, x_2, y_3]]. \quad (3.5)$$

Before defining the 3-Leibniz bialgebra let us define special actions such that $\mathcal{A}^{\otimes 3}$ be 3-Leibniz module. We define the following cases of the actions such that $\mathcal{A}^{\otimes 3}$ be 3-Leibniz module.

- If \mathcal{A} is the first 3-Leibniz algebra.

$$\begin{aligned} \rho_1 &: \mathcal{A}^{\otimes 3} \otimes \mathcal{A}^{\otimes 2} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_1(y_1 \otimes y_2 \otimes y_3, x_2, x_3) &:= ad_{(\widehat{x_1}, x_2, x_3)}^{(3)}(y_1 \otimes y_2 \otimes y_3), \\ &= (ad_{(\widehat{x_1}, x_2, x_3)} \otimes 1 \otimes 1 + 1 \otimes ad_{(\widehat{x_1}, x_2, x_3)} \otimes 1 + 1 \otimes 1 \otimes ad_{(\widehat{x_1}, x_2, x_3)})(y_1 \otimes y_2 \otimes y_3) \\ &= [y_1, x_2, x_3] \otimes y_2 \otimes y_3 + y_1 \otimes [y_2, x_2, x_3] \otimes y_3 + y_1 \otimes y_2 \otimes [y_3, x_2, x_3], \\ \rho_2 &: \mathcal{A} \otimes \mathcal{A}^{\otimes 3} \otimes \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_2(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &= 0, \\ \rho_3 &: \mathcal{A}^{\otimes 2} \otimes \mathcal{A}^{\otimes 3} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_3(x_1, x_2, y_1 \otimes y_2 \otimes y_3) &= 0. \end{aligned} \quad (3.6)$$

$$\begin{aligned} \rho_1 &: \mathcal{A}^{\otimes 3} \otimes \mathcal{A}^{\otimes 2} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_1(y_1 \otimes y_2 \otimes y_3, x_2, x_3) &:= (ad_{(\widehat{x_1}, x_2, x_3)} \otimes 1 \otimes 1)(y_1 \otimes y_2 \otimes y_3) = [y_1, x_2, x_3] \otimes y_2 \otimes y_3, \\ \rho_2 &: \mathcal{A} \otimes \mathcal{A}^{\otimes 3} \otimes \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_2(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &= (ad_{(x_1, \widehat{x_2}, x_3)} \otimes 1 \otimes 1)(y_1 \otimes y_2 \otimes y_3) = [x_1, y_1, x_3] \otimes y_2 \otimes y_3, \\ \rho_3 &: \mathcal{A}^{\otimes 2} \otimes \mathcal{A}^{\otimes 3} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_3(x_1, x_2, y_1 \otimes y_2 \otimes y_3) &= (ad_{(x_1, x_2, \widehat{x_3})} \otimes 1 \otimes 1)(y_1 \otimes y_2 \otimes y_3) = [x_1, x_2, y_1] \otimes y_2 \otimes y_3. \end{aligned} \quad (3.7)$$

$$\begin{aligned} \rho_1 &: \mathcal{A}^{\otimes 3} \otimes \mathcal{A}^{\otimes 2} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_1(y_1 \otimes y_2 \otimes y_3, x_2, x_3) &:= (1 \otimes ad_{(\widehat{x_1}, x_2, x_3)} \otimes 1)(y_1 \otimes y_2 \otimes y_3) = y_1 \otimes [y_2, x_2, x_3] \otimes y_3, \\ \rho_2 &: \mathcal{A} \otimes \mathcal{A}^{\otimes 3} \otimes \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_2(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &= (1 \otimes ad_{(x_1, \widehat{x_2}, x_3)} \otimes 1)(y_1 \otimes y_2 \otimes y_3) = y_1 \otimes [x_1, y_2, x_3] \otimes y_3, \\ \rho_3 &: \mathcal{A}^{\otimes 2} \otimes \mathcal{A}^{\otimes 3} \longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_3(x_1, x_2, y_1 \otimes y_2 \otimes y_3) &= (1 \otimes ad_{(x_1, x_2, \widehat{x_3})} \otimes 1)(y_1 \otimes y_2 \otimes y_3) = y_1 \otimes [x_1, x_2, y_2] \otimes y_3. \end{aligned} \quad (3.8)$$

$$\begin{aligned}
\rho_1 &: \mathcal{A}^{\otimes 3} \otimes \mathcal{A}^{\otimes 2} \longrightarrow \mathcal{A}^{\otimes 3}, \\
\rho_1(y_1 \otimes y_2 \otimes y_3, x_2, x_3) &:= (1 \otimes 1 \otimes ad_{(\widehat{x_1, x_2, x_3})})(y_1 \otimes y_2 \otimes y_3) = y_1 \otimes y_2 \otimes [y_3, x_2, x_3], \\
\rho_2 &: \mathcal{A} \otimes \mathcal{A}^{\otimes 3} \otimes \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}, \\
\rho_2(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &= (1 \otimes 1 \otimes ad_{(x_1, \widehat{x_2, x_3})})(y_1 \otimes y_2 \otimes y_3) = y_1 \otimes y_2 \otimes [x_1, y_3, x_3], \\
\rho_3 &: \mathcal{A}^{\otimes 2} \otimes \mathcal{A}^{\otimes 3} \longrightarrow \mathcal{A}^{\otimes 3}, \\
\rho_3(x_1, x_2, y_1 \otimes y_2 \otimes y_3) &= (1 \otimes 1 \otimes ad_{(x_1, x_2, \widehat{x_3})})(y_1 \otimes y_2 \otimes y_3) = y_1 \otimes y_2 \otimes [x_1, x_2, y_3]. \quad (3.9)
\end{aligned}$$

Above actions for all $z_1 \otimes z_2 \otimes z_3 \in \mathcal{A}^{\otimes 3}$ and $x_2, x_3, y_1, y_2, y_3 \in \mathcal{A}$ satisfy in the following identities:

$$\begin{aligned}
\rho_1(\rho_1(z_1 \otimes z_2 \otimes z_3, y_2, y_3), x_2, x_3) &= \rho_1(\rho_1(z_1 \otimes z_2 \otimes z_3, x_2, x_3), y_2, y_3) \\
&+ \rho_1(z_1 \otimes z_2 \otimes z_3, [y_2, x_2, x_3], y_3) + \rho_1(z_1 \otimes z_2 \otimes z_3, y_2, [y_3, x_2, x_3]), \quad (3.10)
\end{aligned}$$

$$\begin{aligned}
\rho_1(\rho_2(y_1, z_1 \otimes z_2 \otimes z_3, y_3), x_2, x_3) &= \rho_2([y_1, x_2, x_3], z_1 \otimes z_2 \otimes z_3, y_3) \\
&+ \rho_2(y_1, \rho_1(z_1 \otimes z_2 \otimes z_3, x_2, x_3), y_3) + \rho_2(y_1, z_1 \otimes z_2 \otimes z_3, [y_3, x_2, x_3]), \quad (3.11)
\end{aligned}$$

$$\begin{aligned}
\rho_1(\rho_3(y_1, y_2, z_1 \otimes z_2 \otimes z_3), x_2, x_3) &= \rho_3([y_1, x_2, x_3], y_2, z_1 \otimes z_2 \otimes z_3) \\
&+ \rho_3(y_1, [y_2, x_2, x_3], z_1 \otimes z_2 \otimes z_3) + \rho_3(y_1, y_2, \rho_1(z_1 \otimes z_2 \otimes z_3, x_2, x_3)), \quad (3.12)
\end{aligned}$$

$$\begin{aligned}
\rho_2([y_1, y_2, y_3], z_1 \otimes z_2 \otimes z_3, x_3) &= \rho_1(\rho_2(y_1, z_1 \otimes z_2 \otimes z_3, x_3), y_2, y_3) \\
&+ \rho_2(y_1, \rho_2(y_2, z_1 \otimes z_2 \otimes z_3, x_3), y_3) + \rho_3(y_1, y_2, \rho_2(y_3, z_1 \otimes z_2 \otimes z_3, x_3)), \quad (3.13)
\end{aligned}$$

$$\begin{aligned}
\rho_3([y_1, y_2, y_3], x_2, z_1 \otimes z_2 \otimes z_3) &= \rho_1(\rho_3(y_1, x_2, z_1 \otimes z_2 \otimes z_3), y_2, y_3) \\
&+ \rho_2(y_1, \rho_3(y_2, x_2, z_1 \otimes z_2 \otimes z_3), y_3) + \rho_3(y_1, y_2, \rho_3(y_3, x_2, z_1 \otimes z_2 \otimes z_3)). \quad (3.14)
\end{aligned}$$

- If \mathcal{A} is the second 3-Leibniz algebra then we have the actions (3.7) – (3.9) and following action:

$$\begin{aligned}
\rho_1 &: \mathcal{A}^{\otimes 3} \otimes \mathcal{A}^{\otimes 2} \longrightarrow \mathcal{A}^{\otimes 3}, \\
\rho_1(y_1 \otimes y_2 \otimes y_3, x_2, x_3) &= 0, \\
\rho_2 &: \mathcal{A} \otimes \mathcal{A}^{\otimes 3} \otimes \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}, \\
\rho_2(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &:= ad_{(x_1, \widehat{y_2, y_3})}^{(3)}(y_1 \otimes y_2 \otimes y_3) \\
&= (ad_{(x_1, \widehat{y_2, y_3})} \otimes 1 \otimes 1 + 1 \otimes ad_{(x_1, \widehat{y_2, y_3})} \otimes 1 + 1 \otimes 1 \otimes ad_{(x_1, \widehat{y_2, y_3})})(y_1 \otimes y_2 \otimes y_3) \\
&= [x_1, y_1, x_3] \otimes y_2 \otimes y_3 + y_1 \otimes [x_1, y_2, x_3] \otimes y_3 + y_1 \otimes y_2 \otimes [x_1, y_3, x_3], \\
\rho_3 &: \mathcal{A}^{\otimes 2} \otimes \mathcal{A}^{\otimes 3} \longrightarrow \mathcal{A}^{\otimes 3}, \\
\rho_3(x_1, x_2, y_1 \otimes y_2 \otimes y_3) &= 0. \quad (3.15)
\end{aligned}$$

which satisfies in the following identities:

$$\begin{aligned} \rho_1(z_1 \otimes z_2 \otimes z_3, [y_1, y_2, y_3], x_3) &= \rho_1(\rho_1(z_1 \otimes z_2 \otimes z_3, y_1, x_3), y_2, y_3) \\ &+ \rho_2(y_1, \rho_1(z_1 \otimes z_2 \otimes z_3, y_2, x_3), y_3) + \rho_3(y_1, y_2, \rho_1(z_1 \otimes z_2 \otimes z_3, y_3, x_3)), \end{aligned} \quad (3.16)$$

$$\begin{aligned} \rho_2(x_1, \rho_1(z_1 \otimes z_2 \otimes z_3, y_2, y_3), x_3) &= \rho_1(\rho_2(x_1, z_1 \otimes z_2 \otimes z_3, x_3), y_2, y_3) \\ &+ \rho_1(z_1 \otimes z_2 \otimes z_3, [x_1, y_2, x_3], y_3) + \rho_1(z_1 \otimes z_2 \otimes z_3, y_2, [x_1, y_3, x_3]), \end{aligned} \quad (3.17)$$

$$\begin{aligned} \rho_2(x_1, \rho_2(y_1, z_1 \otimes z_2 \otimes z_3, y_3), x_3) &= \rho_2([x_1, y_1, x_3], z_1 \otimes z_2 \otimes z_3, y_3) \\ &+ \rho_2(y_1, \rho_2(x_1, z_1 \otimes z_2 \otimes z_3, x_3), y_3) + \rho_2(y_1, z_1 \otimes z_2 \otimes z_3, [x_1, y_3, x_3]), \end{aligned} \quad (3.18)$$

$$\begin{aligned} \rho_2(x_1, \rho_3(y_1, y_2, z_1 \otimes z_2 \otimes z_3), x_3) &= \rho_3([x_1, y_1, x_3], y_2, z_1 \otimes z_2 \otimes z_3) \\ &+ \rho_3(y_1, [x_1, y_2, x_3], z_1 \otimes z_2 \otimes z_3) + \rho_3(y_1, y_2, \rho_2(x_1, z_1 \otimes z_2 \otimes z_3, x_3)), \end{aligned} \quad (3.19)$$

$$\begin{aligned} \rho_3(x_1, [y_1, y_2, y_3], z_1 \otimes z_2 \otimes z_3) &= \rho_1(\rho_3(x_1, y_1, z_1 \otimes z_2 \otimes z_3), y_2, y_3) \\ &+ \rho_2(y_1, \rho_3(x_1, y_2, z_1 \otimes z_2 \otimes z_3), y_3) + \rho_3(y_1, y_2, \rho_3(x_1, y_3, z_1 \otimes z_2 \otimes z_3)). \end{aligned} \quad (3.20)$$

