

STRICT 2-CONVEXITY OF CONVEX SOLUTIONS TO THE QUADRATIC HESSIAN EQUATION

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ABSTRACT. We prove that convex viscosity solutions to the quadratic Hessian inequality

$$\sigma_2(D^2u) \geq 1$$

are strictly 2-convex. As a consequence we obtain short proofs of smoothness and interior C^2 estimates for convex viscosity solutions to $\sigma_2(D^2u) = 1$, which were proven using different methods in recent works of Guan-Qiu [GQ], McGonagle-Song-Yuan [MSY] and Shankar-Yuan [SY2].

1. INTRODUCTION

In this note we consider convex viscosity solutions to the quadratic Hessian inequality

$$(1) \quad \sigma_2(D^2u) \geq 1.$$

Our main result is their strict two-convexity. That is:

Theorem 1.1. *Let u be a convex viscosity solution to (1) in $\Omega \subset \mathbb{R}^n$, and let L be a supporting linear function to u in Ω . Then*

$$\dim\{u = L\} \leq n - 2.$$

Theorem 1.1 is sharp in view of the example $u = x_1^2 + x_2^2$, with $L = 0$.

Local smoothness of convex viscosity solutions to

$$(2) \quad \sigma_2(D^2u) = 1$$

follows from Theorem 1.1, using the classical solvability of the Dirichlet problem [CNS] and the Pogorelov-type interior C^2 estimate from [CW] (see Section 2). With a compactness argument we can in fact prove a universal modulus of strict 2-convexity (see Proposition 4.1). As a result we obtain:

Theorem 1.2. *Let u be a convex viscosity solution of (2) in $B_1 \subset \mathbb{R}^n$. Then u is smooth, and*

$$(3) \quad |D^2u(0)| \leq C(n, \|u\|_{L^\infty(B_1)}).$$

Inequality (3) was recently proven for smooth convex solutions of (2) in [GQ] and [MSY], and Theorem 1.2 was proven in [SY2]. A subtle issue in passing to the viscosity case is that smooth approximations of convex viscosity solutions may not be convex. An advantage of our approach is that it avoids using a priori estimates for smooth convex solutions, which allows us to bypass this issue. The methods in the above-mentioned works are quite different from ours, based in [GQ] on the

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Bernstein technique, and in [MSY] and [SY2] on the properties of the equation for the Legendre-Lewy transform of u .

An interesting question is whether the conclusion of Theorem 1.2 holds without assuming that u is convex. It is true when $n = 2$ (in which case solutions are automatically convex and (2) is the Monge-Ampère equation, [H]) and when $n = 3$ (in which case (2) is equivalent to the special Lagrangian equation, [WY]). It is also known to be true if u is slightly non-convex [SY2]. Finally, an interior C^2 estimate of the form (3) was recently obtained in [SY1] for smooth solutions to (2) that satisfy the semi-convexity condition $D^2u \geq -KI$, with C depending also on K . The general case in dimension $n \geq 4$ remains open.

Remark 1.3. Local smoothness and interior C^2 estimates are false for convex viscosity solutions to the k -Hessian equation

$$\sigma_k(D^2u) = 1$$

when $k \geq 3$, in view of the well-known Pogorelov example ([P], [U]). The same example shows that convex viscosity solutions to $\sigma_k(D^2u) \geq 1$ are not always strictly k -convex when $k \geq 3$. In particular, Theorems 1.1 and 1.2 are both special to the quadratic Hessian equation.

The paper is organized as follows. In Section 2 we recall a few classical results about the k -Hessian equation, and we use them to show that Theorem 1.1 implies that convex viscosity solutions of (2) are smooth. In Section 3 we prove Theorem 1.1. Finally, in Section 4 we prove a quantitative version of Theorem 1.1 using a compactness argument, and we use it to complete the proof of Theorem 1.2.

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2. PRELIMINARIES

In this section we recall a few classical facts about the k -Hessian equation. Below Ω denotes a bounded domain in \mathbb{R}^n , and $1 \leq k \leq n$.

We first recall some facts about the σ_k operator. The function σ_k on $Sym_{n \times n}$ denotes the k^{th} symmetric polynomial of the eigenvalues. It is elliptic on the cone

$$\Gamma_k := \{M \in Sym_{n \times n} : \sigma_l(M) > 0 \text{ for each } 1 \leq l \leq k\},$$

and has convex level sets in Γ_k . Furthermore, the function σ_k is uniformly elliptic on compact subsets of Γ_k .

Next we recall the notion of viscosity solution. We say that a function $u \in C^2(\Omega)$ is k -convex if $D^2u \in \overline{\Gamma}_k$. Given a nonnegative function $f \in C(\Omega)$, we say that a function $u \in C(\Omega)$ is a viscosity solution of

$$\sigma_k(D^2u) \geq (\leq) f$$

if, whenever a k -convex function $\varphi \in C^2(\Omega)$ touches u from above (below) at a point $x_0 \in \Omega$, we have

$$\sigma_k(D^2\varphi(x_0)) \geq (\leq) f(x_0).$$

We say that $u \in C(\Omega)$ is a viscosity solution of

$$\sigma_k(D^2u) = f$$

if it is a viscosity solution of both $\sigma_k(D^2u) \geq f$ and $\sigma_k(D^2u) \leq f$. Viscosity solutions are closed under uniform convergence, and the notions of classical and viscosity solution coincide on C^2 functions that are k -convex.

