

The Lie algebra of vector fields - overview
pp 40-50

2.4.3 Lie bracket [p. 45]

$$\begin{array}{c} \mathbb{R}^k \\ \cup \\ M \text{ smooth} \end{array}$$

$X, Y \in \text{Vect } M$ smooth maps $M \rightarrow \mathbb{R}^k$ $X(p), Y(p) \in T_p M \subset \mathbb{R}^k$

$dX(p)$ is a linear map $: T_p(M) \rightarrow \mathbb{R}^k = \underline{T_{X(p)} \mathbb{R}^k}$

lemma 2.4.18 [p. 46] If X and Y are complete vector fields then $\underline{dX(p)Y(p) - dY(p)X(p)} \in T_p(M)$

Def 2.4.19 [p. 48] The Lie bracket of complete vector fields X, Y $[X, Y]$ is $\underline{[X, Y](p) = dX(p)Y(p) - dY(p)X(p)}$
 $[X, Y]$ is a smooth vector field

lemma 2.4.20 [p. 48] For vector fields X, Y, Z on M

$$[X, Y] = -[Y, X]$$

$$[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$$

Example 2.4.22 [p. 49]

$(\text{Vect } M, [\cdot, \cdot])$ is a Lie algebra.

2.4.2 Flow of a vector field

$M \subset \mathbb{R}^k$ smooth m -manifold, $X \in \text{Vect } M$ smooth vector field

$p_0 \in M$ By Theorem 2.4.7 (i) (p. 38) $\exists$ open interval

$0 \in I \subset \mathbb{R}$ and smooth map $\gamma: I \rightarrow M$ (curve)

$$(2.4.1) \rightarrow \dot{\gamma}(t) = X(\gamma(t)), \gamma(0) = p_0, t \in I.$$

let $I(p_0) :=$ the union of all such intervals I

Then $\exists$ smooth $\Gamma: I(p_0) \rightarrow M$ satisfying the initial value

$$\text{problem (2.4.1)}: \Gamma(0) = p_0, \dot{\Gamma}(t) = X(\Gamma(t)) \quad \forall t \in I(p_0)$$

" $\Gamma = \Gamma_{p_0}$ " (see the next page (3) for details)

Definition 2.4.8 p. 40 (The flow of a vector field)

let $\mathcal{D} = \{(t, p_0) : p_0 \in M, t \in I(p_0)\} \subseteq \mathbb{R} \times M$

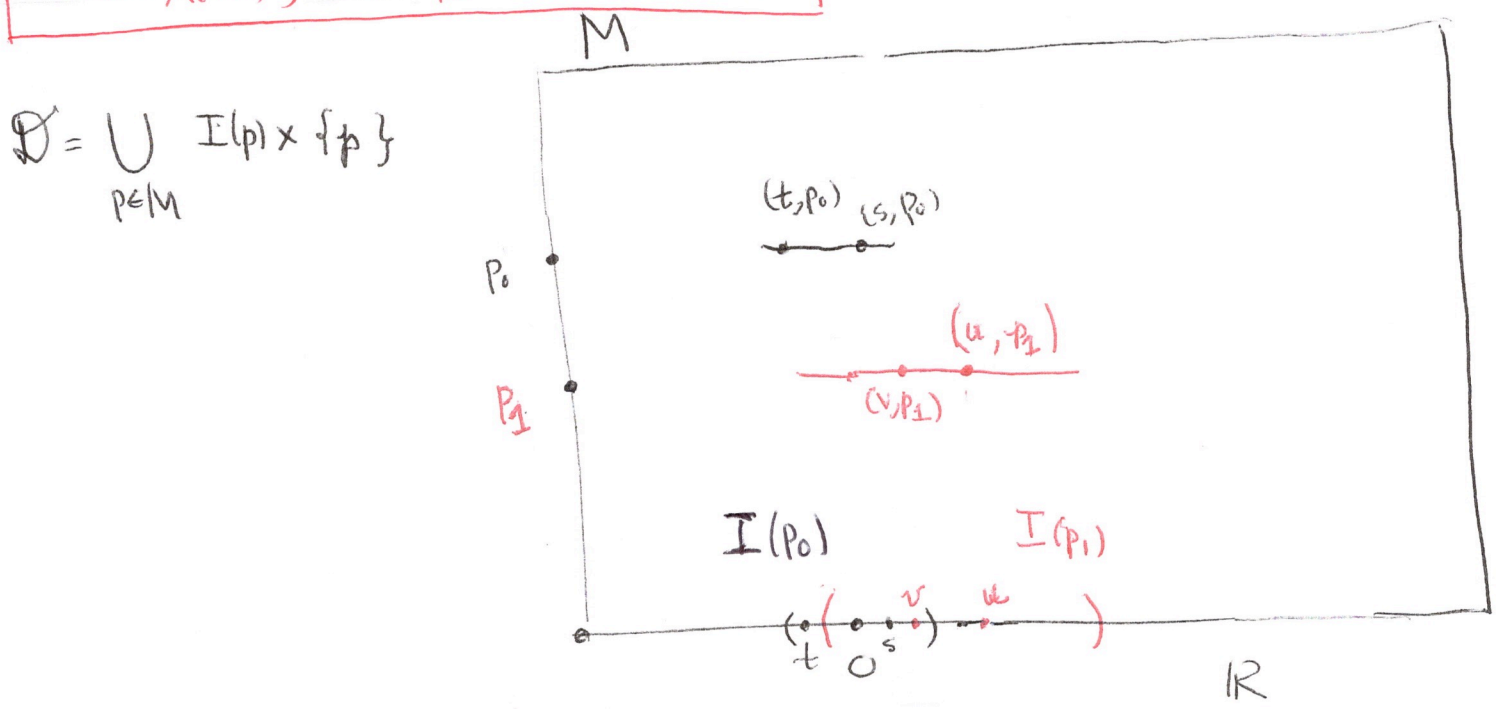
and define $\phi: \mathcal{D} \rightarrow M$ by $\phi(t, p_0) = \Gamma(t)$