- If \mathcal{A} is the third 3-Leibniz algebra then we have the actions (3.7) – (3.9) and following action:

$$\begin{aligned} \rho_1 : \mathcal{A}^{\otimes 3} \otimes \mathcal{A}^{\otimes 2} &\longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_1(y_1 \otimes y_2 \otimes y_3, x_2, x_3) &= 0, \\ \rho_2 : \mathcal{A} \otimes \mathcal{A}^{\otimes 3} \otimes \mathcal{A} &\longrightarrow \mathcal{A}^{\otimes 3}, \\ \rho_2(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &= 0, \\ \rho_3(x_1, y_1 \otimes y_2 \otimes y_3, x_3) &:= ad_{(x_1, x_2, \widehat{x_3})}^{(3)}(y_1 \otimes y_2 \otimes y_3) \\ &= (ad_{(x_1, x_2, \widehat{x_3})} \otimes 1 \otimes 1 + 1 \otimes ad_{(x_1, x_2, \widehat{x_3})} \otimes 1 + 1 \otimes 1 \otimes ad_{(x_1, x_2, \widehat{x_3})})(y_1 \otimes y_2 \otimes y_3) \\ &= [x_1, x_2, y_1] \otimes y_2 \otimes y_3 + y_1 \otimes [x_1, x_2, y_2] \otimes y_3 + y_1 \otimes y_2 \otimes [x_1, x_2, y_3]. \end{aligned} \quad (3.21)$$

which satisfies in the following identities:

$$\begin{aligned} \rho_1(z_1 \otimes z_2 \otimes z_3, x_2, [y_1, y_2, y_3]) &= \rho_1(\rho_1(z_1 \otimes z_2 \otimes z_3, x_2, y_1), y_2, y_3) \\ &+ \rho_2(y_1, \rho_1(z_1 \otimes z_2 \otimes z_3, x_2, y_2), y_3) + \rho_3(y_1, y_2, \rho_1(z_1 \otimes z_2 \otimes z_3, x_2, y_3)), \end{aligned} \quad (3.22)$$

$$\begin{aligned} \rho_2(x_1, z_1 \otimes z_2 \otimes z_3, [y_1, y_2, y_3]) &= \rho_1(\rho_2(x_1, z_1 \otimes z_2 \otimes z_3, y_1), y_2, y_3) \\ &+ \rho_2(y_1, \rho_2(x_1, z_1 \otimes z_2 \otimes z_3, y_2), y_3) + \rho_3(y_1, y_2, \rho_2(x_1, z_1 \otimes z_2 \otimes z_3, y_3)), \end{aligned} \quad (3.23)$$

$$\begin{aligned} \rho_3(x_1, x_2, \rho_1(z_1 \otimes z_2 \otimes z_3, y_2, y_3)) &= \rho_1(\rho_3(x_1, x_2, z_1 \otimes z_2 \otimes z_3), y_2, y_3) \\ &+ \rho_1(z_1 \otimes z_2 \otimes z_3, [x_1, x_2, y_2], y_3) + \rho_1(z_1 \otimes z_2 \otimes z_3, y_2, [x_1, x_2, y_3]), \end{aligned} \quad (3.24)$$

$$\begin{aligned} \rho_3(x_1, x_2, \rho_2(y_1, z_1 \otimes z_2 \otimes z_3, y_3)) &= \rho_2([x_1, x_2, y_1], z_1 \otimes z_2 \otimes z_3, y_3) \\ &+ \rho_2(y_1, \rho_3(x_1, x_2, z_1 \otimes z_2 \otimes z_3), y_3) + \rho_2(y_1, z_1 \otimes z_2 \otimes z_3, [x_1, x_2, y_3]), \end{aligned} \quad (3.25)$$

$$\begin{aligned} \rho_3(x_1, x_2, \rho_3(y_1, y_2, z_1 \otimes z_2 \otimes z_3)) &= \rho_3([x_1, x_2, y_1], y_2, z_1 \otimes z_2 \otimes z_3) \\ &+ \rho_3(y_1, [x_1, x_2, y_2], z_1 \otimes z_2 \otimes z_3) + \rho_3(y_1, y_2, \rho_3(x_1, x_2, z_1 \otimes z_2 \otimes z_3)). \end{aligned} \quad (3.26)$$

In the following definition we suppose that \mathcal{A} be a 3-Leibniz algebra and $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be its associated Leibniz algebra and M is a representation of \mathcal{A} . We generalize the p -cochain of \mathcal{A} ($p \geq 1$) with coefficients in \mathcal{A} to p -cochain of \mathcal{A} ($p \geq 1$) with coefficients in M and also the corresponding coboundary map is defined.

Definition 3.3 *Since we have three types of 3-Leibniz algebra we define cohomology complex for them separately.*

1. If \mathcal{A} be the first 3-Leibniz algebra then $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with the following bracket

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [x_1, y_1, y_2] \otimes x_2 + x_1 \otimes [x_2, y_1, y_2],$$

is a right Leibniz algebra. The p -cochain of \mathcal{A} ($p \geq 1$) with coefficients in M is a linear map from $\mathcal{A} \otimes \mathcal{G}^{\otimes(p-1)}$ to M . Set also $\Gamma L^0(\mathcal{A}, M) := \mathcal{A} \otimes M$. The space of p -cochains is denoted by $\Gamma L^p(\mathcal{A}, M)$. The coboundary map is given by

$$\begin{aligned} d^p : \Gamma L^p(\mathcal{A}, M) &\longrightarrow \Gamma L^{p+1}(\mathcal{A}, M) \\ (d^0(x \otimes m))(y) &= -\rho_3(y, x, m), \quad \forall x, y \in \mathcal{A}, \forall m \in M \end{aligned}$$

$$\begin{aligned} (d^p(\alpha)(Y, X_1, \dots, X_{p-1})) &= \sum_{i=1}^{p-2} \sum_{j=i+1}^{p-1} (-1)^i \alpha(Y, X_1, \dots, \widehat{X}_i, \dots, X_{j-1}, [X_i, X_j], X_{j+1}, \dots, X_{p-1}) \\ &+ \sum_{i=1}^{p-1} (-1)^i \alpha(\{X_i, Y\}, X_1, \dots, \widehat{X}_i, \dots, X_{p-1}) \\ &+ (-1)^p \alpha([y_1, y_2, y_3], X_1, \dots, X_{p-1}) \\ &+ \sum_{i=1}^{p-1} (-1)^{i+1} \rho_1(\alpha(Y, X_1, \dots, \widehat{X}_i, \dots, X_{p-1}), X_i) \\ &+ (-1)^{p+1} \sum_{i=1}^3 \rho_i(y_1, \dots, y_{i-1}, \alpha(y_i, X_1, \dots, X_{p-1}), \dots, y_3), \end{aligned} \quad (3.27)$$

where $X_i \in \mathcal{G}$ for $i = 1, \dots, p-1$, $Y = y_1 \otimes y_2 \otimes y_3 \in \mathcal{A}^{\otimes 3}$ and for $X \in \mathcal{G}$ of the form $X = x_1 \otimes x_2$ we set $\{X, Y\} := \sum_{i=1}^3 y_1 \otimes \dots \otimes y_{i-1} \otimes [y_i, x_1, x_2] \otimes \dots \otimes y_3$. In this case we

have

$$\begin{aligned}
d^1 : \Gamma L^1(\mathcal{A}, M) &\longrightarrow \Gamma L^2(\mathcal{A}, M) \\
(d^1 \alpha)(y_1 \otimes y_2 \otimes y_3) &= -\alpha([y_1, y_2, y_3]) + \rho_1(\alpha(y_1), y_2, y_3) + \rho_2(y_1, \alpha(y_2), y_3) + \rho_3(y_1, y_2, \alpha(y_3))
\end{aligned} \tag{3.28}$$

$$\begin{aligned}
d^2 : \Gamma L^2(\mathcal{A}, M) &\longrightarrow \Gamma L^3(\mathcal{A}, M) \\
d^2(\alpha)(y_1 \otimes y_2 \otimes y_3 \otimes x_1 \otimes x_2) &= -\alpha([y_1, x_1, x_2], y_2, y_3) - \alpha(y_1, [y_2, x_1, x_2], y_3) \\
&- \alpha(y_1, y_2, [y_3, x_1, x_2]) + \alpha([y_1, y_2, y_3], x_1, x_2) + \rho_1(\alpha(y_1, y_2, y_3), x_1, x_2) - \rho_1(\alpha(y_1, x_1, x_2), y_2, y_3) \\
&- \rho_2(y_1, \alpha(y_2, x_1, x_2), y_3) - \rho_3(y_1, y_2, \alpha(y_3, x_1, x_2)).
\end{aligned} \tag{3.29}$$

2. If \mathcal{A} be the second 3-Leibniz algebra then $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with the following bracket

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [x_1, y_1, x_2] \otimes y_2 + y_1 \otimes [x_1, y_2, x_2],$$

is a left Leibniz algebra and with the following bracket is right Leibniz algebra.

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [y_1, x_1, y_2] \otimes x_2 + x_1 \otimes [y_1, x_2, y_2].$$

The p -cochain of \mathcal{A} ($p \geq 2$) with coefficients in M is a linear map from $\mathcal{A}^{\otimes 3} \otimes \mathcal{G}^{\otimes (p-2)}$ to M . Set also $\Gamma L^0(\mathcal{A}, M) := M \otimes \mathcal{A}$ and $\Gamma L^1(\mathcal{A}, M)$ is a linear map from \mathcal{A} to M . The space of p -cochains is denoted by $\Gamma L^p(\mathcal{A}, M)$. The coboundary map is given by

$$\begin{aligned}
d^p : \Gamma L^p(\mathcal{A}, M) &\longrightarrow \Gamma L^{p+1}(\mathcal{A}, M) \\
(d^0(m \otimes x))(y) &= -\rho_1(m, y, x), \quad \forall x, y \in \mathcal{A}, \forall m \in M
\end{aligned}$$

$$\begin{aligned}
(d^p(\alpha)(Y, X_1, \dots, X_{p-1})) &= \sum_{i=1}^{p-2} \sum_{j=i+1}^{p-1} (-1)^i \alpha(Y, X_1, \dots, \widehat{X}_i, \dots, X_{j-1}, [X_i, X_j], X_{j+1}, \dots, X_{p-1}) \\
&+ \sum_{i=1}^{p-1} (-1)^i \alpha(\{X_i, Y\}, X_1, \dots, \widehat{X}_i, \dots, X_{p-1}) \\
&+ (-1)^p \alpha(x_1^1, [y_1, y_2, y_3], x_1^2, X_2, \dots, X_{p-1}) \\
&+ \sum_{i=1}^{p-1} (-1)^{i+1} \rho_2(x_i^1, \alpha(Y, X_1, \dots, \widehat{X}_i, \dots, X_{p-1}), x_i^2) \\
&+ (-1)^{p+1} \sum_{i=1}^3 \rho_i(y_1, \dots, y_{i-1}, \alpha(x_1^1, y_i, x_1^2, \dots, X_{p-1}), \dots, y_3), \tag{3.30}
\end{aligned}$$

where $X_i \in \mathcal{G}$ for $i = 1, \dots, p-1$, $Y = y_1 \otimes y_2 \otimes y_3 \in \mathcal{A}^{\otimes 3}$ and for $X_i \in \mathcal{G}$ of the form $X_i = x_i^1 \otimes x_i^2$ we set $\{X_i, Y\} := \sum_{j=1}^3 y_1 \otimes \dots \otimes y_{j-1} \otimes [x_i^1, y_j, x_i^2] \otimes \dots \otimes y_3$. In this case we

have

$$\begin{aligned}
d^1 : \Gamma L^1(\mathcal{A}, M) &\longrightarrow \Gamma L^2(\mathcal{A}, M) \\
(d^1 \alpha)(y_1 \otimes y_2 \otimes y_3) &= -\alpha([y_1, y_2, y_3]) + \rho_1(\alpha(y_1), y_2, y_3) + \rho_2(y_1, \alpha(y_2), y_3) + \rho_3(y_1, y_2, \alpha(y_3))
\end{aligned} \tag{3.31}$$

$$\begin{aligned}
d^2 : \Gamma L^2(\mathcal{A}, M) &\longrightarrow \Gamma L^3(\mathcal{A}, M) \\
d^2(\alpha)(y_1 \otimes y_2 \otimes y_3 \otimes x_1 \otimes x_2) &= -\alpha([x_1, y_1, x_2], y_2, y_3) - \alpha(y_1, [x_1, y_2, x_2], y_3) \\
&- \alpha(y_1, y_2, [x_1, y_3, x_2]) + \alpha(x_1, [y_1, y_2, y_3], x_2) + \rho_2(x_1, \alpha(y_1, y_2, y_3), x_2) - \rho_1(\alpha(x_1, y_1, x_2), y_2, y_3) \\
&- \rho_2(y_1, \alpha(x_1, y_2, x_2), y_3) - \rho_3(y_1, y_2, \alpha(x_1, y_3, x_2)).
\end{aligned} \tag{3.32}$$

