

Harnessing the Power of Calculus

Half derivatives and Image Processing

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Undergraduate Math Seminar Feb 2 2023



Run Experiment 1



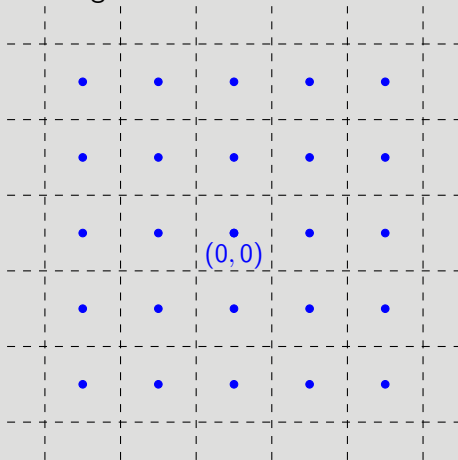
Derivation of ...

Consider an infinite grid



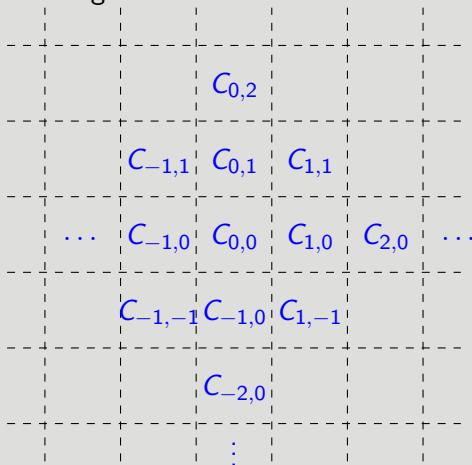
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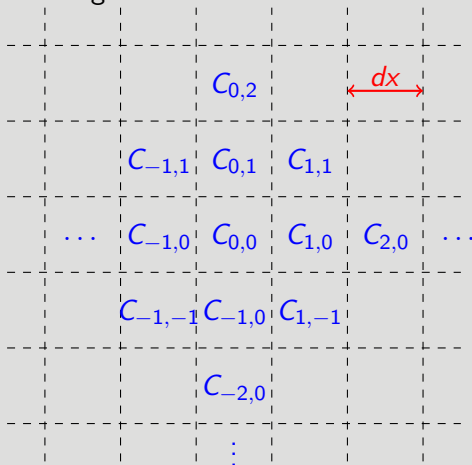
Derivation of ...

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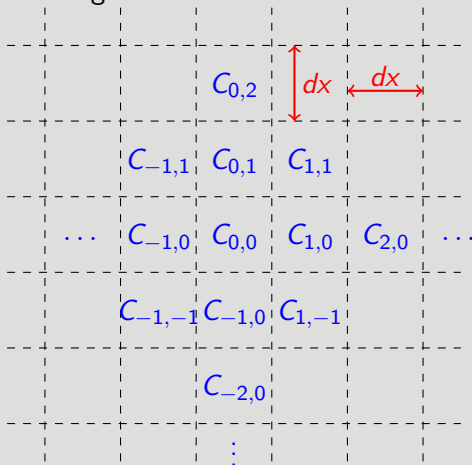
Derivation of ...

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Derivation of ...

Consider an infinite grid



Derivation (continued)

Consider the following process:



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point $(j, k)dx$



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point $(j, k)dx$
at time $n dt$



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point $(j, k)dx$
at time $n dt$ (step $n \in \mathbb{N}$)



Derivation (continued)

Consider the following process:

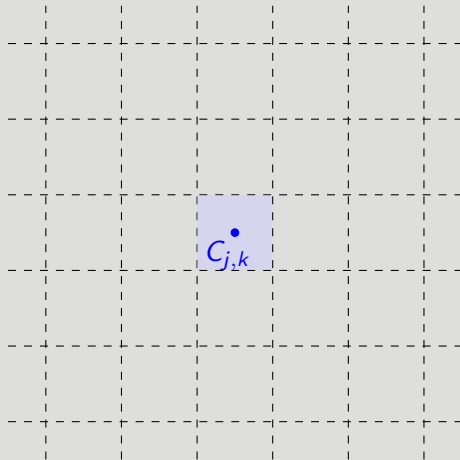
A particle found in cell $C_{j,k}$
centered at the point $(j, k)dx$
at time $n dt$ (step $n \in \mathbb{N}$) for $dt > 0$



Derivation (continued)

with probability 1

step n



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point (jdx, kdx)
at time ndt (step n) for $n \in \mathbb{N}$ and $dt > 0$,
in step $n + 1$ will move one cell



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point (jdx, kdx)
at time ndt (step n) for $n \in \mathbb{N}$ and $dt > 0$,
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up or down



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point (jdx, kdx)
at time ndt (step n) for $n \in \mathbb{N}$ and $dt > 0$,
in step $n + 1$ will move one cell
up or down, left or right



Derivation (continued)

Consider the following process:

