## DERIVATIONS

Introduction to non-associative algebra

## OR

Playing havoc with the product rule?

PART I-ALGEBRAS

BERNARD RUSSO University of California, Irvine

UNDERGRADUATE COLLOQUIUM UCI Anteater Mathematics Club event

$$
\begin{aligned}
& \text { MAY 2, } 2011 \\
& (5: 30 \text { PM) }
\end{aligned}
$$

# PART II-TRIPLE SYSTEMS <br> 2011-2012 <br> (DATE AND TIME TBA) 

## PART I-ALGEBRAS <br> Sophus Lie (1842-1899)



Marius Sophus Lie was a Norwegian mathematician. He largely created the theory of continuous symmetry, and applied it to the study of geometry and differential equations.

## Pascual Jordan (1902-1980)



Pascual Jordan was a German theoretical and mathematical physicist who made significant contributions to quantum mechanics and quantum field theory.

## THE DERIVATIVE

$$
f^{\prime}(x)=\lim _{h \rightarrow 0} \frac{f(x+h)-f(x)}{h}
$$

## DIFFERENTIATION IS A LINEAR PROCESS

$$
\begin{gathered}
(f+g)^{\prime}=f^{\prime}+g^{\prime} \\
(c f)^{\prime}=c f^{\prime}
\end{gathered}
$$

THE SET OF DIFFERENTIABLE FUNCTIONS FORMS AN ALGEBRA $\mathcal{D}$

$$
\begin{gathered}
(f g)^{\prime}=f g^{\prime}+f^{\prime} g \\
(\text { product rule) }
\end{gathered}
$$

## HEROS OF CALCULUS

## \#1

## Sir Isaac Newton (1642-1727)



Isaac Newton was an English physicist, mathematician, astronomer, natural philosopher, alchemist, and theologian, and is considered by many scholars and members of
the general public to be one of the most influential people in human history.


## LEIBNIZ RULE

$$
\begin{aligned}
& (f g)^{\prime}=f^{\prime} g+f g^{\prime} \\
& \text { (order changed) }
\end{aligned}
$$

$* * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * *$

$$
(f g h)^{\prime}=f^{\prime} g h+f g^{\prime} h+f g h^{\prime}
$$

************************************

$$
\left(f_{1} f_{2} \cdots f_{n}\right)^{\prime}=f_{1}^{\prime} f_{2} \cdots f_{n}+\cdots+f_{1} f_{2} \cdots f_{n}^{\prime}
$$

The chain rule,

$$
\begin{aligned}
& (f \circ g)^{\prime}(x)=f^{\prime}(g(x)) g^{\prime}(x) \\
& \text { plays no role in this talk }
\end{aligned}
$$

Neither does the quotient rule

$$
(f / g)^{\prime}=\frac{g f^{\prime}-f g^{\prime}}{g^{2}}
$$

## \#2

## Gottfried Wilhelm Leibniz (1646-1716)



Gottfried Wilhelm Leibniz was a German mathematician and philosopher. He developed the infinitesimal calculus independently of Isaac Newton, and Leibniz's mathematical notation has been widely used ever since it was published.


## CONTINUITY

$$
x_{n} \rightarrow x \Rightarrow f\left(x_{n}\right) \rightarrow f(x)
$$

## THE SET OF CONTINUOUS FUNCTIONS FORMS AN ALGEBRA $\mathcal{C}$

(sums, constant multiples and products of continuous functions are continuous)
$\mathcal{D}$ and $\mathcal{C}$ ARE EXAMPLES OF ALGEBRAS WHICH ARE BOTH ASSOCIATIVE AND COMMUTATIVE

PROPOSITION 1
EVERY DIFFERENTIABLE FUNCTION IS CONTINUOUS
$\mathcal{D}$ is a subalgebra of $\mathcal{C} ; \mathcal{D} \subset \mathcal{C}$

## DIFFERENTIATION IS A LINEAR PROCESS

## LET US DENOTE IT BY D AND WRITE $D f$ for $f^{\prime}$

$$
\begin{gathered}
D(f+g)=D f+D g \\
D(c f)=c D f \\
D(f g)=(D f) g+f(D g) \\
D(f / g)=\frac{g(D f)-f(D g)}{g^{2}}
\end{gathered}
$$

IS THE LINEAR PROCESS $D: f \mapsto f^{\prime}$ CONTINUOUS?
(If $f_{n} \rightarrow f$ in $\mathcal{D}$, does it follow that $f_{n}^{\prime} \rightarrow f^{\prime}$ ? ) (ANSWER: NO!)