3. If \mathcal{A} be the third 3-Leibniz algebra then $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with the following bracket

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [x_1, x_2, y_1] \otimes y_2 + y_1 \otimes [x_1, x_2, y_2],$$

is a left Leibniz algebra. The p -cochain of \mathcal{A} ($p \geq 1$) with coefficients in M is a linear map from $\mathcal{G}^{\otimes(p-1)} \otimes \mathcal{A}$ to M . Set also $\Gamma L^0(\mathcal{A}, M) := M \otimes \mathcal{A}$. The space of p -cochains is denoted by $\Gamma L^p(\mathcal{A}, M)$. The coboundary map is given by

$$\begin{aligned}
d^p : \Gamma L^p(\mathcal{A}, M) &\longrightarrow \Gamma L^{p+1}(\mathcal{A}, M) \\
(d^0(m \otimes x))(y) &= -\rho_1(m, x, y), \quad \forall x, y \in \mathcal{A}, \forall m \in M
\end{aligned}$$

$$\begin{aligned}
(d^p(\alpha))(X_1, \dots, X_{p-1}, Y) &= \sum_{i=1}^{p-2} \sum_{j=i+1}^{p-1} (-1)^i \alpha(X_1, \dots, \widehat{X}_i, \dots, X_{j-1}, [X_i, X_j], X_{j+1}, \dots, X_{p-1}, Y) \\
&+ \sum_{i=1}^{p-1} (-1)^i \alpha(X_1, \dots, \widehat{X}_i, \dots, X_{p-1}, \{X_i, Y\}) \\
&+ (-1)^p \alpha(X_1, \dots, X_{p-1}, [y_1, y_2, y_3]) \\
&+ \sum_{i=1}^{p-1} (-1)^{i+1} \rho_3(X_i, \alpha(X_1, \dots, \widehat{X}_i, \dots, X_{p-1}, Y)) \\
&+ (-1)^{p+1} \sum_{i=1}^3 \rho_i(y_1, \dots, y_{i-1}, \alpha(X_1, \dots, X_{p-1}, y_i), \dots, y_3), \tag{3.33}
\end{aligned}$$

where $X_i \in \mathcal{G}$ for $i = 1, \dots, p-1, Y = y_1 \otimes y_2 \otimes y_3 \in \mathcal{A}^{\otimes 3}$ and for $X \in \mathcal{G}$ of the form $X_i = x_i^1 \otimes x_i^2$ we set $\{X_i, Y\} := \sum_{j=1}^3 y_1 \otimes \dots \otimes y_{j-1} \otimes [x_i^1, x_i^2, y_j] \otimes \dots \otimes y_3$. In this case we

have

$$\begin{aligned}
d^1 : \Gamma L^1(\mathcal{A}, M) &\longrightarrow \Gamma L^2(\mathcal{A}, M) \\
(d^1\alpha)(y_1 \otimes y_2 \otimes y_3) &= -\alpha([y_1, y_2, y_3]) + \rho_1(\alpha(y_1), y_2, y_3) + \rho_2(y_1, \alpha(y_2), y_3) + \rho_3(y_1, y_2, \alpha(y_3))
\end{aligned} \tag{3.34}$$

$$\begin{aligned}
d^2 : \Gamma L^2(\mathcal{A}, M) &\longrightarrow \Gamma L^3(\mathcal{A}, M) \\
d^2(\alpha)(x_1 \otimes x_2 \otimes y_1 \otimes y_2 \otimes y_3) &= -\alpha([x_1, x_2, y_1], y_2, y_3) - \alpha(y_1, [x_1, x_2, y_2], y_3) \\
&- \alpha(y_1, y_2, [x_1, x_2, y_3]) + \alpha(x_1, x_2 \otimes [y_1, y_2, y_3]) + \rho_3(x_1, x_2, \alpha(y_1, y_2, y_3)) - \rho_1(\alpha(x_1, x_2, y_1), y_2, y_3) \\
&- \rho_2(y_1, \alpha(x_1, x_2, y_2), y_3) - \rho_3(y_1, y_2, \alpha(x_1, x_2, y_3)).
\end{aligned} \tag{3.35}$$

In all above cases, since M is a 3-Leibniz module with three actions ρ_1 , ρ_2 and ρ_3 it is easy to see that $d^2d^1 = 0$ and also the 3-Leibniz identity results that $d^1d^0 = 0$.

Now, with these actions we define the 3-Leibniz bialgebra.

Definition 3.4 A 3-Leibniz bialgebra (\mathcal{A}, γ) is a (the first or the second or the third) 3-Leibniz algebra \mathcal{A} with a linear map (cocommutor) $\gamma : \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}$ such that

- γ is a 1-cocycle on \mathcal{A} with values in $\mathcal{A}^{\otimes 3}$ according to (3.6)-(3.9), (3.15) and (3.21).

$$\gamma[y_1, y_2, y_3] = \rho_1(\gamma(y_1), y_2, y_3) + \rho_2(y_1, \gamma(y_2), y_3) + \rho_3(y_1, y_2, \gamma(y_3)), \tag{3.36}$$

such that $\mathcal{A}^{\otimes 3}$ be a 3-Leibniz module. In above identity ρ_1, ρ_2 and ρ_3 are three actions that define 3-Leibniz structure on $\mathcal{A}^{\otimes 3}$.

- $\gamma^t : \mathcal{A}^{\otimes 3} \longrightarrow \mathcal{A}^*$ defines a 3-Leibniz bracket on \mathcal{A}^* .

If we use the notation

$$[\tilde{x}^1, \tilde{x}^2, \tilde{x}^3]_* = \gamma^t(\tilde{x}^1 \otimes \tilde{x}^2 \otimes \tilde{x}^3), \quad \forall \tilde{x}^1, \tilde{x}^2, \tilde{x}^3 \in \mathcal{A}^* \tag{3.37}$$

then $\forall x \in \mathcal{A}$ we have

$$\langle [\tilde{x}^1, \tilde{x}^2, \tilde{x}^3]_*, x \rangle = \langle \gamma^t(\tilde{x}^1 \otimes \tilde{x}^2 \otimes \tilde{x}^3), X \rangle = \langle \tilde{x}^1 \otimes \tilde{x}^2 \otimes \tilde{X}^3, \gamma(x) \rangle, \tag{3.38}$$

where \langle, \rangle is the natural pairing between \mathcal{A} and \mathcal{A}^* .

Note that dependent on the type of the 3-Leibniz algebra \mathcal{A} and also its actions ρ_1 , ρ_2 and ρ_3 such that $\mathcal{A}^{\otimes 3}$ be a 3-Leibniz module, the 1-cocycle condition (3.36) can be rewritten in one of the

following forms:

$$\gamma([x_1, x_2, x_3]) = ad_{(\widehat{x_1, x_2, x_3})}^{(3)}\gamma(x_1), \quad (3.39)$$

$$\gamma([x_1, x_2, x_3]) = ad_{(x_1, \widehat{x_2, x_3})}^{(3)}\gamma(x_2), \quad (3.40)$$

$$\gamma([x_1, x_2, x_3]) = ad_{(x_1, x_2, \widehat{x_3})}^{(3)}\gamma(x_3), \quad (3.41)$$

$$\begin{aligned} \gamma([x_1, x_2, x_3]) &= (ad_{(\widehat{x_1, x_2, x_3})} \otimes 1 \otimes 1)(\gamma(x_1)) \\ &\quad + (ad_{(x_1, \widehat{x_2, x_3})} \otimes 1 \otimes 1)(\gamma(x_2)) + (ad_{(x_1, x_2, \widehat{x_3})} \otimes 1 \otimes 1)(\gamma(x_3)), \end{aligned} \quad (3.42)$$

$$\begin{aligned} \gamma([x_1, x_2, x_3]) &= (1 \otimes ad_{(\widehat{x_1, x_2, x_3})} \otimes 1)(\gamma(x_1)) \\ &\quad + (1 \otimes ad_{(x_1, \widehat{x_2, x_3})} \otimes 1)(\gamma(x_2)) + (1 \otimes ad_{(x_1, x_2, \widehat{x_3})} \otimes 1)(\gamma(x_3)), \end{aligned} \quad (3.43)$$

$$\begin{aligned} \gamma([x_1, x_2, x_3]) &= (1 \otimes 1 \otimes ad_{(\widehat{x_1, x_2, x_3})})(\gamma(x_1)) \\ &\quad + (1 \otimes 1 \otimes ad_{(x_1, \widehat{x_2, x_3})})(\gamma(x_2)) + (1 \otimes 1 \otimes ad_{(x_1, x_2, \widehat{x_3})})(\gamma(x_3)). \end{aligned} \quad (3.44)$$

In (3.39) , (3.40) ,(3.41) \mathcal{A} is the first and the second and the third 3-Leibniz algebra respectively. In (3.42) , (3.43) , (3.44) \mathcal{A} can be 3-Leibniz algebra from various three types. According to which of the above conditions holds for the 1-cocycle; the 3-Leibniz algebra \mathcal{A}^* can be the first and the second and the third 3-Leibniz algebra. We investigate this subject as follows:

Proposition 3.5 *If (\mathcal{A}, γ) is a 3-Leibniz bialgebra, and μ is the 3-Leibniz bracket of \mathcal{A} , then (\mathcal{A}^*, μ^t) is a 3-Leibniz bialgebra, where γ^t is the 3-Leibniz bracket of \mathcal{A}^* .*

Proof. • If we use from (3.39) the value of $\gamma([x_1, x_2, x_3])$, then from (3.38) we have

$$\begin{aligned} \prec [\xi_1, \xi_2, \xi_3]_*, [x_1, x_2, x_3] \succ &= \prec \xi_1 \otimes \xi_2 \otimes \xi_3, \gamma[x_1, x_2, x_3] \succ \\ &= \prec \xi_1 \otimes \xi_2 \otimes \xi_3, (ad_{(\widehat{x_1, x_2, x_3})} \otimes 1 \otimes 1)(\gamma(x_1)) \succ \\ &\quad + \prec \xi_1 \otimes \xi_2 \otimes \xi_3, (1 \otimes ad_{(\widehat{x_1, x_2, x_3})} \otimes 1)(\gamma(x_1)) \succ \\ &\quad + \prec \xi_1 \otimes \xi_2 \otimes \xi_3, (1 \otimes 1 \otimes ad_{(\widehat{x_1, x_2, x_3})})(\gamma(x_1)) \succ . \end{aligned} \quad (3.45)$$

We now define the coadjoint representation of a 3-Leibniz algebra on the dual vector space. Let \mathcal{A} be a 3-Leibniz algebra and let \mathcal{A}^* be its dual vector space, then for $x_1, x_2, x_3 \in \mathcal{A}$ we

have

$$\begin{aligned} ad_{(\widehat{x_1, x_2, x_3})}^* : \mathcal{A}^* &\longrightarrow \mathcal{A}^*, \\ \prec ad_{(\widehat{x_1, x_2, x_3})}^* \xi, y \succ &= - \prec \xi, ad_{(\widehat{x_1, x_2, x_3})} y \succ = - \prec \xi, [y, x_2, x_3] \succ, \end{aligned} \quad (3.46)$$

$$\begin{aligned} ad_{(x_1, \widehat{x_2, x_3})}^* : \mathcal{A}^* &\longrightarrow \mathcal{A}^*, \\ \prec ad_{(x_1, \widehat{x_2, x_3})}^* \xi, y \succ &= - \prec \xi, ad_{(x_1, \widehat{x_2, x_3})} y \succ = - \prec \xi, [x_1, y, x_3] \succ, \end{aligned} \quad (3.47)$$

$$\begin{aligned} ad_{(x_1, x_2, \widehat{x_3})}^* : \mathcal{A}^* &\longrightarrow \mathcal{A}^*, \\ \prec ad_{(x_1, x_2, \widehat{x_3})}^* \xi, y \succ &= - \prec \xi, ad_{(x_1, x_2, \widehat{x_3})} y \succ = - \prec \xi, [x_1, x_2, y] \succ. \end{aligned} \quad (3.48)$$