ϕ is the flow of the vector field X

$$\frac{d}{dt} \phi(t, p_0) = \dot{\Gamma}(t) = X(\Gamma(t)) = X(\phi(t, p_0))$$

$$\phi(0, p_0) = \Gamma(0) = p_0.$$

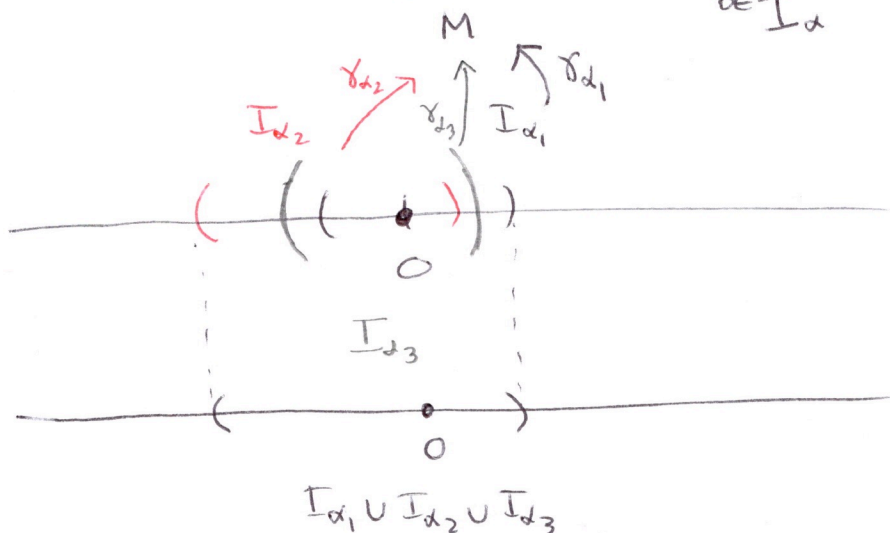
$\phi(0, p_0)$ is the solution of the initial value problem
 $u'(t) = X(u(t)), u(0) = p_0$ on $I(p_0)$



(3)

For a fixed vector field X ,

$$I(p_0) = \bigcup_{\alpha \in A} \{ I_\alpha : \exists \gamma_\alpha^{\text{smooth}} : I_\alpha \rightarrow M \mid \gamma_\alpha(0) = p_0, \gamma_\alpha'(t) = X(\gamma_\alpha(t)) \forall t \in I_\alpha \}$$