# DEFINITION 1 <br> A DERIVATION ON $\mathcal{C}$ IS A LINEAR PROCESS SATISFYING THE LEIBNIZ RULE: 

$$
\begin{gathered}
\delta(f+g)=\delta(f)+\delta(g) \\
\delta(c f)=c \delta(f) \\
\delta(f g)=\delta(f) g+f \delta(g)
\end{gathered}
$$

THEOREM 1
There are no (non-zero) derivations on $\mathcal{C}$.

In other words,
Every derivation of $\mathcal{C}$ is identically zero

COROLLARY $\mathcal{D} \neq \mathcal{C}$
(NO DUUUH! $f(x)=|x|)$

# THEOREM 1A <br> (1955-Singer and Wermer) 

Every continuous derivation on $\mathcal{C}$ is zero.

## Theorem 1B

(1960-Sakai)
Every derivation on $\mathcal{C}$ is continuous.
(False for $\mathcal{D}$ )


John Wermer
(b. 1925)

Soichiro Sakai
(b. 1926)

Isadore Singer (b. 1924)


Isadore Manuel Singer is an Institute Professor in the Department of Mathematics at the Massachusetts Institute of Technology. He is noted for his work with Michael Atiyah in 1962, which paved the way for new interactions between pure mathematics and theoretical physics.

## DERIVATIONS ON THE SET OF MATRICES

THE SET $M_{n}(\mathbf{R})$ of $n$ by $n$ MATRICES IS AN ALGEBRA UNDER<br>MATRIX ADDITION<br>$$
A+B
$$<br>AND

MATRIX MULTIPLICATION
$A \times B$
WHICH IS ASSOCIATIVE BUT NOT commutative.

DEFINITION 2<br>A DERIVATION ON $M_{n}($ R $)$ WITH<br>RESPECT TO MATRIX MULTIPLICATION IS A LINEAR PROCESS $\delta$ WHICH SATISFIES THE LEIBNIZ RULE<br>$$
\delta(A \times B)=\delta(A) \times B+A \times \delta(B)
$$

## PROPOSITION 2

FIX A MATRIX $A$ in $M_{n}(\mathbf{R})$ AND DEFINE

$$
\delta_{A}(X)=A \times X-X \times A
$$

THEN $\delta_{A}$ IS A DERIVATION WITH RESPECT TO MATRIX MULTIPLICATION (WHICH CAN BE NON-ZERO)

THEOREM 2
(1942 Hochschild)

EVERY DERIVATION ON $M_{n}(\mathbf{R})$ WITH RESPECT TO MATRIX MULTIPLICATION IS OF THE FORM $\delta_{A}$ FOR SOME $A$ IN $M_{n}(\mathbf{R})$.

## Gerhard Hochschild (1915-2010)



Gerhard Paul Hochschild was an American mathematician who worked on Lie groups, algebraic groups, homological algebra and algebraic number theory.

(Photo 1976)

(Photo 1981)

## THE BRACKET PRODUCT ON THE SET OF MATRICES

THE BRACKET PRODUCT ON THE SET $M_{n}(\mathrm{R})$ OF MATRICES IS DEFINED BY

$$
[X, Y]=X \times Y-Y \times X
$$

THE SET $M_{n}(\mathbf{R})$ of $n$ by $n$ MATRICES IS AN ALGEBRA UNDER MATRIX ADDITION AND BRACKET MULTIPLICATION, WHICH IS NOT ASSOCIATIVE AND NOT COMMUTATIVE.