Using these relations, (3.45) can be rewritten as

$$\begin{aligned} \prec [\xi_1, \xi_2, \xi_3]_*, [x_1, x_2, x_3] \succ &= - \prec [ad_{(\widehat{x_1, x_2, x_3})}^* \xi_1, \xi_2, \xi_3]_*, x_1 \succ \\ &- \prec [\xi_1, ad_{(\widehat{x_1, x_2, x_3})}^* \xi_2, \xi_3]_*, x_1 \succ - \prec [\xi_1, \xi_2, ad_{(\widehat{x_1, x_2, x_3})}^* \xi_3]_*, x_1 \succ. \end{aligned} \quad (3.49)$$

In the similar way as above; for any $\xi_1, \xi_2, \xi_3 \in \mathcal{A}^*$ we have

$$\begin{aligned} ad_{(\widehat{\xi_1, \xi_2, \xi_3})}^* : \mathcal{A} &\longrightarrow \mathcal{A} \cong \mathcal{A}^{**}, \\ \prec ad_{(\widehat{\xi_1, \xi_2, \xi_3})}^* x, \eta \succ &= - \prec x, ad_{(\widehat{\xi_1, \xi_2, \xi_3})} \eta \succ = - \prec x, [\eta, \xi_2, \xi_3]_* \succ, \end{aligned} \quad (3.50)$$

$$\begin{aligned} ad_{(\xi_1, \widehat{\xi_2, \xi_3})}^* : \mathcal{A} &\longrightarrow \mathcal{A} \cong \mathcal{A}^{**}, \\ \prec ad_{(\xi_1, \widehat{\xi_2, \xi_3})}^* x, \eta \succ &= - \prec x, ad_{(\xi_1, \widehat{\xi_2, \xi_3})} \eta \succ = - \prec x, [\xi_1, \eta, \xi_3]_* \succ, \end{aligned} \quad (3.51)$$

$$\begin{aligned} ad_{(\xi_1, \xi_2, \widehat{\xi_3})}^* : \mathcal{A} &\longrightarrow \mathcal{A} \cong \mathcal{A}^{**}, \\ \prec ad_{(\xi_1, \xi_2, \widehat{\xi_3})}^* x, \eta \succ &= - \prec x, ad_{(\xi_1, \xi_2, \widehat{\xi_3})} \eta \succ = - \prec x, [\xi_1, \xi_2, \eta]_* \succ. \end{aligned} \quad (3.52)$$

By using these relations, (3.49) can be rewritten as

$$\begin{aligned} \prec [\xi_1, \xi_2, \xi_3]_*, [x_1, x_2, x_3] \succ &= \prec ad_{(\widehat{x_1, x_2, x_3})}^* \xi_1, ad_{(\widehat{\xi_1, \xi_2, \xi_3})}^* x_1 \succ \\ &+ \prec ad_{(\widehat{x_1, x_2, x_3})}^* \xi_2, ad_{(\xi_1, \widehat{\xi_2, \xi_3})}^* x_1 \succ \\ &+ \prec ad_{(\widehat{x_1, x_2, x_3})}^* \xi_3, ad_{(\xi_1, \xi_2, \widehat{\xi_3})}^* x_1 \succ, \end{aligned} \quad (3.53)$$

or

$$\begin{aligned} \prec [\xi_1, \xi_2, \xi_3]_*, \mu(x_1 \otimes x_2 \otimes x_3) \succ &= \prec \xi_1, [ad_{(\widehat{\xi_1, \xi_2, \xi_3})}^* x_1, x_2, x_3] \succ \\ &- \prec \xi_2, [ad_{(\xi_1, \widehat{\xi_2, \xi_3})}^* x_1, x_2, x_3] \succ \\ &- \prec \xi_3, [ad_{(\xi_1, \xi_2, \widehat{\xi_3})}^* x_1, x_2, x_3] \succ, \end{aligned} \quad (3.54)$$

where μ is the 3-Leibniz bracket on \mathcal{A} and μ^t is cocommutator on \mathcal{A}^* i.e. $\mu^t : \mathcal{A}^* \longrightarrow$

$\mathcal{A}^* \otimes \mathcal{A}^* \otimes \mathcal{A}^*$. Therefore, we have

$$\begin{aligned} \prec \mu^t[\xi_1, \xi_2, \xi_3]_*, x_1 \otimes x_2 \otimes x_3 \succ &= \prec (ad_{(\widehat{\xi}_1, \widehat{\xi}_2, \widehat{\xi}_3)} \otimes 1 \otimes 1)(\mu^t(\xi_1)), x_1 \otimes x_2 \otimes x_3 \succ \\ &+ \prec (ad_{(\xi_1, \widehat{\xi}_2, \widehat{\xi}_3)} \otimes 1 \otimes 1)(\mu^t(\xi_2)), x_1 \otimes x_2 \otimes x_3 \succ \\ &+ \prec (ad_{(\xi_1, \xi_2, \widehat{\xi}_3)} \otimes 1 \otimes 1)(\mu^t(\xi_3)), x_1 \otimes x_2 \otimes x_3 \succ, \end{aligned} \quad (3.55)$$

or

$$\begin{aligned} \mu^t[\xi_1, \xi_2, \xi_3]_* &= (ad_{(\widehat{\xi}_1, \widehat{\xi}_2, \widehat{\xi}_3)} \otimes 1 \otimes 1)(\mu^t(\xi_1)) + (ad_{(\xi_1, \widehat{\xi}_2, \widehat{\xi}_3)} \otimes 1 \otimes 1)(\mu^t(\xi_2)) \\ &+ (ad_{(\xi_1, \xi_2, \widehat{\xi}_3)} \otimes 1 \otimes 1)(\mu^t(\xi_3)). \end{aligned} \quad (3.56)$$

But, this relation is the 1-cocycle condition (3.42) for (\mathcal{A}^*, μ^t) such that it shows $\mathcal{A}^{*\otimes 3}$ is a 3-Leibniz module on \mathcal{A}^* ; i.e. \mathcal{A}^* can be 3-Leibniz algebra from various three types.

- In the same way, if one uses from (3.40) for the value of $\gamma([x_1, x_2, x_3])$, then by assuming that \mathcal{A} is the second 3-Leibniz algebra, we have

$$\begin{aligned} \mu^t[\xi_1, \xi_2, \xi_3]_* &= (1 \otimes ad_{(\widehat{\xi}_1, \widehat{\xi}_2, \widehat{\xi}_3)} \otimes 1)(\mu^t(\xi_1)) + (1 \otimes ad_{(\xi_1, \widehat{\xi}_2, \widehat{\xi}_3)} \otimes 1)(\mu^t(\xi_2)) \\ &+ (1 \otimes ad_{(\xi_1, \xi_2, \widehat{\xi}_3)} \otimes 1)(\mu^t(\xi_3)), \end{aligned} \quad (3.57)$$

instead of (3.56), such that this relation is the 1-cocycle condition (3.43) for (\mathcal{A}^*, μ^t) , where it shows $\mathcal{A}^* \otimes \mathcal{A}^* \otimes \mathcal{A}^*$ is a 3-Leibniz module on \mathcal{A}^* and \mathcal{A}^* can be 3-Leibniz algebra from various three types.

On the other hand, for the third 3-Leibniz algebra (\mathcal{A}, μ) when one uses (3.41) for the value $\gamma([x_1, x_2, x_3])$ we have

$$\begin{aligned} \mu^t[\xi_1, \xi_2, \xi_3]_* &= (1 \otimes 1 \otimes ad_{(\widehat{\xi}_1, \widehat{\xi}_2, \widehat{\xi}_3)})(\mu^t(\xi_1)) + (1 \otimes 1 \otimes ad_{(\xi_1, \widehat{\xi}_2, \widehat{\xi}_3)})(\mu^t(\xi_2)) \\ &+ (1 \otimes 1 \otimes ad_{(\xi_1, \xi_2, \widehat{\xi}_3)})(\mu^t(\xi_3)), \end{aligned} \quad (3.58)$$

instead of (3.56), and this shows that μ^t is a 1-cocycle condition (3.44) for (\mathcal{A}^*, μ^t) such that it shows $\mathcal{A}^* \otimes \mathcal{A}^* \otimes \mathcal{A}^*$ is a 3-Leibniz module on \mathcal{A}^* and \mathcal{A}^* can be 3-Leibniz algebra from various three types.

- In the same way, if one uses from (3.42) for the value of $\gamma([x_1, x_2, x_3])$, then by assuming that \mathcal{A} is 3-Leibniz algebra from various three types, we have

$$\mu^t[\xi_1, \xi_2, \xi_3]_* = ad_{(\widehat{\xi}_1, \widehat{\xi}_2, \widehat{\xi}_3)}^{(3)} \mu^t(x_1), \quad (3.59)$$

and this shows that μ^t is a 1-cocycle condition (3.39) for (\mathcal{A}^*, μ^t) such that it shows $\mathcal{A}^* \otimes \mathcal{A}^* \otimes \mathcal{A}^*$ is a 3-Leibniz module on \mathcal{A}^* and \mathcal{A}^* is the first 3-Leibniz algebra.

- Using (3.43) for the value of $\gamma([x_1, x_2, x_3])$, then by assuming that \mathcal{A} is 3-Leibniz algebra from various three types, we have

$$\mu^t[\xi_1, \xi_2, \xi_3]_* = ad_{(\xi_1, \widehat{\xi_2}, \xi_3)}^{(3)} \mu^t(x_2), \quad (3.60)$$

and this shows that μ^t is a 1-cocycle condition (3.40) for (\mathcal{A}^*, μ^t) such that it shows $\mathcal{A}^* \otimes \mathcal{A}^* \otimes \mathcal{A}^*$ is a 3-Leibniz module on \mathcal{A}^* and \mathcal{A}^* is the second 3-Leibniz algebra.

- Finally, if one uses from (3.44) for the value of $\gamma([x_1, x_2, x_3])$, then by assuming that \mathcal{A} is 3-Leibniz algebra from various three types, we have

$$\mu^t[\xi_1, \xi_2, \xi_3]_* = ad_{(\xi_1, \xi_2, \widehat{\xi_3})}^{(3)} \mu^t(x_3), \quad (3.61)$$

and this shows that μ^t is a 1-cocycle condition (3.41) for (\mathcal{A}^*, μ^t) such that it shows $\mathcal{A}^* \otimes \mathcal{A}^* \otimes \mathcal{A}^*$ is a 3-Leibniz module on \mathcal{A}^* and \mathcal{A}^* is the third 3-Leibniz algebra.

Therefore, a 3-Leibniz bialgebra (\mathcal{A}, γ) can also be denoted by $(\mathcal{A}, \mathcal{A}^*)$. ■

There are no Manin triple for 3-Leibniz bialgebras.

4 3-Leibniz bialgebra in terms of structure constants; some examples

In this section, we obtain some examples of 3-Leibniz bialgebras. For these proposes we first rewrite the 1-cocycle conditions (3.39)-(3.41) in terms of structure constants of the 3-Leibniz algebra \mathcal{A} and \mathcal{A}^* . If we choose $(\{x_i\}, f_{ijk}^m)$ and $(\{\tilde{x}^i\}, \tilde{f}^{ijk}_m)$ as the basis and structure constants of 3-Leibniz algebra \mathcal{A} and \mathcal{A}^* respectively; then we have the commutation relations as follows

$$[x_i, x_j, x_k] = f_{ijk}^m x_m, \quad [\tilde{x}^i, \tilde{x}^j, \tilde{x}^k]_* = \tilde{f}^{ijk}_m \tilde{x}^m. \quad (4.1)$$

Using (3.38) we have

$$\begin{aligned} \langle \tilde{x}^j \otimes \tilde{x}^k \otimes \tilde{x}^m, \gamma(x^i) \rangle &= \langle \gamma^t(\tilde{x}^j \otimes \tilde{x}^k \otimes \tilde{x}^m), x_i \rangle = \langle [\tilde{x}^j, \tilde{x}^k, \tilde{x}^m]_*, x_i \rangle \\ &= \langle \tilde{f}^{jkm}_n \tilde{x}^n, x_i \rangle = \tilde{f}^{jkm}_i, \end{aligned} \quad (4.2)$$

namely

$$\gamma(x_i) = \tilde{f}^{jkm}_i x_j \otimes x_k \otimes x_m \quad (4.3)$$

Now using structure constants of \mathcal{A} and (4.3) in the 1-cocycle conditions (3.39)-(3.41) we obtain the following relations respectively:

$$f_{isn}^p \tilde{f}^{jkm}_p = \tilde{f}^{j'km}_i f_{j'sn}^j + \tilde{f}^{jk'm}_i f_{k'sn}^k + \tilde{f}^{jkm'}_i f_{m'sn}^m, \quad (4.4)$$

$$f_{isn}^p \tilde{f}^{jkm}_p = \tilde{f}^{j'km}_s f_{ij'n}^j + \tilde{f}^{jk'm}_s f_{ik'n}^k + \tilde{f}^{jkm'}_s f_{im'n}^m, \quad (4.5)$$

$$f_{isn}^p \tilde{f}^{jkm}_p = \tilde{f}^{j'km}_n f_{isj'}^j + \tilde{f}^{jk'm}_n f_{isk'}^k + \tilde{f}^{jkm'}_n f_{ism'}^m. \quad (4.6)$$

Note that similar to the Lie bialgebras case [15] one can use three relations as a definition of 3-Leibniz bialgebra.