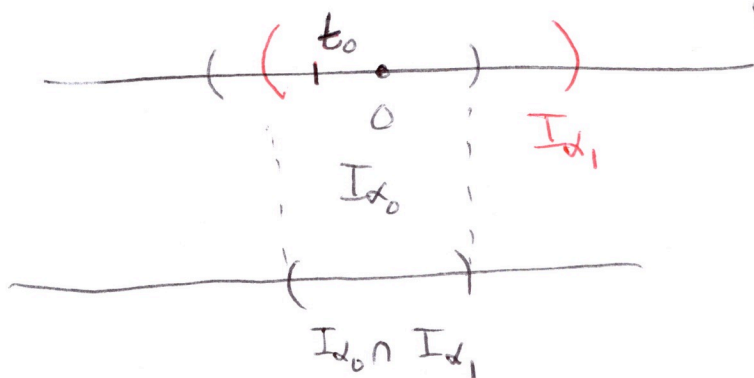


Define $\Pi : I(p_0) \rightarrow M$ as follows. If $t_0 \in I(p_0)$, then

$t_0 \in I_{\alpha_0}$ for some I_{α_0} so define $\Pi(t_0) = \gamma_{\alpha_0}(t_0)$

Is Π well defined? Let $t_0 \in I_{\alpha_1}$ also.

we need $\gamma_{\alpha_0}(t_0) = \gamma_{\alpha_1}(t_0)$



This follows from part (ii)

of Theorem 2.4.7 which

states that $\gamma_{\alpha_0}(t) = \gamma_{\alpha_1}(t)$

$\forall t \in I_{\alpha_0} \cap I_{\alpha_1}$

Theorem 2.4.9 p. 40 $M \subset \mathbb{R}^k$ m-mfld, $X \in \text{Vect } M$, $\phi: \mathcal{D} \rightarrow M$ flow of X
 $\Rightarrow$ ① $\mathcal{D}$ is an open subset of $\mathbb{R} \times M \subseteq \mathbb{R}^{k+1}$

(ii) $\phi: \mathcal{D} \rightarrow M$ is smooth map

(iii) let $p_0 \in M$, $s \in I(p_0)$. Then

Proof of Th 2.4.9
on p. 41

$$(2.4.3) \quad I(\phi(s, p_0)) = I(p_0) - s$$

$$(2.4.4) \quad \phi(s+t, p_0) = \phi(t, \phi(s, p_0)), \quad \forall t \in \mathbb{R} \text{ with } s+t \in I(p_0)$$

Definition 2.4.11 (p. 41) X is a complete vector field if $I(p_0) = \mathbb{R} \forall p_0 \in M$

Lemma 2.4.12 (p. 42) If $M \subset \mathbb{R}^k$ is a compact manifold then every vector field on M is complete.

Remark (p. 42) let $M \subset \mathbb{R}^k$ be a smooth mfd, $X \in \text{Vect } M$

$$X \text{ is complete} \iff I(p) = \mathbb{R} \forall p \in M \iff \mathcal{D} = \mathbb{R} \times M$$

If X is complete, with flow $\phi: \mathcal{D} = \mathbb{R} \times M \rightarrow M$, write, for $t \in \mathbb{R}$

$$\phi^t: M \rightarrow M, \quad \phi^t(p) = \phi(t, p). \quad \text{Then}$$

• ϕ^t is smooth, $\forall t \in \mathbb{R}$ (Th 2.4.9(ii))

$$\text{Diff}(M) :=$$

$$\{ \phi: M \rightarrow M : \phi \text{ is a diffeomorphism} \}$$

$$(2.4.5) \quad \phi^{s+t} = \phi^s \circ \phi^t, \quad \phi^0 = \text{id}_M \quad (\text{Th 2.4.9(iii)})$$

[proof $\phi^{s+t}(p) = \phi(s+t, p) = \phi(t, \phi(s, p)) = \phi^t(\phi(s, p)) = \phi^t(\phi^s(p)) = \phi^t \circ \phi^s(p)$]

• ϕ^t is bijective, $(\phi^t)^{-1} = \phi^{-t}$, so ϕ^t is a diffeomorphism.

[proof $\phi^0(p) = \phi(0, p) = p$ so $\phi^0 = \text{id}_M$ $\phi^t \circ \phi^{-t} = \phi^0 = \text{id}_M$] (smooth) what is the manifold structure of $\text{Diff}(M)$?

• $\mathbb{R} \ni t \rightarrow \phi^t \in \text{Diff}(M)$ is a group homomorphism