## DEFINITION 3

A DERIVATION ON $M_{n}(\mathbf{R})$ WITH RESPECT TO BRACKET MULTIPLICATION

IS A LINEAR PROCESS $\delta$ WHICH SATISFIES THE LEIBNIZ RULE

$$
\delta([A, B])=[\delta(A), B]+[A, \delta(B)]
$$

PROPOSITION 3
FIX A MATRIX $A$ in $M_{n}(\mathbf{R})$ AND DEFINE

$$
\delta_{A}(X)=[A, X]=A \times X-X \times A .
$$

THEN $\delta_{A}$ IS A DERIVATION WITH RESPECT TO BRACKET MULTIPLICATION

## THEOREM 3

(1942 Hochschild, Zassenhaus)
EVERY DERIVATION ON $M_{n}($ R $)$ WITH RESPECT TO BRACKET MULTIPLICATION IS OF THE FORM $\delta_{A}$ FOR SOME $A$ IN $M_{n}(\mathbf{R})$.

Hans Zassenhaus (1912-1991)


Hans Julius Zassenhaus was a German mathematician, known for work in many parts of abstract algebra, and as a pioneer of computer algebra.

## Gerhard Hochschild (1915-2010)



# THE CIRCLE PRODUCT ON THE SET OF MATRICES 

THE CIRCLE PRODUCT ON THE SET $M_{n}(\mathbf{R})$ OF MATRICES IS DEFINED BY

$$
X \circ Y=(X \times Y+Y \times X) / 2
$$

THE SET $M_{n}(\mathbf{R})$ of $n$ by $n$ MATRICES IS AN ALGEBRA UNDER MATRIX ADDITION AND CIRCLE MULTIPLICATION, WHICH IS COMMUTATIVE BUT NOT ASSOCIATIVE.

## DEFINITION 4

A DERIVATION ON $M_{n}(\mathbf{R})$ WITH RESPECT TO CIRCLE MULTIPLICATION

IS A LINEAR PROCESS $\delta$ WHICH SATISFIES THE LEIBNIZ RULE

$$
\delta(A \circ B)=\delta(A) \circ B+A \circ \delta(B)
$$

PROPOSITION 4 FIX A MATRIX $A$ in $M_{n}(\mathbf{R})$ AND DEFINE

$$
\delta_{A}(X)=A \times X-X \times A .
$$

THEN $\delta_{A}$ IS A DERIVATION WITH RESPECT TO CIRCLE MULTIPLICATION

THEOREM 4
(1972-Sinclair)
EVERY DERIVATION ON $M_{n}(\mathbf{R})$ WITH
RESPECT TO CIRCLE MULTIPLICATION
IS OF THE FORM $\delta_{A}$ FOR SOME $A$ IN $M_{n}(\mathbf{R})$.

REMARK
(1937-Jacobson)
THE ABOVE PROPOSITION AND
THEOREM NEED TO BE MODIFIED FOR
THE SUBALGEBRA (WITH RESPECT TO
CIRCLE MULTIPLICATION) OF SYMMETRIC MATRICES.

## Alan M. Sinclair (retired)



Nathan Jacobson (1910-1999)


Nathan Jacobson was an American mathematician who was recognized as one of the leading algebraists of his generation, and he was also famous for writing more than a dozen standard monographs.



# IT IS TIME FOR A SUMMARY OF THE PRECEDING 

## Table 1

| $M_{n}(\mathbf{R})$ (ALGEBRAS) |  |  |
| :---: | :---: | :---: |
| matrix | bracket | circle |
| $a b=a \times b$ | $[a, b]=a b-b a$ | $a \circ b=a b+b a$ |
| Th. 2 | Th.3 | Th.4 |
| $\delta_{a}(x)$ | $\delta_{a}(x)$ | $\delta_{a}(x)$ |
| $=$ | $=$ | $=$ |
| $a x-x a$ | $a x-x a$ | $a x-x a$ |

## AXIOMATIC APPROACH

AN ALGEBRA IS DEFINED TO BE A SET (ACTUALLY A VECTOR SPACE) WITH TWO BINARY OPERATIONS, CALLED ADDITION AND MULTIPLICATION

## ADDITION IS DENOTED BY

 $a+b$AND IS REQUIRED TO BE COMMUTATIVE AND ASSOCIATIVE $a+b=b+a, \quad(a+b)+c=a+(b+c)$