Definition 4.1 *Two 3-Leibniz algebra \mathcal{A} and \mathcal{A}^* construct a 3-Leibniz bialgebra if their structure constants satisfy in relations (4.4) – (4.6).*

To use these relations in the calculations we must first translate the tensor form of these relations to the matrix forms by using the following adjoint representations

$$f_{isn}{}^p = (\chi_{is})_n{}^p = (Y_i{}^p)_{sn} = f'_{sin}{}^p = (\chi'_{si})_n{}^p = (Y'_s{}^p)_{in} \quad (4.7)$$

$$\tilde{f}^{jkm}{}_p = (\tilde{\chi}^{jk})^m{}_p = (\tilde{Y}^j{}_p)^{km} = \tilde{f}'^{kjm}{}_p = (\tilde{\chi}'^{kj})^m{}_p = (\tilde{Y}'^k{}_p)^{jm} \quad (4.8)$$

Then, relations (4.4) – (4.6) have the following matrix forms respectively:

$$(\chi_{is})(\tilde{\chi}^{jk})^t = (Y'_s{}^j)^t(\tilde{Y}'^k{}_i) + (Y'_s{}^k)^t(\tilde{Y}^j{}_i) + (\tilde{\chi}^{jk})^{m'}{}_i(\chi_{m's}), \quad (4.9)$$

$$(\chi_{is})(\tilde{\chi}^{jk})^t = (Y_i{}^j)^t(\tilde{Y}'^k{}_s) + (Y_i{}^k)^t(\tilde{Y}^j{}_s) + (\tilde{\chi}^{jk})^{m'}{}_s(\chi_{im'}), \quad (4.10)$$

$$(\chi_{is})(\tilde{\chi}^{jk})^t = (\chi_{is})_{j'}{}^j(\tilde{\chi}^{j'k})^t + (\chi_{is})_{k'}{}^k(\tilde{\chi}^{jk'})^t + (\tilde{\chi}^{jk})^t(\chi_{is}), \quad (4.11)$$

where in the above relations t stands for transpose of a matrix. On the other hand, identities (3.3) - (3.5) for 3-Leibniz algebra \mathcal{A}^* in terms of structure constant as follows:

$$\tilde{f}^{ijk}{}_p \tilde{f}^{psm}{}_n = \tilde{f}^{ism}{}_p \tilde{f}^{pjk}{}_n + \tilde{f}^{jsm}{}_p \tilde{f}^{ipk}{}_n + \tilde{f}^{ksm}{}_p \tilde{f}^{ijp}{}_n, \quad (4.12)$$

$$\tilde{f}^{jks}{}_p \tilde{f}^{ipm}{}_n = \tilde{f}^{ijm}{}_p \tilde{f}^{pks}{}_n + \tilde{f}^{ikm}{}_p \tilde{f}^{jps}{}_n + \tilde{f}^{ism}{}_p \tilde{f}^{jkp}{}_n, \quad (4.13)$$

$$\tilde{f}^{ksm}{}_p \tilde{f}^{ijp}{}_n = \tilde{f}^{ijk}{}_p \tilde{f}^{psm}{}_n + \tilde{f}^{ijs}{}_p \tilde{f}^{kpm}{}_n + \tilde{f}^{ijm}{}_p \tilde{f}^{ksp}{}_n, \quad (4.14)$$

where we have the following matrix form for these relations respectively:

$$(\tilde{\chi}^{ij})(\tilde{Y}'^s{}_n) = (\tilde{Y}'^j{}_n)^t(\tilde{\chi}^{is})^t + (\tilde{Y}^i{}_n)^t(\tilde{\chi}^{js})^t + (\tilde{\chi}^{ij})^p{}_n(\tilde{Y}'^s{}_p), \quad (4.15)$$

$$(\tilde{\chi}^{jk})(\tilde{Y}^i{}_n) = (\tilde{Y}'^k{}_n)^t(\tilde{\chi}^{ij})^t + (\tilde{Y}^j{}_n)^t(\tilde{\chi}^{ik})^t + (\tilde{\chi}^{jk})^p{}_m(\tilde{Y}^i{}_p), \quad (4.16)$$

$$(\tilde{\chi}^{ks})(\tilde{\chi}^{ij}) = (\tilde{\chi}^{ij})^k{}_p(\tilde{\chi}^{ps}) + (\tilde{\chi}^{ij})^s{}_p(\tilde{\chi}^{kp}) + (\tilde{\chi}^{ij})(\tilde{\chi}^{ks}). \quad (4.17)$$

Now, one can use the relations (4.9)-(4.11) and (4.15)-(4.17) for calculation of the dual 3-Leibniz algebra \mathcal{A}^* . According to the type of 3-Leibniz algebras \mathcal{A} and \mathcal{A}^* , we must solve the following equations:

- If \mathcal{A} and \mathcal{A}^* are both the first 3-Leibniz algebra

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (Y'_s{}^j)^t(\tilde{Y}'^k{}_i) - (Y'_s{}^k)^t(\tilde{Y}^j{}_i) - (\tilde{\chi}^{jk})^{m'}{}_i(\chi_{m's}) &= 0, \\ (\tilde{\chi}^{ij})(\tilde{Y}'^s{}_n) - (\tilde{Y}'^j{}_n)^t(\tilde{\chi}^{is})^t - (\tilde{Y}^i{}_n)^t(\tilde{\chi}^{js})^t - (\tilde{\chi}^{ij})^p{}_n(\tilde{Y}'^s{}_p) &= 0. \end{aligned} \quad (4.18)$$

- If \mathcal{A} and \mathcal{A}^* are the first and the second 3-Leibniz algebra respectively

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (Y'_s{}^j)^t(\tilde{Y}'^k{}_i) - (Y'_s{}^k)^t(\tilde{Y}^j{}_i) - (\tilde{\chi}^{jk})^{m'}{}_i(\chi_{m's}) &= 0, \\ (\tilde{\chi}^{jk})(\tilde{Y}^i{}_n) - (\tilde{Y}'^k{}_n)^t(\tilde{\chi}^{ij})^t - (\tilde{Y}^j{}_n)^t(\tilde{\chi}^{ik})^t - (\tilde{\chi}^{jk})^p{}_m(\tilde{Y}^i{}_p) &= 0. \end{aligned} \quad (4.19)$$

- If \mathcal{A} and \mathcal{A}^* are the first and the third 3-Leibniz algebra respectively

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (Y_s'{}^j)^t(\tilde{Y}'{}^k{}_i) - (Y_s'{}^k)^t(\tilde{Y}'{}^j{}_i) - (\tilde{\chi}^{jk})^{m'}{}_i(\chi_{m's}) &= 0, \\ (\tilde{\chi}^{ks})(\tilde{\chi}^{ij}) - (\tilde{\chi}^{ij})^k{}_p(\tilde{\chi}^{ps}) - (\tilde{\chi}^{ij})^s{}_p(\tilde{\chi}^{kp}) - (\tilde{\chi}^{ij})(\tilde{\chi}^{ks}) &= 0. \end{aligned} \quad (4.20)$$

- If \mathcal{A} and \mathcal{A}^* are the second and the first 3-Leibniz algebra respectively

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (Y_i'{}^j)^t(\tilde{Y}'{}^k{}_s) - (Y_i'{}^k)^t(\tilde{Y}'{}^j{}_s) - (\tilde{\chi}^{jk})^{m'}{}_s(\chi_{im'}) &= 0, \\ (\tilde{\chi}^{ij})(\tilde{Y}'{}^s{}_n) - (\tilde{Y}'{}^j{}_n)^t(\tilde{\chi}^{is})^t - (\tilde{Y}'{}^i{}_n)^t(\tilde{\chi}^{js})^t - (\tilde{\chi}^{ij})^p{}_n(\tilde{Y}'{}^s{}_p) &= 0. \end{aligned} \quad (4.21)$$

- If \mathcal{A} and \mathcal{A}^* are both the second 3-Leibniz algebra

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (Y_i'{}^j)^t(\tilde{Y}'{}^k{}_s) - (Y_i'{}^k)^t(\tilde{Y}'{}^j{}_s) - (\tilde{\chi}^{jk})^{m'}{}_s(\chi_{im'}) &= 0, \\ (\tilde{\chi}^{jk})(\tilde{Y}'{}^i{}_n) - (\tilde{Y}'{}^k{}_n)^t(\tilde{\chi}^{ij})^t - (\tilde{Y}'{}^j{}_n)^t(\tilde{\chi}^{ik})^t - (\tilde{\chi}^{jk})^p{}_m(\tilde{Y}'{}^i{}_p) &= 0. \end{aligned} \quad (4.22)$$

- If \mathcal{A} and \mathcal{A}^* are the second and the third 3-Leibniz algebra respectively

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (Y_i'{}^j)^t(\tilde{Y}'{}^k{}_s) - (Y_i'{}^k)^t(\tilde{Y}'{}^j{}_s) - (\tilde{\chi}^{jk})^{m'}{}_s(\chi_{im'}) &= 0, \\ (\tilde{\chi}^{ks})(\tilde{\chi}^{ij}) - (\tilde{\chi}^{ij})^k{}_p(\tilde{\chi}^{ps}) - (\tilde{\chi}^{ij})^s{}_p(\tilde{\chi}^{kp}) - (\tilde{\chi}^{ij})(\tilde{\chi}^{ks}) &= 0. \end{aligned} \quad (4.23)$$

- If \mathcal{A} and \mathcal{A}^* are the third and the first 3-Leibniz algebra respectively

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (\chi_{is})_{j'}{}^j(\tilde{\chi}^{j'k})^t - (\chi_{is})_{k'}{}^k(\tilde{\chi}^{j'k})^t - (\tilde{\chi}^{jk})^t(\chi_{is}) &= 0, \\ (\tilde{\chi}^{ij})(\tilde{Y}'{}^s{}_n) - (\tilde{Y}'{}^j{}_n)^t(\tilde{\chi}^{is})^t - (\tilde{Y}'{}^i{}_n)^t(\tilde{\chi}^{js})^t - (\tilde{\chi}^{ij})^p{}_n(\tilde{Y}'{}^s{}_p) &= 0. \end{aligned} \quad (4.24)$$

- If \mathcal{A} and \mathcal{A}^* are the third and the second 3-Leibniz algebra respectively

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (\chi_{is})_{j'}{}^j(\tilde{\chi}^{j'k})^t - (\chi_{is})_{k'}{}^k(\tilde{\chi}^{j'k})^t - (\tilde{\chi}^{jk})^t(\chi_{is}) &= 0, \\ (\tilde{\chi}^{jk})(\tilde{Y}'{}^i{}_n) - (\tilde{Y}'{}^k{}_n)^t(\tilde{\chi}^{ij})^t - (\tilde{Y}'{}^j{}_n)^t(\tilde{\chi}^{ik})^t - (\tilde{\chi}^{jk})^p{}_m(\tilde{Y}'{}^i{}_p) &= 0. \end{aligned} \quad (4.25)$$

- If \mathcal{A} and \mathcal{A}^* are both the third 3-Leibniz algebra

$$\begin{aligned} (\chi_{is})(\tilde{\chi}^{jk})^t - (\chi_{is})_{j'}{}^j(\tilde{\chi}^{j'k})^t - (\chi_{is})_{k'}{}^k(\tilde{\chi}^{j'k})^t - (\tilde{\chi}^{jk})^t(\chi_{is}) &= 0, \\ (\tilde{\chi}^{ks})(\tilde{\chi}^{ij}) - (\tilde{\chi}^{ij})^k{}_p(\tilde{\chi}^{ps}) - (\tilde{\chi}^{ij})^s{}_p(\tilde{\chi}^{kp}) - (\tilde{\chi}^{ij})(\tilde{\chi}^{ks}) &= 0. \end{aligned} \quad (4.26)$$

Now, by use of the above relations we obtain some examples as follows.