A particle found in cell $C_{j,k}$
centered at the point (jdx, kdx)
at time ndt (step n) for $n \in \mathbb{N}$ and $dt > 0$,
in step $n + 1$ will move one cell
up or down, left or right
with probability $1/4$ each



Derivation (continued)

with probability $1/4$

step $n + 1$



Derivation (continued)

with probability $1/4$

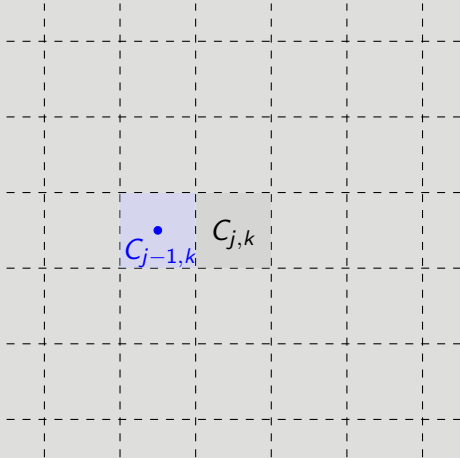
step $n + 1$



Derivation (continued)

with probability $1/4$

step $n + 1$



Derivation (continued)

with probability $1/4$

step $n + 1$



Derivation (continued)

Let now $p_{j,k}^n$ be probability density



Derivation (continued)

Let now $p_{j,k}^n$ be probability density to find the particle in $C_{j,k}$



Derivation (continued)

Let now $p_{j,k}^n$ be probability density to find the particle in $C_{j,k}$ at step n ,



Derivation (continued)

Let now $p_{j,k}^n$ be probability density to find the particle in $C_{j,k}$ at step n , that is

$$P(X^n \in C_{j,k}) = p_{j,k}^n dx^2,$$



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where X^n is the particle's position at step n .



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$$P(X^{n+1} \in C_{j,k}) = \sum_{\tilde{j}, \tilde{k}} P(X^{n+1} \in C_{j,k} | X^n \in C_{\tilde{j}, \tilde{k}}) P(X^n \in C_{\tilde{j}, \tilde{k}})$$



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which amounts to

$$p_{j,k}^{n+1} = \frac{1}{4} [p_{j-1,k}^n + p_{j+1,k}^n + p_{j,k-1}^n + p_{j,k+1}^n]$$



Derivation (continued)

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which amounts to

$$p_{j,k}^{n+1} - p_{j,k}^n = \frac{1}{4} [p_{j-1,k}^n + p_{j+1,k}^n + p_{j,k-1}^n + p_{j,k+1}^n - 4p_{j,k}^n]$$



Derivation (continued)

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which amounts to

$$\frac{p_{j,k}^{n+1} - p_{j,k}^n}{dt} = \frac{1}{4dt} \frac{p_{j-1,k}^n + p_{j+1,k}^n + p_{j,k-1}^n + p_{j,k+1}^n - 4p_{j,k}^n}{1}$$



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which amounts to

$$\frac{p_{j,k}^{n+1} - p_{j,k}^n}{dt} = \frac{dx^2}{4dt} \frac{p_{j-1,k}^n + p_{j+1,k}^n + p_{j,k-1}^n + p_{j,k+1}^n - 4p_{j,k}^n}{dx^2}$$



Derivation of the Heat Equation

Notice that

$$\begin{aligned}\frac{p_{j,k}^{n+1} - p_{j,k}^n}{dt} &\simeq \frac{p(\textcolor{green}{n}dt + \textcolor{red}{dt}, jdx, kdx) - p(\textcolor{green}{n}dt, jdx, kdx)}{\textcolor{red}{dt}} \\ &= \frac{p(\textcolor{green}{t} + \textcolor{red}{dt}, x_1, x_2) - p(\textcolor{green}{t}, x_1, x_2)}{\textcolor{red}{dt}} \\ &\quad \text{for } \textcolor{green}{n}dt = \textcolor{green}{t} \text{ and } (jdx, kdx) = (x_1, x_2) = x \\ &\simeq \frac{d}{\textcolor{red}{dt}} p(t, x) = p_{\textcolor{red}{t}}(t, x)\end{aligned}$$



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Similarly

$$\begin{aligned}\frac{p_{j-1,k}^n - 2p_{j,k}^n + p_{j+1,k}^n}{dx^2} &\simeq \frac{p(t, x_1 - dx, x_2) - 2p(t, x_1, x_2) + p(t, x_1 + dx, x_2)}{dx^2} \\ &\simeq \frac{\partial^2}{\partial x_1^2} p(t, x) = p_{x_1 x_1}(t, x)\end{aligned}$$



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Similarly

$$\begin{aligned}\frac{p_{j,k-1}^n - 2p_{j,k}^n + p_{j,k+1}^n}{dx^2} &\simeq \frac{p(t, x_1, x_2 - dx) - 2p(t, x_1, x_2) + p(t, x_1, x_2 + dx)}{dx^2} \\ &\simeq \frac{\partial^2}{\partial x_2^2} p(t, x) = p_{x_2 x_2}(t, x)\end{aligned}$$