## MULTIPLICATION IS DENOTED BY $a b$

AND IS REQUIRED TO BE DISTRIBUTIVE WITH RESPECT TO ADDITION

$$
(a+b) c=a c+b c, \quad a(b+c)=a b+a c
$$

# AN ALGEBRA IS SAID TO BE ASSOCIATIVE (RESP. COMMUTATIVE) IF THE MULTIPLICATION IS ASSOCIATIVE (RESP. COMMUTATIVE) 

(RECALL THAT ADDITION IS ALWAYS COMMUTATIVE AND ASSOCIATIVE)

## THE ALGEBRAS $\mathcal{C}, \mathcal{D}$ AND $M_{n}(\mathbf{R})$ ARE EXAMPLES OF ASSOCIATIVE ALGEBRAS.

$\mathcal{C}$ AND $\mathcal{D}$ ARE COMMUTATIVE, AND $M_{n}(\mathrm{R})$ IS NOT COMMUTATIVE.

IN THIS TALK, I AM MOSTLY
INTERESED IN ALGEBRAS (PART I) AND TRIPLE SYSTEMS (PART II) WHICH ARE NOT ASSOCIATIVE, ALTHOUGH THEY MAY OR MAY NOT BE COMMUTATIVE.
(ASSOCIATIVE AND COMMUTATIVE HAVE TO BE INTERPRETED
APPROPRIATELY FOR THE TRIPLE
SYSTEMS CONSIDERED WHICH ARE NOT ACTUALLY ALGEBRAS)

## LET'S START AT THE BEGINNING

## THE AXIOM WHICH CHARACTERIZES ASSOCIATIVE ALGEBRAS IS <br> $$
a(b c)=(a b) c
$$

THESE ARE CALLED ASSOCIATIVE ALGEBRAS

## THE AXIOM WHICH CHARACTERIZES COMMUTATIVE ALGEBRAS IS <br> $$
a b=b a
$$

## THESE ARE CALLED (you guessed it) COMMUTATIVE ALGEBRAS

HOWEVER, THESE TWO CONCEPTS ARE TOO GENERAL TO BE OF ANY USE BY THEMSELVES

## THE AXIOMS WHICH CHARACTERIZE

 BRACKET MULTIPLICATION ARE$$
a^{2}=0
$$

$(a b) c+(b c) a+(c a) b=0$
THESE ARE CALLED
LIE ALGEBRAS


## Sophus Lie (1842-1899)



Marius Sophus Lie was a Norwegian mathematician. He largely created the theory of continuous symmetry, and applied it to the study of geometry and differential equations.

## THE AXIOMS WHICH CHARACTERIZE CIRCLE MULTIPLICATION ARE <br> $$
a b=b a
$$ <br> $$
a\left(a^{2} b\right)=a^{2}(a b)
$$

THESE ARE CALLED
JORDAN ALGEBRAS


## Pascual Jordan (1902-1980)



Pascual Jordan was a German theoretical and mathematical physicist who made significant contributions to quantum mechanics and quantum field theory.

# LET'S SUMMARIZE AGAIN 

Table 2
ALGEBRAS
commutative algebras

$$
a b=b a
$$

associative algebras
$a(b c)=(a b) c$
Lie algebras
$a^{2}=0$
$(a b) c+(b c) a+(c a) b=0$
Jordan algebras

$$
\begin{aligned}
a b & =b a \\
a\left(a^{2} b\right) & =a^{2}(a b)
\end{aligned}
$$

## DERIVATIONS ON $C^{*}$-ALGEBRAS

> THE ALGEBRA $M_{n}(\mathrm{R})$, WITH MATRIX MULTIPLICATION, AS WELL AS THE ALGEBRA $\mathcal{C}$, WITH ORDINARY
> MULTIPLICATION, ARE EXAMPLES OF $C^{*}$-ALGEBRAS.

THE FOLLOWING THEOREM THUS EXPLAINS THEOREM 1.

THEOREM 5 (1966-Sakai, Kadison) EVERY DERIVATION OF A $C^{*}$-ALGEBRA IS OF THE FORM $x \mapsto a x-x a$ FOR SOME $a$ IN THE $C^{*}$-ALGEBRA

KEY POINT: C*-ALGEBRAS CAN BE INFINITE DIMENSIONAL!

Richard Kadison (b. 1925)


Richard V. Kadison is an American mathematician known for his contributions to the study of operator algebras.