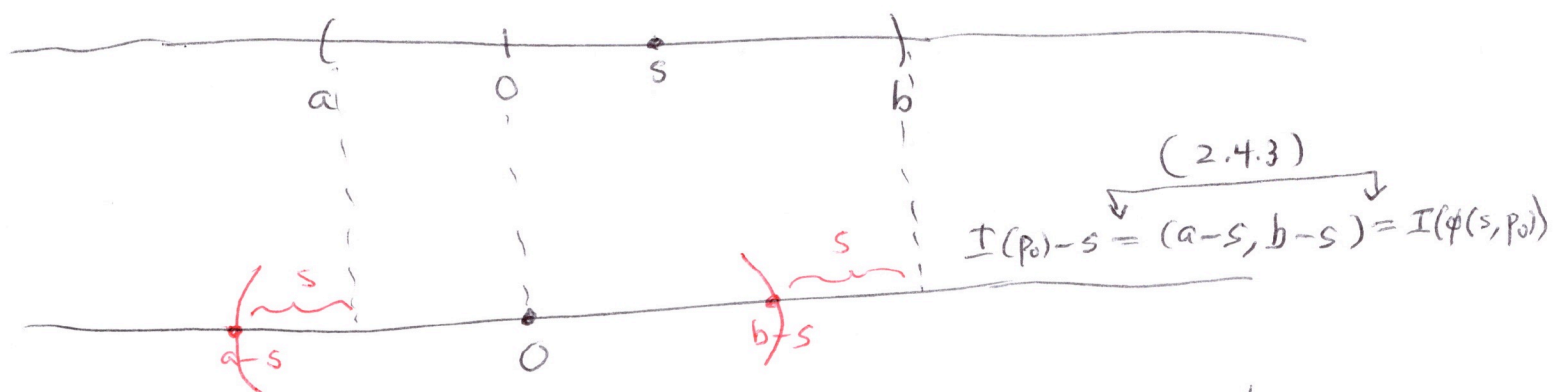
$$(\mathbb{R}, +)$$

$$(\text{Diff}(M), \circ)$$

$$\frac{d}{dt} \phi^t(p) = X(\phi^t(p)), \quad \phi^0(p) = p$$

proof of (2.4.4) assuming (2.4.3)

$$I(p_0) = (a, b)$$



$$s+t \in (a, b) \Leftrightarrow a < s+t < b \Leftrightarrow a-s < t < b-s$$

$\phi(\cdot, p_0)$ is the unique solution of $u'(t) = X(u(t))$, $u(0) = p_0$, t inside $I(p_0)$

$\phi(\cdot, \phi(s, p_0))$ is the unique solution of $u'(t) = X(u(t))$, $u(0) = \phi(s, p_0)$, t inside $I(\phi(s, p_0))$

Fix $s \in I(p_0)$. Consider $\gamma(t) = \phi(s+t, p_0)$ for $t \in I(p_0) - s$

$$\gamma(0) = \phi(s, p_0) \quad \text{and} \quad \dot{\gamma}(t) = \frac{d}{dt} \phi(s+t, p_0) = \frac{d}{dr} \phi(r, p_0)$$

$$r(t) = s+t \quad \frac{dr}{dt} = 1$$

$$\text{So } \dot{\gamma}(t) = \frac{d}{dr} \phi(r, p_0) \cdot \frac{dr}{dt} = \frac{d}{dr} \phi(r, p_0) = X(\phi(r, p_0)) = X(\phi(s+t, p_0)) = X(\gamma(t))$$

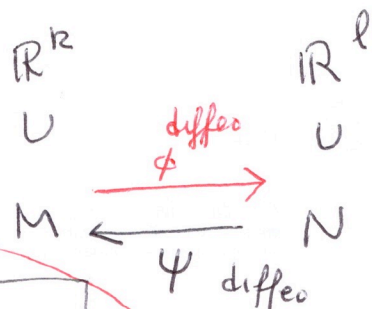
Thus γ is a solution of $u'(t) = X(u(t))$, $\gamma(0) = \phi(s, p_0)$ for t in the interval $I(p_0) \cap (I(p_0) - s) = (a, b-s)$

By uniqueness of solutions $\gamma(t) = \phi(t, \phi(s, p_0))$ for $t \in (a, b-s)$