Example 4.2 We consider the following three dimensional first 3-Leibniz algebras [21]

$$1. [e_2, e_3, e_3] = e_1 \quad , \quad [e_3, e_3, e_3] = e_2,$$

for this example we have

$$\chi_{23} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \chi_{33} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad \chi_{12} = \chi_{21} = \chi_{32} = \chi_{11} = \chi_{22} = \chi_{13} = \chi_{31} = 0,$$

$$Y_2^1 = Y_3^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad Y_1^2 = Y_1^1 = Y_2^2 = Y_2^3 = Y_3^3 = Y_1^3 = Y_3^1 = 0,$$

$$\chi'_{32} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \chi'_{33} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad \chi'_{12} = \chi'_{21} = \chi'_{23} = \chi'_{11} = \chi'_{22} = \chi'_{13} = \chi'_{31} = 0,$$

$$Y_3^1 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad Y_3^2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad Y_1^2 = Y_1^1 = Y_2^2 = Y_2^3 = Y_3^3 = Y_1^3 = Y_2^1 = 0,$$

By solving the system of equations (4.18) – (4.20) we obtain the following \mathcal{A}^* algebras:

- \mathcal{A}^* as a second 3-Leibniz algebra

$$[\tilde{e}^1, \tilde{e}^1, \tilde{e}^1]_* = b\tilde{e}^2 + a\tilde{e}^3, \quad [\tilde{e}^1, \tilde{e}^2, \tilde{e}^1]_* = b\tilde{e}^3,$$

where a and b are any non zero real numbers.

- \mathcal{A}^* as a third 3-Leibniz algebra

$$[\tilde{e}^1, \tilde{e}^1, \tilde{e}^1]_* = b\tilde{e}^2 + a\tilde{e}^3, \quad [\tilde{e}^1, \tilde{e}^1, \tilde{e}^2]_* = b\tilde{e}^3,$$

where a and b are any non zero real numbers.

$$2. [e_3, e_2, e_3] = e_2 \quad , \quad [e_3, e_3, e_2] = -e_2, \quad , \quad [e_3, e_3, e_3] = e_1 + e_2,$$

we have

$$\begin{aligned}
\chi_{32} &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, & \chi_{33} &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}, & \chi_{12} &= \chi_{21} = \chi_{23} = \chi_{11} = \chi_{22} = \chi_{13} = \chi_{31} = 0, \\
Y_3^2 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 1 \end{pmatrix}, & Y_3^1 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, & Y_1^2 &= Y_1^1 = Y_2^2 = Y_2^3 = Y_3^3 = Y_1^3 = Y_2^1 = 0, \\
\chi'_{23} &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, & \chi'_{33} &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}, & \chi'_{12} &= \chi'_{21} = \chi'_{32} = \chi'_{11} = \chi'_{22} = \chi'_{13} = \chi'_{31} = 0, \\
Y_2'^2 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, & Y_3'^2 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & -1 & 1 \end{pmatrix}, & Y_3'^1 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\
Y_1'^2 &= Y_1'^1 = Y_2'^2 = Y_2'^3 = Y_3'^3 = Y_1'^3 = Y_2'^1 = 0,
\end{aligned}$$

In the same way by solving the system of equations (4.18) – (4.20) we obtain the following \mathcal{A}^* algebras:

- \mathcal{A}^* as a first 3-Leibniz algebra

$$[\tilde{e}^1, \tilde{e}^1, \tilde{e}^2]_* = a\tilde{e}^3, \quad [\tilde{e}^1, \tilde{e}^2, \tilde{e}^2]_* = b\tilde{e}^3, \quad [\tilde{e}^2, \tilde{e}^1, \tilde{e}^2]_* = c\tilde{e}^3, \quad [\tilde{e}^2, \tilde{e}^2, \tilde{e}^2]_* = d\tilde{e}^3,$$

where a, b, c, d are any non zero real numbers.

- \mathcal{A}^* as second 3-Leibniz algebra

$$[\tilde{e}^1, \tilde{e}^1, \tilde{e}^1]_* = a\tilde{e}^3, \quad [\tilde{e}^1, \tilde{e}^1, \tilde{e}^2]_* = b\tilde{e}^3, \quad [\tilde{e}^1, \tilde{e}^2, \tilde{e}^1]_* = c\tilde{e}^3, \quad [\tilde{e}^1, \tilde{e}^2, \tilde{e}^2]_* = d\tilde{e}^3,$$

where a, b, c, d are any non zero real numbers.

- \mathcal{A}^* as third 3-Leibniz algebra

$$\begin{aligned}
[\tilde{e}^1, \tilde{e}^1, \tilde{e}^1]_* &= a\tilde{e}^3, & [\tilde{e}^1, \tilde{e}^1, \tilde{e}^2]_* &= b\tilde{e}^3, \\
[\tilde{e}^1, \tilde{e}^2, \tilde{e}^1]_* &= c\tilde{e}^3, & [\tilde{e}^1, \tilde{e}^2, \tilde{e}^2]_* &= d\tilde{e}^3, \\
[\tilde{e}^2, \tilde{e}^1, \tilde{e}^1]_* &= m\tilde{e}^3, & [\tilde{e}^2, \tilde{e}^1, \tilde{e}^2]_* &= f\tilde{e}^3, \\
[\tilde{e}^2, \tilde{e}^2, \tilde{e}^1]_* &= g\tilde{e}^3, & [\tilde{e}^2, \tilde{e}^2, \tilde{e}^2]_* &= h\tilde{e}^3,
\end{aligned}$$

where a, b, c, d, m, f, g, h are any non zero real numbers.

5 Correspondence between 3-Leibniz bialgebra and its associated Leibniz bialgebra

In this section, we determine the type of the associated Leibniz algebra for any three types of 3-Leibniz algebras and prove a theorem about correspondence between 3-Leibniz bialgebra and its associated Leibniz bialgebra [20].

- If \mathcal{A} be the first 3-Leibniz algebra then its associated Leibniz algebra $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [x_1, y_1, y_2] \otimes x_2 + x_1 \otimes [x_2, y_1, y_2], \quad (5.1)$$

is right Leibniz algebra.

- If \mathcal{A} be the second 3-Leibniz algebra then its associated Leibniz algebra $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with following brackets

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [x_1, y_1, x_2] \otimes y_2 + y_1 \otimes [x_1, y_2, x_2], \quad (5.2)$$

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [y_1, x_1, y_2] \otimes x_2 + x_1 \otimes [y_1, x_2, y_2], \quad (5.3)$$

is left and right Leibniz algebra respectively.

- If \mathcal{A} be the third 3-Leibniz algebra then its associated Leibniz algebra $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with

$$[x_1 \otimes x_2, y_1 \otimes y_2] = [x_1, x_2, y_1] \otimes y_2 + y_1 \otimes [x_1, x_2, y_2], \quad (5.4)$$

is a left Leibniz algebra.

Now we prove a theorem about the correspondence between 3-Leibniz bialgebra and its associated Leibniz bialgebra [?].

Theorem 5.1 *Let (\mathcal{A}, γ) be a 3-Leibniz bialgebra and $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be its associated Leibniz algebra then there exist a linear map $\delta : \mathcal{G} \rightarrow \mathcal{G} \otimes \mathcal{G}$ such that it defines a Leibniz bialgebra structure on \mathcal{G} . Conversely if (\mathcal{G}, δ) is a Leibniz bialgebra such that $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ and \mathcal{A} be a 3-Leibniz algebra then there exist a linear map $\gamma : \mathcal{A} \rightarrow \mathcal{A} \otimes \mathcal{A} \otimes \mathcal{A}$ such that it defines a 3-Leibniz bialgebra structure on \mathcal{A} .*

Proof. Since \mathcal{A} can be 3-Leibniz algebra from various three types the proof of the theorem divided to following three parts².

²Here we write only the proof of one case. The proof of the other cases are similar.

1. If (\mathcal{A}, γ) be a 3-Leibniz bialgebra such that (3.39) is valid for $\gamma[x_1, x_2, x_3]$ then $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ is a right Leibniz algebra with bracket (5.1). \mathcal{A}^* can be 3-Leibniz algebra from three cases.

(a) If \mathcal{A}^* is the first 3-Leibniz algebra then $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ with bracket from type (5.1) is a right Leibniz algebra. We want to prove there exist a linear map $\delta : \mathcal{G} \rightarrow \mathcal{G} \otimes \mathcal{G}$ such that it defines a Leibniz bialgebra structure on \mathcal{G} . We can rewrite the bracket $[\cdot, \cdot]_*$ on \mathcal{G}^* with γ^t as follows:

$$[\tilde{x}^1 \otimes \tilde{x}^2, \tilde{y}^1 \otimes \tilde{y}^2]_* = \gamma^t(\tilde{x}^1 \otimes \tilde{y}^1 \otimes \tilde{y}^2) \otimes \tilde{x}^2 + \tilde{x}^1 \otimes \gamma^t(\tilde{x}^2 \otimes \tilde{y}^1 \otimes \tilde{y}^2), \quad (5.5)$$

using the following flip operators

$$\sigma_{24} : \mathcal{A}^{*\otimes 4} \rightarrow \mathcal{A}^{*\otimes 4}, \quad \sigma_{24}(\xi_1 \otimes \xi_2 \otimes \xi_3 \otimes \xi_4) = \xi_1 \otimes \xi_4 \otimes \xi_3 \otimes \xi_2 \quad (5.6)$$

$$\sigma_{34} : \mathcal{A}^{*\otimes 4} \rightarrow \mathcal{A}^{*\otimes 4}, \quad \sigma_{34}(\xi_1 \otimes \xi_2 \otimes \xi_3 \otimes \xi_4) = \xi_1 \otimes \xi_2 \otimes \xi_4 \otimes \xi_3, \quad (5.7)$$

(5.5) can be written as

$$[\tilde{x}^1 \otimes \tilde{x}^2, \tilde{y}^1 \otimes \tilde{y}^2]_* = ((\gamma^t \otimes I_{\mathcal{A}^*}) \circ \sigma_{24} \circ \sigma_{34} + I_{\mathcal{A}^*} \otimes \gamma^t) (\tilde{x}^1 \otimes \tilde{x}^2 \otimes \tilde{y}^1 \otimes \tilde{y}^2), \quad (5.8)$$

setting

$$\delta^t := [\cdot, \cdot]_*, \quad (5.9)$$

then we have

$$\delta^t = (\gamma^t \otimes I_{\mathcal{A}^*}) \circ \sigma_{24} \circ \sigma_{34} + I_{\mathcal{A}^*} \otimes \gamma^t, \quad (5.10)$$

and so

$$\delta(x_1 \otimes x_2) = (\sigma_{34}^t \circ \sigma_{24}^t \circ (\gamma \otimes I_{\mathcal{A}}) + I_{\mathcal{A}} \otimes \gamma) (x_1 \otimes x_2), \quad (5.11)$$

where $\sigma_{24}^t, \sigma_{34}^t : \mathcal{A}^{\otimes 4} \rightarrow \mathcal{A}^{\otimes 4}$ act as follows

$$\sigma_{24}^t(x_1 \otimes x_2 \otimes x_3 \otimes x_4) = x_1 \otimes x_4 \otimes x_3 \otimes x_2, \quad (5.12)$$

$$\sigma_{34}^t(x_1 \otimes x_2 \otimes x_3 \otimes x_4) = x_1 \otimes x_2 \otimes x_4 \otimes x_3, \quad (5.13)$$

then for any $X, Y \in \mathcal{G}$ we have

$$\begin{aligned} \delta[X, Y] &= \delta[x_1 \otimes x_2, y_1 \otimes y_2] = \delta([x_1, y_1, y_2] \otimes x_2 + x_1 \otimes [x_2, y_1, y_2]) \\ &= (\sigma_{34}^t \circ \sigma_{24}^t \circ (\gamma \otimes I_{\mathcal{A}}) + I_{\mathcal{A}} \otimes \gamma) ([x_1, y_1, y_2] \otimes x_2 + x_1 \otimes [x_2, y_1, y_2]) \\ &= [x_1^1, y_1, y_2] \otimes x_2 \otimes x_1^2 \otimes x_1^3 + x_1^1 \otimes x_2 \otimes [x_1^2, y_1, y_2] \otimes x_1^3 \\ &\quad + x_1^1 \otimes x_2 \otimes x_1^2 \otimes [x_1^3, y_1, y_2] + [x_1, y_1, y_2] \otimes x_2^1 \otimes x_2^2 \otimes x_2^3 \\ &\quad + x_1^1 \otimes [x_2, y_1, y_2] \otimes x_1^2 \otimes x_1^3 + x_1 \otimes [x_2^1, y_1, y_2] \otimes x_2^2 \otimes x_2^3 \\ &\quad + x_1 \otimes x_2^1 \otimes [x_2^2, y_1, y_2] \otimes x_2^3 + x_1 \otimes x_2^1 \otimes x_2^2 \otimes [x_2^3, y_1, y_2] \\ &= \left(1_{\mathcal{G}} \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1_{\mathcal{G}} \right) \delta(X) \end{aligned} \quad (5.14)$$

where in above identity we use $\gamma(x_1) = x_1^1 \otimes x_1^2 \otimes x_1^3$ and $\gamma(x_2) = x_2^1 \otimes x_2^2 \otimes x_2^3$.