Derivation of the Heat Equation

Letting $dx, dt \rightarrow 0$



Derivation of the Heat Equation

Letting $dx, dt \rightarrow 0$ in such a way as to keep $\frac{dx^2}{4dt} = d = \text{constant}$



Derivation of the Heat Equation

Letting $dx, dt \rightarrow 0$ in such a way as to keep $\frac{dx^2}{4dt} = d = \text{constant}$, we obtain that

$$p_t = d(p_{x_1x_1} + p_{x_2x_2}) = d\Delta p$$



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$$p_{j,k}^0 = \begin{cases} \frac{1}{dx^2}, & (j, k) = (0, 0) \\ 0, & (j, k) \neq (0, 0) \end{cases}$$



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and obtain an **initial value problem** for p



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and obtain an initial value problem for p , which is solved by

$$p(t, x) = \frac{1}{4\pi t} e^{-\frac{|x|^2}{4t}}, \quad t > 0, \quad x \in \mathbb{R}^2.$$



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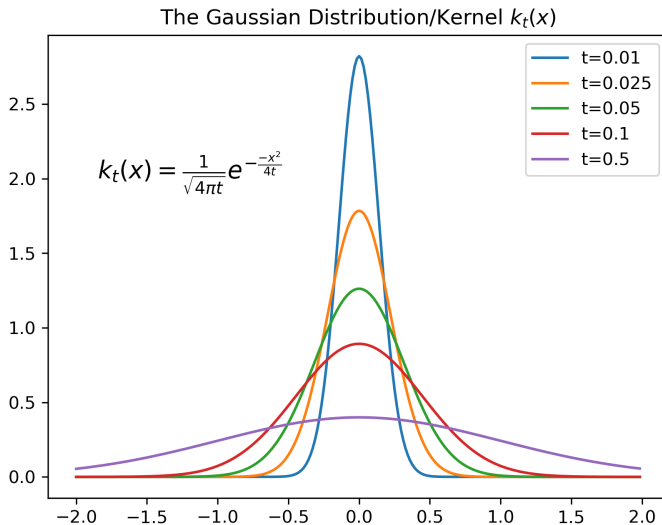
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The solution p yields e.g.

$$P(X^t \in A) = \int_A p(t, x) dx.$$



The Heat Kernel



Simple Functions:



Functions

Simple Functions:

$$f(x) = 1$$



Functions

Simple Functions:

$$f(x) = 1, \cos(x)$$



Functions

Simple Functions:

$$f(x) = 1, \cos(x), \sin(x)$$



Functions

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$$f(x) = 1, \cos(x), \sin(x), \cos(2x)$$



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Simple Functions:

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Slightly more complex:



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$$f(x) = 1, \cos(x), \sin(x), \cos(2x), \dots, \cos(nx), \sin(nx)$$

Slightly more complex:

$$f(x) = 3 \cos(2x) - \sin(5x), \dots$$



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Arbitrary function:

$$f(x) = \alpha_0 + \alpha_1 \cos(x) + \beta_1 \sin(x) + \alpha_2 \cos(2x) + \dots$$



Functions

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Arbitrary function:

$$\begin{aligned} f(x) &= \alpha_0 + \alpha_1 \cos(x) + \beta_1 \sin(x) + \alpha_2 \cos(2x) + \dots \\ &= \alpha_0 + \sum_{k=1}^{\infty} \left[\alpha_k \cos(kx) + \beta_k \sin(kx) \right] \end{aligned}$$



Functions

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Functions

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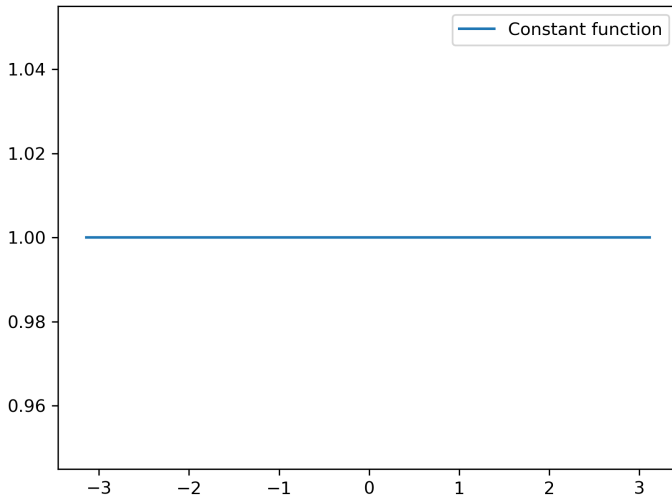
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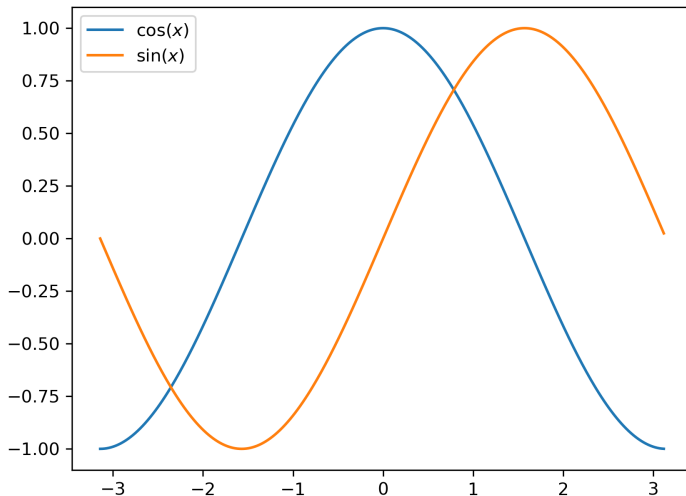
for the simple functions $\varphi_k = e^{ik \cdot}$.