$$\phi(s+t, p_0)$$



2.4.3 p. 45



$$\phi_* X(q) = d\phi(\bar{\phi}^{-1}(q)) X(\bar{\phi}^{-1}(q))$$

$$\phi_* X \in \text{Vect } N$$

Def: $\phi_* X =$
pushforward
of X under ϕ

given
 $\text{Vect } M \ni X$

Def: $\psi^* X =$
pullback of X
under ψ

$$\psi^* X(q) = d\psi(q)^{-1} (X(\psi(q)))$$

$$\psi^* X \in \text{Vect } N$$

$$\psi: N \rightarrow M$$

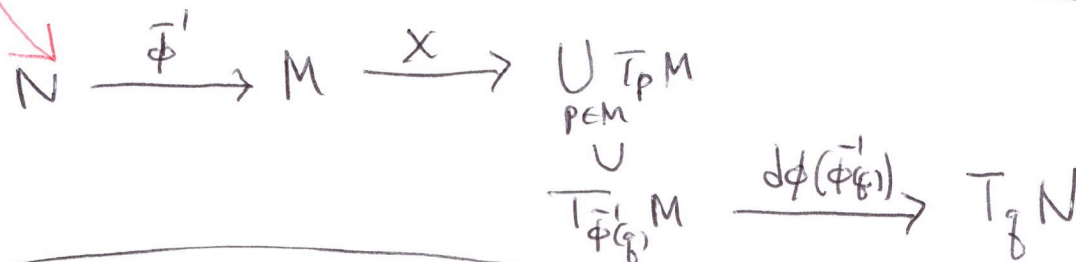
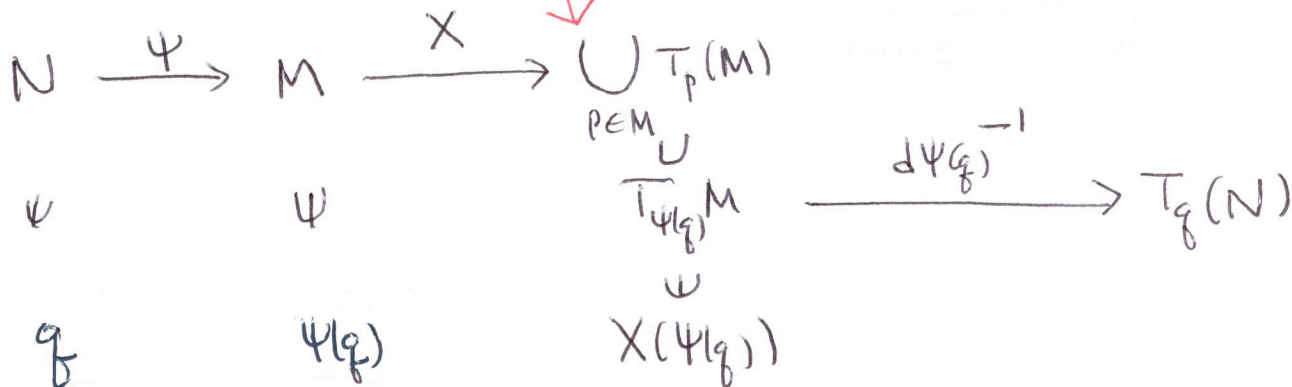
$$d\psi(q): T_q N \rightarrow T_{\psi(q)} M$$

$$d\psi(q)^{-1}: T_{\psi(q)} M \rightarrow T_q(N)$$

$$\phi: M \rightarrow N$$

$$d\phi(p): T_p M \rightarrow T_{\phi(p)} N$$

$$d\phi(\bar{\phi}^{-1}(q)): T_{\bar{\phi}^{-1}(q)} M \rightarrow T_q N$$



Lemma 2.4.18 p. 46 $M \subset \mathbb{R}^k$ m -mfd $X, Y \in \text{Vect } M$ (complete)

let $t \rightarrow \phi^t$ be the flow of X , $t \rightarrow \psi^t$ the flow of Y
 $(\mathbb{R} \rightarrow \text{Diff}(M))$ $(\mathbb{R} \rightarrow \text{Diff}(M))$

Fix $p \in M$ & let $\gamma: \mathbb{R} \rightarrow M$ $\gamma(t) = \phi^t \circ \psi^t \circ \phi^{-t} \circ \psi^{-t}(p)$

Then

- $\dot{\gamma}(0) = 0$

- $\frac{1}{2} \ddot{\gamma}(0) = \frac{d}{ds} \Big|_{s=0} ((\phi^s)_* Y)(p)$
 $= \frac{d}{dt} \Big|_{t=0} ((\psi^t)^* X)(p)$
 $= dX(p)Y(p) - dY(p)X(p) \in T_p M$

Definition 2.4.19 $[X, Y](p) = dX(p)Y(p) - dY(p)X(p)$

is the Lie bracket of the vector fields X and Y

Lemma 2.4.20 Let $M \subset \mathbb{R}^k$ be a smooth manifold.

(2.4.18) • For $X, Y \in \text{Vect } M$, $[X, Y] + [Y, X] = 0$

(2.4.19) • For $X, Y, Z \in \text{Vect } M$, $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$

Let $\phi: M \rightarrow N$ be a diffeomorphism of smooth manifolds M, N

Then for $X, Y \in \text{Vect } M$,

(2.4.17) • $\phi^*[X, Y] = [\phi^*X, \phi^*Y]$