## John von Neumann (1903-1957)



John von Neumann was a Hungarian American mathematician who made major contributions to a vast range of fields, including set theory, functional analysis, quantum mechanics, ergodic theory, continuous geometry, economics and game theory, computer science, numerical analysis, hydrodynamics, and statistics, as well as many other mathematical fields. He is generally regarded as one of the greatest mathematicians in modern history

# AUTOMATIC CONTINUITY REVISITED 

## THEOREM 6 (SAKAI 1960)

# EVERY DERIVATION OF A C*-ALGEBRA 

 IS CONTINUOUSDERIVATIONS INTO A MODULE: COHOMOLOGY THEORY

THEOREM 7<br>(RINGROSE 1972)

EVERY DERIVATION OF A C*-ALGEBRA
INTO A MODULE IS CONTINUOUS

WHAT IS A MODULE ANYWAY? WHAT IS COHOMOLOGY?

## John Ringrose (b. 1932)



John Ringrose is a leading world expert on non-self-adjoint operators and operator algebras. He has written a number of influential texts including Compact non-self-adjoint operators (1971) and, with R V Kadison, Fundamentals of the theory of operator algebras in four volumes published in 1983, 1986, 1991 and 1992.

## TOPICS FOR FUTURE COLLOQUIA

1. PROOFS OF THEOREMS 2-4
2. REPRESENTATION THEORY (MODULES AND COHOMOLOGY) FOR ALGEBRAS
3. GEOMETRY OF LIE AND JORDAN STRUCTURES

GRADUS AD PARNASSUM PART I-ALGEBRAS

HOMEWORK IN PREPARATION FOR THE PROOFS OF THEOREMS 2-4
(SEE THE NEXT PAGE)

# GRADUS AD PARNASSUM PART I-ALGEBRAS 

## HOMEWORK IN PREPARATION FOR THE

 PROOFS OF THEOREMS 2-41. Prove Proposition 2
2. Prove Proposition 3
3. Prove Proposition 4
4. Let $A, B$ are two fixed matrices in $M_{n}(\mathbf{R})$. Show that the linear process

$$
\delta_{A, B}(X)=A \circ(B \circ X)-B \circ(A \circ X)
$$

is a derivation of $M_{n}(\mathbf{R})$ with respect to circle multiplication.
(cf. Remark following Theorem 4)
5. Show that $M_{n}(\mathbf{R})$ is a Lie algebra with respect to bracket multiplication. In other words, show that the two axioms for Lie algebras in Table 2 are satisfied if $a b$ denotes $[a, b]=a b-b a$ ( $a$ and $b$ denote matrices and $a b$ denotes matrix multiplication)
6. Show that $M_{n}(\mathbf{R})$ is a Jordan algebra with respect to circle multiplication. In other words, show that the two axioms for Jordan algebras in Table 2 are satisfied if $a b$ denotes $a \circ b=a b+b a$ ( $a$ and $b$ denote matrices and $a b$ denotes matrix multiplicationforget about dividing by 2)
7. (Extra credit)

Let us write $\delta_{a, b}$ for the linear process $\delta_{a, b}(x)=$ $a(b x)-b(a x)$ in a Jordan algebra. Show that $\delta_{a, b}$ is a derivation of the Jordan algebra by following the outline below. (cf. Homework problem 4 above.)
(a) In the Jordan algebra axiom

$$
u\left(u^{2} v\right)=u^{2}(u v)
$$

replace $u$ by $u+w$ to obtain the two equations

$$
2 u((u w) v)+w\left(u^{2} v\right)=2(u w)(u v)+u^{2}(w v)
$$

(1)
and

$$
u\left(w^{2} v\right)+2 w((u w) v)=w^{2}(u v)+2(u w)(u v) .
$$

(Hint: Consider the "degree" of $w$ on each side of the equation resulting from the substitution)
(b) In (1), interchange $v$ and $w$ and subtract the resulting equation from (1) to obtain the equation

$$
\begin{equation*}
2 u\left(\delta_{v, w}(u)\right)=\delta_{v, w}\left(u^{2}\right) . \tag{2}
\end{equation*}
$$

(c) In (2), replace $u$ by $x+y$ to obtain the equation

$$
\delta_{v, w}(x y)=y \delta_{v, w}(x)+x \delta_{v, w}(y),
$$

which is the desired result.

## END OF PART I