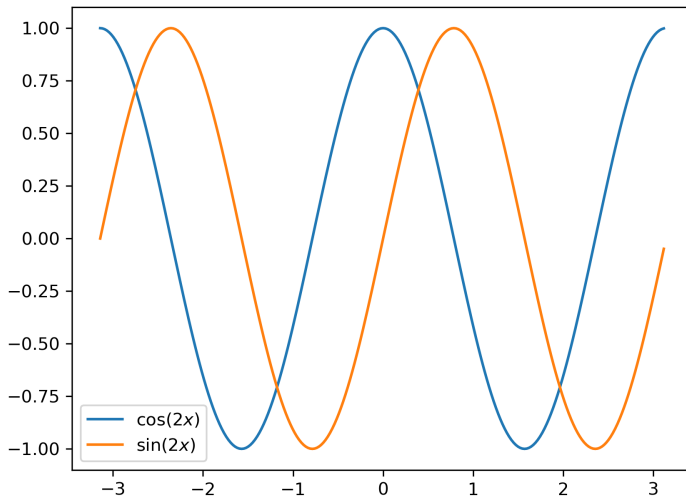
Example of Functions/Expansions



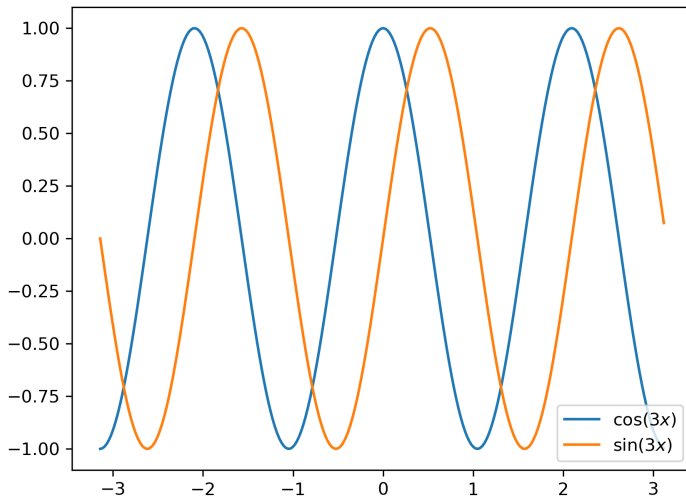
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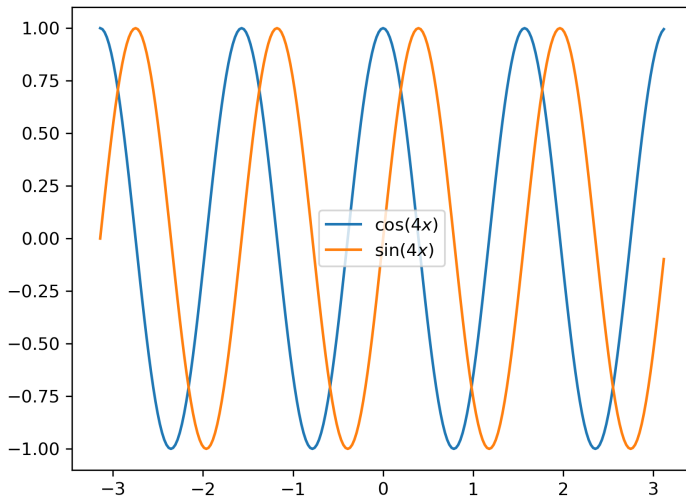
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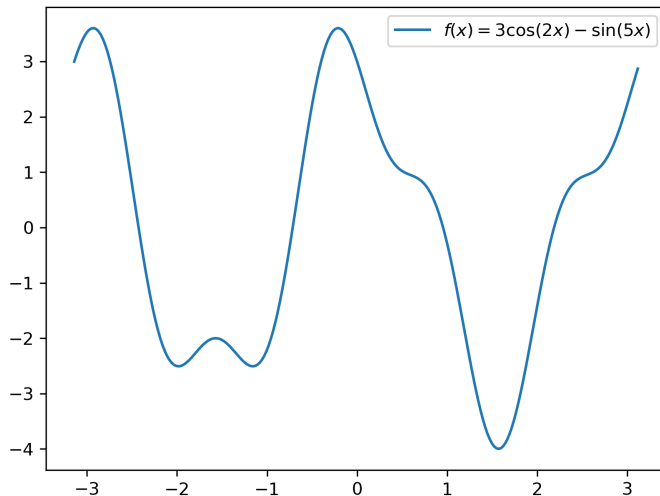