In the same way one can prove the following cases:

(b) If \mathcal{A}^* be the second 3-Leibniz algebra then

i. If $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a left Leibniz algebra with bracket from type (5.2) then

$$\delta(x_1 \otimes x_2) = (\sigma_{23}^t \circ (\gamma \otimes I_{\mathcal{A}}) + \sigma_{34}^t \circ \sigma_{24}^t \circ \sigma_{12}^t \circ (I_{\mathcal{A}} \otimes \gamma)) (x_1 \otimes x_2) \quad (5.15)$$

ii. If $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a right Leibniz algebra with bracket from type (5.3) then

$$\delta(x_1 \otimes x_2) = (\sigma_{34}^t \circ \sigma_{24}^t \circ \sigma_{12}^t \circ (\gamma \otimes I_{\mathcal{A}}) + \sigma_{23}^t \circ (I_{\mathcal{A}} \otimes \gamma)) (x_1 \otimes x_2) \quad (5.16)$$

(c) If \mathcal{A}^* be the third 3-Leibniz algebra then $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a left Leibniz algebra with bracket from type (5.4) then we have

$$\delta(x_1 \otimes x_2) = (\gamma \otimes I_{\mathcal{A}} + \sigma_{23}^t \circ \sigma_{23}^t \circ (I_{\mathcal{A}} \otimes \gamma)) (x_1 \otimes x_2). \quad (5.17)$$

In all above cases 1-cocycle condition is

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1_{\mathcal{G}} \right) \delta(X) \quad \forall X, Y \in \mathcal{G} \quad (5.18)$$

2. If (\mathcal{A}, γ) be a 3-Leibniz bialgebra such that (3.40) is valid for $\gamma[x_1, x_2, x_3]$ then we have the following cases:

(a) If \mathcal{A}^* be the first 3-Leibniz algebra then $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a right Leibniz algebra with bracket from type (5.1).

i. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a left Leibniz algebra with bracket (5.2) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_X^{(l)} + ad_X^{(l)} \otimes 1_{\mathcal{G}} \right) \delta(Y) \quad \forall X, Y \in \mathcal{G}$$

ii. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a right Leibniz algebra with bracket (5.3) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1_{\mathcal{G}} \right) \delta(X) \quad \forall X, Y \in \mathcal{G}$$

in above two cases we have

$$\delta(x_1 \otimes x_2) = (\sigma_{34}^t \circ \sigma_{24}^t \circ (\gamma \otimes I_{\mathcal{A}}) + I_{\mathcal{A}} \otimes \gamma) (x_1 \otimes x_2). \quad (5.19)$$

(b) If \mathcal{A}^* be the second 3-Leibniz algebra then

i. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ and $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ are both left Leibniz algebra with bracket from type (5.2) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_X^{(l)} + ad_X^{(l)} \otimes 1_{\mathcal{G}} \right) \delta(Y) \quad \forall X, Y \in \mathcal{G}$$

- ii. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a right Leibniz algebra with bracket (5.3) and $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a left Leibniz algebra with bracket from type (5.2) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1_{\mathcal{G}}\right) \delta(X) \quad \forall X, Y \in \mathcal{G},$$

where in the above two cases we have

$$\delta(x_1 \otimes x_2) = \left(\sigma_{23}^t \circ (\gamma \otimes I_{\mathcal{A}}) + \sigma_{34}^t \circ \sigma_{24}^t \circ \sigma_{12}^t \circ (I_{\mathcal{A}} \otimes \gamma)\right) (x_1 \otimes x_2). \quad (5.20)$$

- iii. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a left Leibniz algebra with bracket (5.2) and $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a right Leibniz algebra with bracket from type (5.3) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_X^{(l)} + ad_X^{(l)} \otimes 1_{\mathcal{G}}\right) \delta(Y) \quad \forall X, Y \in \mathcal{G}$$

- iv. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ and $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ are both right Leibniz algebra with bracket from type (5.3) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1_{\mathcal{G}}\right) \delta(X) \quad \forall X, Y \in \mathcal{G},$$

where in the above two cases we have

$$\delta(x_1 \otimes x_2) = \left(\sigma_{34}^t \circ \sigma_{24}^t \circ \sigma_{12}^t \circ (\gamma \otimes \sigma_{23}^t \circ I_{\mathcal{A}}) + \sigma_{12}^t \circ (I_{\mathcal{A}} \otimes \gamma)\right) (x_1 \otimes x_2). \quad (5.21)$$

(c) If \mathcal{A}^* be the third 3-Leibniz algebra then we have:

- i. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a left Leibniz algebra with bracket (5.2) and $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a left Leibniz algebra with bracket from type (5.4) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_X^{(l)} + ad_X^{(l)} \otimes 1_{\mathcal{G}}\right) \delta(Y) \quad \forall X, Y \in \mathcal{G}$$

- ii. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a right Leibniz algebra with bracket (5.3) and $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ be a left Leibniz algebra with bracket from type (5.4) then we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_Y^{(r)} + ad_Y^{(r)} \otimes 1_{\mathcal{G}}\right) \delta(X) \quad \forall X, Y \in \mathcal{G}$$

where in the above two cases we have

$$\delta(x_1 \otimes x_2) = \left(\gamma \otimes I_{\mathcal{A}} + \sigma_{23}^t \circ \sigma_{12}^t \circ (I_{\mathcal{A}} \otimes \gamma)\right) (x_1 \otimes x_2). \quad (5.22)$$

3. If (\mathcal{A}, γ) be a 3-Leibniz bialgebra such that (3.41) is valid for $\gamma[x_1, x_2, x_3]$ then $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ with bracket (5.4) is a left Leibniz algebra and also \mathcal{A}^* can be 3-Leibniz algebra from three types

(a) If \mathcal{A}^* is the first 3-Leibniz algebra then $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ with bracket from type (5.1) is a right Leibniz algebra then we have

$$\delta(x_1 \otimes x_2) = (\sigma_{34}^t \circ \sigma_{24}^t \circ (\gamma \otimes I_{\mathcal{A}}) + I_{\mathcal{A}} \otimes \gamma) (x_1 \otimes x_2). \quad (5.23)$$

(b) If \mathcal{A}^* is the second 3-Leibniz algebra then we have

i. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a left Leibniz algebra with bracket (5.2) then we have

$$\delta(x_1 \otimes x_2) = (\sigma_{23}^t \circ (\gamma \otimes I_{\mathcal{A}}) + \sigma_{34}^t \circ \sigma_{24}^t \circ \sigma_{12}^t \circ (I_{\mathcal{A}} \otimes \gamma)) (x_1 \otimes x_2). \quad (5.24)$$

ii. If $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be a right Leibniz algebra with bracket (5.3) then we have

$$\delta(x_1 \otimes x_2) = (\sigma_{34}^t \circ \sigma_{24}^t \circ \sigma_{12}^t \circ (\gamma \otimes I_{\mathcal{A}}) + \sigma_{23}^t \circ (I_{\mathcal{A}} \otimes \gamma)) (x_1 \otimes x_2). \quad (5.25)$$

(c) If \mathcal{A}^* is the second 3-Leibniz algebra then $\mathcal{G}^* = \mathcal{A}^* \otimes \mathcal{A}^*$ with bracket from type (5.4) is a left Leibniz algebras then we have

$$\delta(x_1 \otimes x_2) = (\gamma \otimes I_{\mathcal{A}} + \sigma_{23}^t \circ \sigma_{12}^t \circ (I_{\mathcal{A}} \otimes \gamma)) (x_1 \otimes x_2). \quad (5.26)$$

where in the above cases we have

$$\delta[X, Y] = \left(1_{\mathcal{G}} \otimes ad_X^{(l)} + ad_X^{(l)} \otimes 1_{\mathcal{G}} \right) \delta(Y) \quad \forall X, Y \in \mathcal{G}$$

The proof of inverse is clearly. ■

6 3-Lie bialgebras

In this section we suppose \mathcal{A} is a 3-Lie algebra as a special case, then we have the following fundamental identity for $n = 3$

$$[x_1, x_2, [y_1, y_2, y_3]] = [[x_1, x_2, y_1], y_2, y_3] + [y_1, [x_1, x_2, y_2], y_3] + [y_1, y_2, [x_1, x_2, y_3]], \quad (6.1)$$

We want to define bialgebra structure for 3-Lie algebra similar to 3-Leibniz algebra with a little difference.

Remark 6.1 *In Definition 2.7 if ρ satisfies only in identity (2.11) we say ρ is a semi-representation of \mathcal{A} in V .*

If $V = \mathcal{A}$ it is clearly that $\rho : \mathcal{A} \otimes \mathcal{A} \longrightarrow End(\mathcal{A})$ with the following relation

$$\rho(x_1, x_2)(z) = ad_{(x_1, x_2, x_3)}(z) = [x_1, x_2, z],$$

is a representation of \mathcal{A} in \mathcal{A} .

Remark 6.2 If $\rho_i : \mathcal{A} \otimes \mathcal{A} \longrightarrow \text{End}(V_i), i = 1, 2, 3$ are three representation of \mathcal{A} in vector spaces V_i then $\rho : \mathcal{A} \otimes \mathcal{A} \longrightarrow \text{End}(V_1 \otimes V_2 \otimes V_3)$ with the following identities

$$\begin{aligned} \rho(x_1, x_2)(y_1 \otimes y_2 \otimes y_3) &= \rho_1(x_1, x_2)(y_1) \otimes y_2 \otimes y_3 + y_1 \otimes \rho_2(x_1, x_2)(y_2) \otimes y_3 \\ &\quad + y_1 \otimes y_2 \otimes \rho_3(x_1, x_2)(y_3), \end{aligned} \quad (6.2)$$

$\forall x_1, x_2 \in \mathcal{A}, \forall y_i \in V_i, i = 1, 2, 3$ is not a representation of \mathcal{A} in $V_1 \otimes V_2 \otimes V_3$ but it is a semi-representation of \mathcal{A} in $V_1 \otimes V_2 \otimes V_3$. Note that in Lie algebra case the tensor product of representations of Lie algebra in vector spaces $V_i, i = 1, \dots, n$ is a representation of Lie algebra in $V_1 \otimes V_2 \otimes \dots \otimes V_n$. If $V_1 = V_2 = V_3 = \mathcal{A}$ then $\rho : \mathcal{A} \otimes \mathcal{A} \longrightarrow \text{End}(\mathcal{A}^{\otimes 3})$ with the following relation

$$\begin{aligned} \rho(y_1, y_2)(z_1 \otimes z_2 \otimes z_3) &= (ad_{(y_1, y_2, \hat{y}_3)} \otimes 1 \otimes 1 + 1 \otimes ad_{(y_1, y_2, \hat{y}_3)} \otimes 1 + 1 \otimes 1 \otimes ad_{(y_1, y_2, \hat{y}_3)})(z_1 \otimes z_2 \otimes z_3) \\ &:= ad_{(y_1, y_2, \hat{y}_3)}^{(3)}(z_1 \otimes z_2 \otimes z_3), \end{aligned} \quad (6.3)$$

is a semi-representation of \mathcal{A} in $\mathcal{A}^{\otimes 3}$.

We need to generalize definition 2.8 for any representation of \mathcal{A} in any vector space V .

Definition 6.3 Let \mathcal{A} be a 3-Lie algebra, an V -valued p -cochain is a linear map $\psi : (\mathcal{A} \otimes \mathcal{A})^{\otimes (p-1)} \otimes \mathcal{A} \longrightarrow V$ and denote the space of V -valued p -cochains with $\Gamma^p(\mathcal{A}, V)$, the coboundary operator is given by:

$$\begin{aligned} d^p \psi(x_1, \dots, x_{2p+1}) &= \sum_{j=1}^p \sum_{k=2j+1}^{2p+1} (-1)^j \psi(x_1, \dots, \hat{x}_{j-1}, \hat{x}_j, \dots, [x_{2j-1}, x_{2j}, x_k], \dots, x_{2p+1}) \\ &\quad + \sum_{k=1}^p \rho(x_{2k-1}, x_{2k}, \psi(x_1, \dots, \hat{x}_{2k-1}, \hat{x}_{2k}, \dots, x_{2p+1})) \\ &\quad - (-1)^{p+1} \rho(x_{2p-1}, x_{2p+1}, \psi(x_1, \dots, x_{2p-2}, x_{2p}),) \\ &\quad + (-1)^{p+1} \rho(x_{2p}, x_{2p+1}, \psi(x_1, \dots, x_{2p-1})), \end{aligned}$$

where $\rho : \mathcal{A} \otimes \mathcal{A} \longrightarrow \text{End}(V)$ is a representation of \mathcal{A} in V .

For $p = 1$ we have

$$d^1 \psi(x_1, x_2, x_3) = -\psi([x_1, x_2, x_3]) + \rho(x_1, x_2, \psi(x_3)) - \rho(x_1, x_3, \psi(x_2)) + \rho(x_2, x_3, \psi(x_1))$$

Definition 6.4 A 3-Lie bialgebra (\mathcal{A}, γ) is a 3-Lie algebra \mathcal{A} with a linear map (cocommutator) $\gamma : \mathcal{A} \longrightarrow \mathcal{A}^{\otimes 3}$ such that

- γ is a 1-cocycle on \mathcal{A} with values in $\mathcal{A}^{\otimes 3}$,

$$\gamma[y_1, y_2, y_3] = \rho(y_2, y_3, \gamma(y_1)) + \rho(y_3, y_1, \gamma(y_2)) + \rho(y_1, y_2, \gamma(y_3)), \quad (6.4)$$

where ρ is a semi-representation of \mathcal{A} in $\mathcal{A}^{\otimes 3}$.

- $\gamma^t : \mathcal{A}^{*\otimes 3} \longrightarrow \mathcal{A}$ defines a 3-Lie bracket on \mathcal{A}^* .

If we use the (3.37) then we have relation (3.38) similar to 3-Leibniz bialgebra.

By use of (6.3) 1-cocycle condition (6.4) is rewritten as follows

$$\gamma[y_1, y_2, y_3] = ad_{(y_2, y_3, \hat{y}_1)}^{(3)}\gamma(y_1) + ad_{(y_3, y_1, \hat{y}_2)}^{(3)}\gamma(y_2) + ad_{(y_1, y_2, \hat{y}_3)}^{(3)}\gamma(y_3). \quad (6.5)$$

Proposition 6.5 *If (\mathcal{A}, γ) is a 3-Lie bialgebra, and μ is the 3-Lie bracket of \mathcal{A} , then (\mathcal{A}, μ^t) is a 3-Lie bialgebra, where γ^t is the 3-Lie bracket of \mathcal{A}^* .*

Proof. By use of (3.38) and (6.5) the proof is clearly. ■

Theorem 6.6 *Let (\mathcal{A}, γ) be a 3-Lie bialgebra and $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ be its associated Leibniz algebra then there exist a linear map $\delta : \mathcal{G} \longrightarrow \mathcal{G} \otimes \mathcal{G}$ such that it defines a Lie bialgebra structure on \mathcal{G} . Conversely if (\mathcal{G}, δ) is a Lie bialgebra such that $\mathcal{G} = \mathcal{A} \otimes \mathcal{A}$ and \mathcal{A} be a 3-Lie algebra then there exist a linear map $\gamma : \mathcal{A} \longrightarrow \mathcal{A} \otimes \mathcal{A} \otimes \mathcal{A}$ such that it defines a 3-Lie bialgebra structure on \mathcal{A} .*

Proof. From the theorem 5.1 the proof is clearly. ■

6.1 3-Lie bialgebra in terms of structure constants; some examples

Here we rewrite the 1-cocycle condition (6.5) in terms of structure constants of the 3-Lie algebra \mathcal{A} and \mathcal{A}^* . Note that in this case we have (4.1) and (4.3) same as 3-Leibniz algebra with difference that the structure constants are antisymmetric.

$$\gamma[x_i, x_s, x_n] = ad_{(x_s, x_n, \hat{x}_i)}^{(3)}\gamma(x_i) + ad_{(x_n, x_i, \hat{x}_s)}^{(3)}\gamma(x_s) + ad_{(x_i, x_s, \hat{x}_n)}^{(3)}\gamma(x_n). \quad (6.6)$$

Using (3.38) and (4.1) in (6.6) we have

$$\begin{aligned} f_{isn}^p \tilde{f}^{jkm}_p &= f_{j'sn}^j \tilde{f}^{j'km}_i + f_{k'sn}^k \tilde{f}^{jk'm}_i + f_{m'sn}^m \tilde{f}^{jkm'}_i \\ &+ f_{ij'n}^j \tilde{f}^{j'km}_s + f_{ik'n}^k \tilde{f}^{jk'm}_s + f_{im'n}^m \tilde{f}^{jkm'}_s \\ &+ f_{isj'}^j \tilde{f}^{j'km}_n + f_{isk'}^k \tilde{f}^{jk'm}_n + f_{ism'}^m \tilde{f}^{jkm'}_n. \end{aligned} \quad (6.7)$$

Definition 6.7 *Two 3-Lie algebra \mathcal{A} and \mathcal{A}^* construct a 3-Lie bialgebra if their structure constants satisfy in relations (6.7).*

To use this relation in the calculations, one can rewrite t in terms of the matrix form using the following adjoint representations:

$$\begin{aligned}
f_{isn}{}^p &= (\chi_{is})_n{}^p = (Y_i{}^p)_{sn} = f_{sni}{}^p = (\chi_{sn})_i{}^p = (Y_s{}^p)_{ni} \\
&= f_{nis}{}^p = (\chi_{ni})_s{}^p = (Y_n{}^p)_{is} = -f_{sin}{}^p = -(\chi_{si})_n{}^p = -(Y_s{}^p)_{in} \\
&= -f_{nsi}{}^p = -(\chi_{ns})_i{}^p = -(Y_n{}^p)_{si} = f_{ins}{}^p = -(\chi_{in})_s{}^p = -(Y_i{}^p)_{ns}, \tag{6.8}
\end{aligned}$$

$$\begin{aligned}
\tilde{f}^{jkm}{}_p &= (\tilde{\chi}^{jk})^m{}_p = (\tilde{Y}^j{}_p)^{km} = \tilde{f}^{kmj}{}_p = (\tilde{\chi}^{km})^j{}_p = (\tilde{Y}^k{}_p)^{mj} \\
&= \tilde{f}^{mjk}{}_p = (\tilde{\chi}^{mj})^k{}_p = (\tilde{Y}^m{}_p)^{jk} = -\tilde{f}^{kjm}{}_p = -(\tilde{\chi}^{kj})^m{}_p = -(\tilde{Y}^k{}_p)^{jm} \\
&= -\tilde{f}^{mkj}{}_p = -(\tilde{\chi}^{mk})^j{}_p = -(\tilde{Y}^m{}_p)^{kj} = -\tilde{f}^{jmk}{}_p = -(\tilde{\chi}^{jm})^k{}_p = -(\tilde{Y}^j{}_p)^{mk}. \tag{6.9}
\end{aligned}$$

Then relation (6.7) has the following matrix form

$$\begin{aligned}
\chi_{ns}(\tilde{\chi}^{mk})^t &= (\tilde{\chi}^{mk})^t(\chi_{ns}) - (\chi_{k's})_n{}^k(\tilde{\chi}^{mk'})^t - (\tilde{\chi}^{m'k})^t(\chi_{m's})_n{}^m \\
&\quad - (\tilde{\chi}^{j'k})^m{}_s(\chi_{nj'}) + Y_n{}^k(\tilde{Y}^m{}_s)^t + Y_n{}^p\tilde{Y}^k{}_s \\
&\quad - (\tilde{\chi}^{j'k})^m{}_n\chi_{j's} - Y_s{}^k(\tilde{Y}^m{}_n)^t + Y_s{}^m(\tilde{Y}^k{}_s)^t, \tag{6.10}
\end{aligned}$$

where in the above relation t stands for transpose of a matrix. Fundamental identity for 3-Lie algebra \mathcal{A}^* in terms of structure constant has the following form

$$\tilde{f}^{nsj}{}_p\tilde{f}^{mkp}{}_i = \tilde{f}^{mkn}{}_p\tilde{f}^{psj}{}_i + \tilde{f}^{mks}{}_p\tilde{f}^{npj}{}_i + \tilde{f}^{mkj}{}_p\tilde{f}^{nsp}{}_i, \tag{6.11}$$

with the matrix form as

$$\tilde{\chi}^{ns}\tilde{\chi}^{mk} = (\tilde{\chi}^{mk})^n{}_p\tilde{\chi}^{ps} + (\tilde{\chi}^{mk})^s{}_p\tilde{\chi}^{np} + \tilde{\chi}^{mk}\tilde{\chi}^{ns}. \tag{6.12}$$

Now for obtaining the dual of \mathcal{A} one must solve the following equations

$$\begin{aligned}
&(\tilde{\chi}^{mk})^t(\chi_{ns}) - (\chi_{k's})_n{}^k(\tilde{\chi}^{mk'})^t - (\tilde{\chi}^{m'k})^t(\chi_{m's})_n{}^m - (\tilde{\chi}^{j'k})^m{}_s(\chi_{nj'}) + Y_n{}^k(\tilde{Y}^m{}_s)^t + Y_n{}^p\tilde{Y}^k{}_s \\
&- (\tilde{\chi}^{j'k})^m{}_n\chi_{j's} - Y_s{}^k(\tilde{Y}^m{}_n)^t + Y_s{}^m(\tilde{Y}^k{}_s)^t - \chi_{ns}(\tilde{\chi}^{mk})^t = 0, \\
&(\tilde{\chi}^{mk})^n{}_p(\tilde{\chi}^{ps}) + (\tilde{\chi}^{mk})^s{}_p(\tilde{\chi}^{np}) + (\tilde{\chi}^{mk})(\tilde{\chi}^{ns}) - (\tilde{\chi}^{ns})(\tilde{\chi}^{mk}) = 0. \tag{6.13}
\end{aligned}$$

Example 6.8 We consider the following four dimentional 3-Lie algebra [?]

$$[e_2, e_3, e_4] = e_1, \quad [e_1, e_3, e_4] = e_2,$$

for this example we have

$$\begin{aligned} \chi_{13} &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}, & \chi_{14} &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, & \chi_{23} &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}, \\ \chi_{24} &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, & \chi_{34} &= \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ Y_1^2 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}, & Y_2^1 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}, & Y_3^1 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}, \\ Y_3^2 &= \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}, & Y_4^1 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, & Y_4^2 &= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}. \end{aligned}$$

By solving the system of equations (6.13) we obtain the following 3-Lie algebras as dual of \mathcal{A}

$$\begin{aligned} [\tilde{e}^1, \tilde{e}^2, \tilde{e}^4]_* &= b\tilde{e}^1, & [\tilde{e}^3, \tilde{e}^2, \tilde{e}^4]_* &= b\tilde{e}^3, \\ [\tilde{e}^2, \tilde{e}^3, \tilde{e}^1]_* &= b\tilde{e}^2, & [\tilde{e}^4, \tilde{e}^3, \tilde{e}^1]_* &= b\tilde{e}^4, \end{aligned}$$

where b is any non zero real number.

7 Conclusion

In this paper we defined the 3-Leibniz and 3-Lie bialgebras using cohomology of 3-Leibniz and 3-Lie algebras. Many theorems have been given, in particular, we have proven the correspondence between 3-Leibniz bialgebra and its associated Leibniz bialgebras. There are some open problems related to this work. The definition of r -matrix and Yang-Baxter equation were related to 3-Leibniz and 3-Lie bialgebra. Applying the definition of 3-Lie bialgebra in M theory [10, 11, 12] as a physical application is our future [22]. We know that for the Nambu-Lie group G [23] on the dual space \mathcal{G}^* of the Lie algebra \mathcal{G} we have an n -Lie algebra structure. One can also investigate the concept of Nambu-Poisson-Lie group and the relation between 3-Lie bialgebra and Lie bialgebra on the space \mathcal{G} [24].

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