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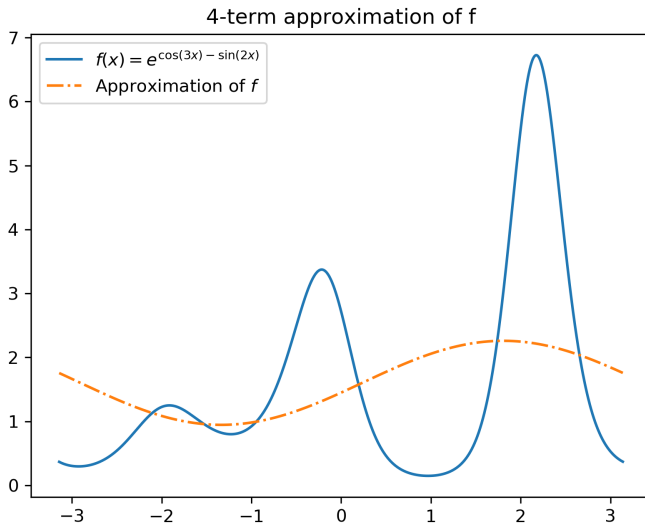
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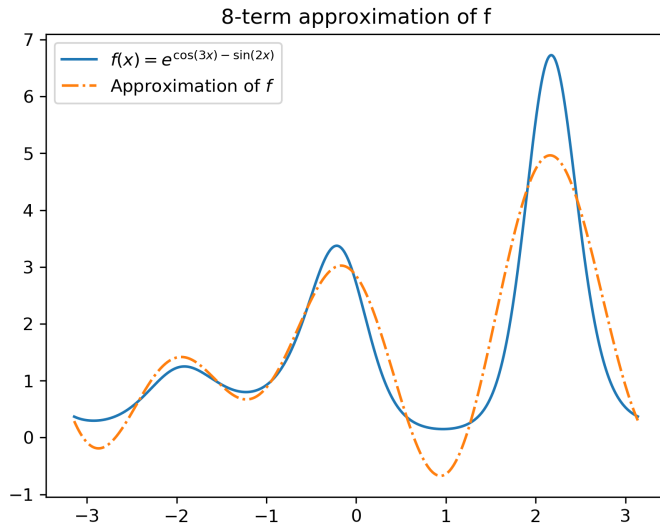
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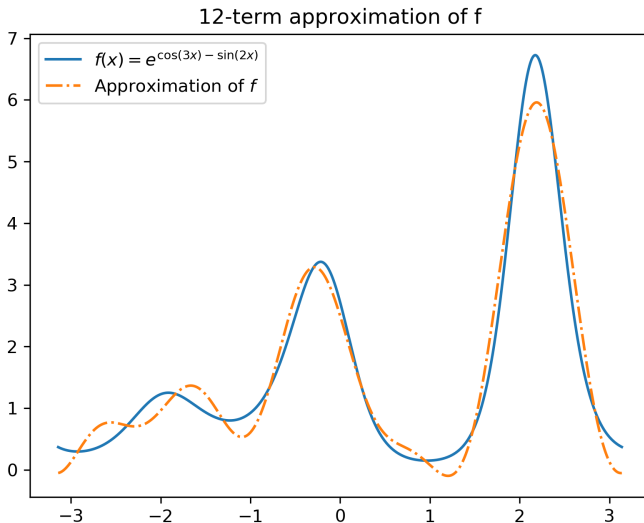
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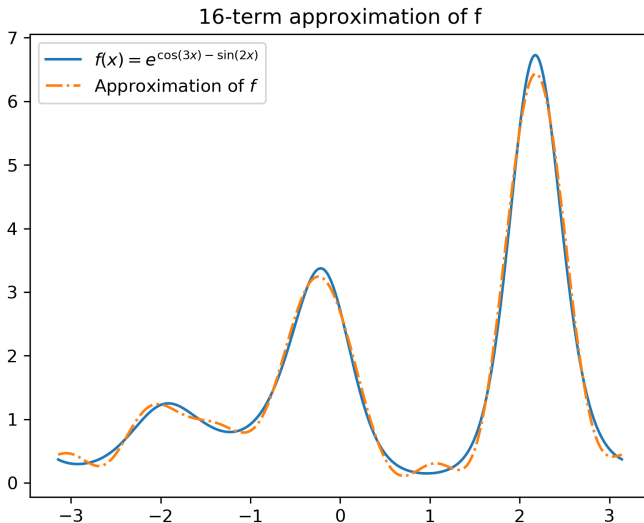
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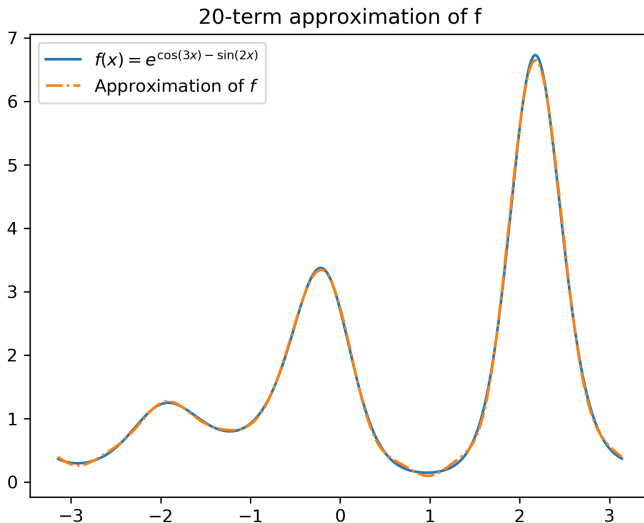
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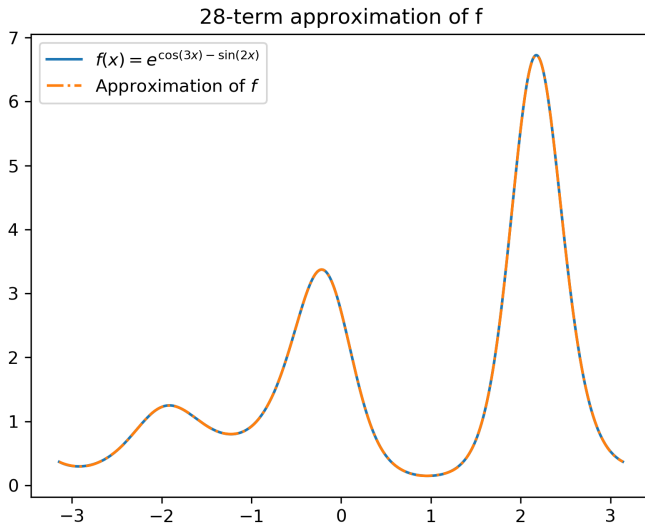
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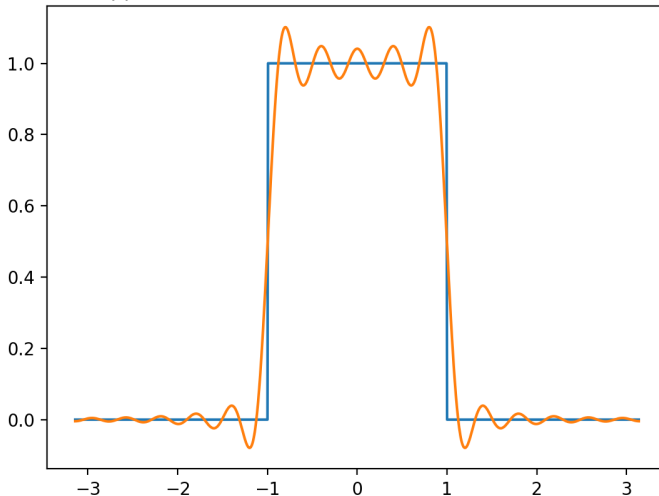


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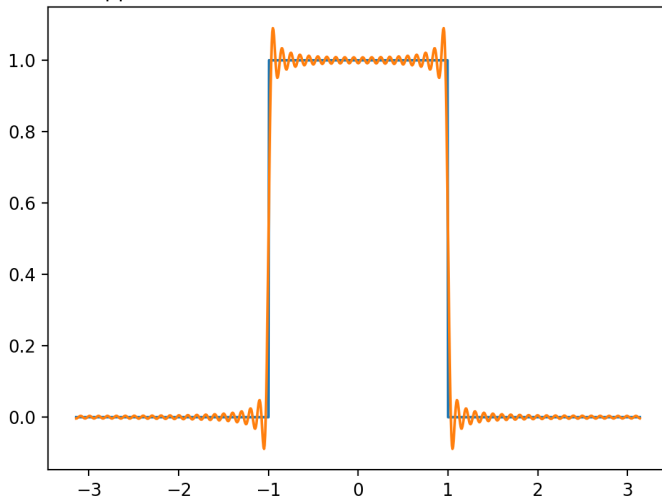
Example of Functions/Expansions

Series approximation of a characteristic function with 32 terms



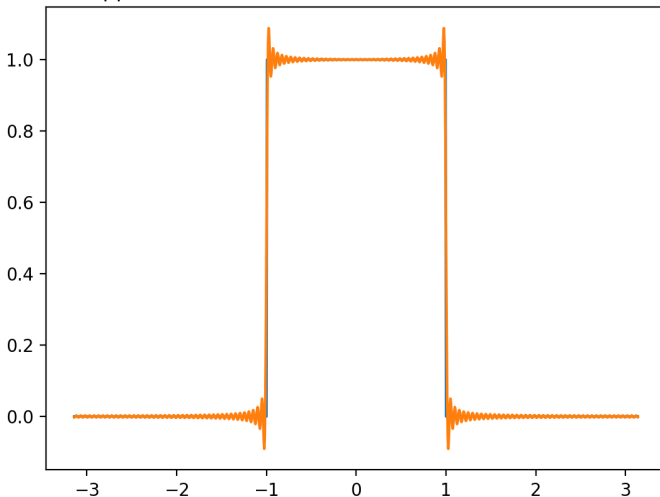
Example of Functions/Expansions

Series approximation of a characteristic function with 128 terms



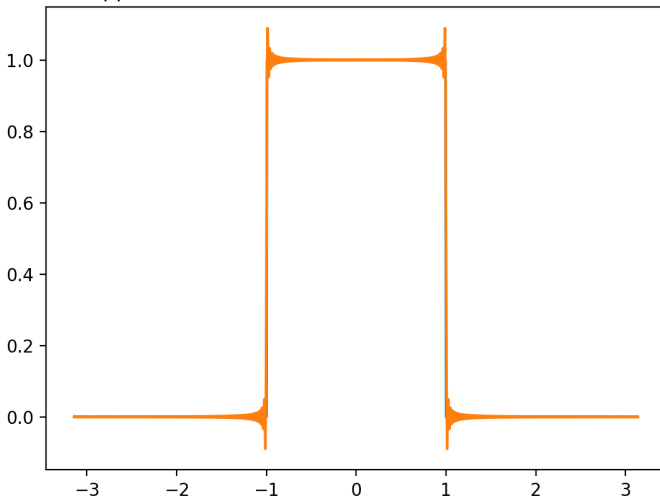
Example of Functions/Expansions

Series approximation of a characteristic function with 256 terms



Example of Functions/Expansions

Series approximation of a characteristic function with 512 terms



Conclusion

Even “wildly behaved” functions can be *understood*



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Even “wildly behaved” functions can be *understood* (read approximated)



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Intuition

Vector space

Scalar product

Orthonormal basis

Basis expansion

Coefficients



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Vector space $V = \mathbb{R}^n \ni x, y$

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For simple functions



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Back to Diffusion

Consider again the **diffusion equation**



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The Effect of Linear Diffusion

Click for video



What is noise?



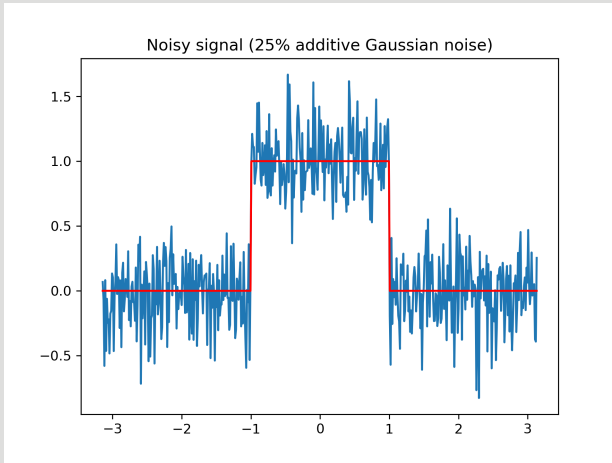
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It is a **perturbation** (of a signal) which introduces **random errors** of a certain size with a certain probability



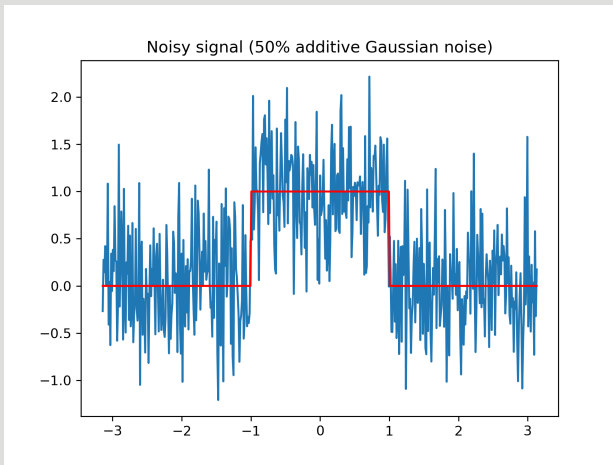
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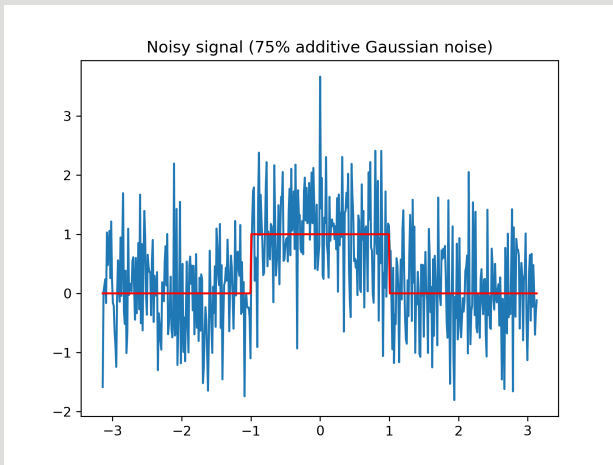
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To some extent, yes, but the signal is at least partly damaged



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To some extent, yes, but the signal is at least partly damaged due to the strong smoothing/averaging property of the diffusion equation.



The Effect of Linear Diffusion

[Click for video](#)



Back to the drawing board

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What do we really want?



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Diffusion where the signal is constant/smooth.



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This is the so-called **Perona-Malik** model introduced in 1990.



The Effect of Perona-Malik

Click for video



Fractional Derivatives

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Can we do even better by using a model that is somehow **between**



Fractional Derivatives

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Fractional Derivative Model

Finally we arrive at a noise reduction model with the desired properties.

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where $\varepsilon \in (0, 1)$ is chosen small but not too much. This model was introduced by **G & Lambers** in 2009.

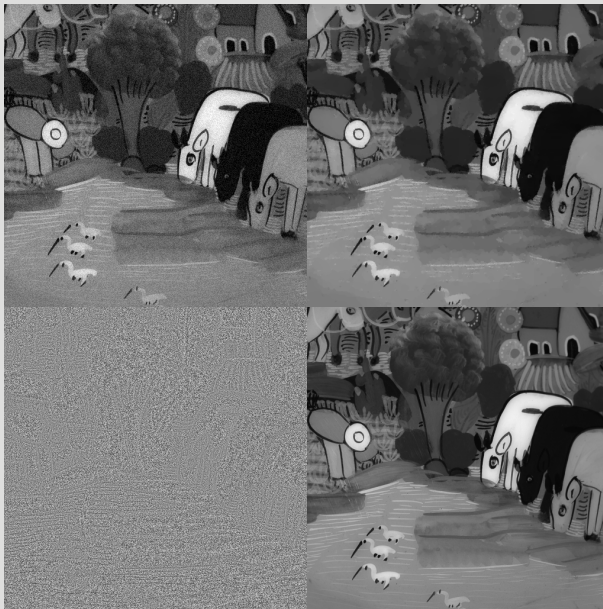


The Effect of Fractional Diffusion

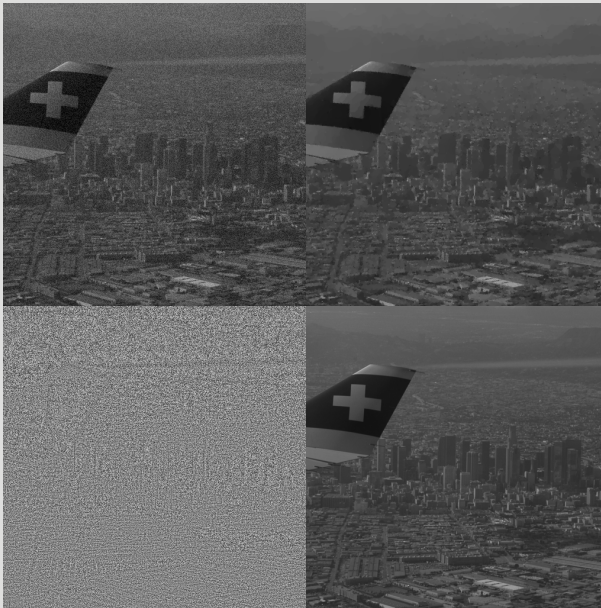
Click for video



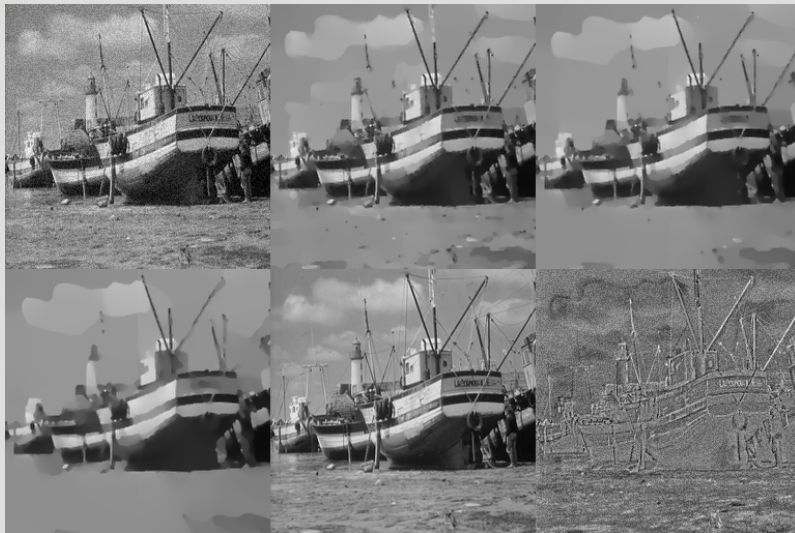
Experiments with Real Images



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Do you have any questions?



The End

Thank you for your attention!



Thank you for your attention!

www.math.uci.edu/~gpatrick/

Do not hesitate to contact me at

gpatrick@math.uci.edu