Third we recall the classical solvability of the Dirichlet problem for the k -Hessian equation, proven in [CNS]:

Theorem 2.1. *Let $g \in C^\infty(\partial B_R)$. Then there exists a unique k -convex solution $u \in C^\infty(\overline{B_R})$ to the Dirichlet problem*

$$\sigma_k(D^2u) = 1 \text{ in } B_R, \quad u|_{\partial B_R} = g.$$

The result in fact holds for smooth bounded $k-1$ -convex domains.

Finally we recall the Pogorelov-type estimate Theorem 4.1 from [CW]:

Theorem 2.2. *Assume that $u \in C^\infty(\overline{\Omega})$ is a k -convex solution to*

$$\sigma_k(D^2u) = 1 \text{ in } \Omega,$$

and that there exists a k -convex function $w \in C(\overline{\Omega})$ such that $u < w$ in Ω and $u = w$ on $\partial\Omega$. Then

$$(4) \quad \sup_{\Omega} ((w-u)^4 |D^2u|) \leq C(n, k, \|u\|_{C^1(\Omega)}).$$

Inequality (4) implies in particular that the equation for u is uniformly elliptic on compact subdomains of Ω . By the Evans-Krylov theorem (see [CC]), interior derivative estimates of all higher orders follow.

To conclude the section we show local smoothness of convex viscosity solutions to (2). We assume u is defined in $B_1 \subset \mathbb{R}^n$, and it suffices to prove smoothness in a neighborhood of the origin. After subtracting a supporting linear function we may assume that $u(0) = 0$ and that $u \geq 0$. By Theorem 1.1 we have after a rotation that $\{u = 0\}$ is contained in the subspace spanned by $\{e_3, \dots, e_n\}$. Let

$$w_\delta(x) := \delta[2(n-2)(x_1^2 + x_2^2) - (x_3^2 + \dots + x_n^2)],$$

and notice that w_δ is 2-convex for all $\delta > 0$. Furthermore, we can choose $\delta, \eta, \mu > 0$ small (depending on u) such that

$$u > w_\delta + \eta \text{ on } \partial B_{1/2} \quad \text{and} \quad \overline{B_\mu} \subset \{u < w_\delta + \eta\}.$$

Let $\{v_j\}$ be a sequence of smooth 2-convex (but not necessarily convex) solutions to (2) that converge uniformly to u in $B_{1/2}$. (One obtains the functions v_j e.g. by taking smooth approximations to u on $\partial B_{1/2}$ and applying Theorem 2.1 with $R = 1/2$ and $k = 2$.) Applying Theorem 2.2 to v_j with $w = w_\delta + \eta$ and $k = 2$, we see that the solutions v_j enjoy uniform derivative estimates of all orders in B_μ as $j \rightarrow \infty$. We conclude that u is smooth in B_μ .

3. PROOF OF THEOREM 1.1

In this section we prove Theorem 1.1.

Proof of Theorem 1.1: Assume by way of contradiction that there exists a supporting linear function L to u such that $\dim\{u = L\} \geq n-1$. After subtracting L , translating, rotating, and quadratically rescaling, we may assume that u is defined in B_2 , that $u \geq 0$, and that $u = 0$ on $\{x_n = 0\} \cap B_2$. After subtracting another supporting linear function of the form ax_n with $a \geq 0$, we may also assume that

$$u(te_n) = o(t) \text{ as } t \rightarrow 0^+.$$

Letting $x = (x', x_n)$, it follows that $\{u < h\}$ contains a cylinder of the form

$$Q_h := \{|x'| < 1\} \times (0, H),$$

with $h/H \rightarrow 0$ as $h \rightarrow 0^+$. For h small, the convex paraboloid

$$P_h := h|x'|^2 + 4\frac{h}{H^2}(x_n - H/2)^2$$

thus satisfies that $P_h \geq h \geq u$ on ∂Q_h , that $P_h(He_n/2) = 0 \leq u$, and that

$$\sigma_2(D^2P_h) = c_1(n)h^2 + c_2(n)\frac{h^2}{H^2} < 1,$$

which contradicts (1). \square

4. PROOF OF THEOREM 1.2

In this section we prove a quantitative version of Theorem 1.1, and we use it to complete the proof of Theorem 1.2. For a set $S \subset \mathbb{R}^n$ and $r > 0$ we let S_r denote the r -neighborhood of S .

Proposition 4.1. *For $K > 0$, $r > 0$ and $n \geq 2$, there exists $\delta(n, K, r) > 0$ such that if u is a convex viscosity solution to (1) in $B_1 \subset \mathbb{R}^n$ with $\|u\|_{L^\infty(B_1)} \leq K$ and L is a supporting linear function to u at 0, then*

$$\{u < L + \delta\} \subset\subset T_r$$

for some $n - 2$ -dimensional subspace T of \mathbb{R}^n .

Proof. Assume not. Then there exist convex viscosity solutions u_j to (1) on B_1 with $\|u_j\|_{L^\infty(B_1)} \leq K$ and supporting linear functions L_j at 0 such that the conclusion fails with $\delta = 1/j$. Up to taking a subsequence, the functions u_j converge locally uniformly to a convex viscosity solution v of (1) in B_1 , and L_j converge to a supporting linear L to v at 0 such that $\{v = L\}$ is not compactly contained in T_r for any $n - 2$ -dimensional subspace T . This contradicts Theorem 1.1. \square

Proof of Theorem 1.2: We proved that u is smooth at the end of Section 2. The proof of the estimate (3) follows the same lines. We call a constant universal if it depends only on n and $\|u\|_{L^\infty(B_1)}$. We may assume after subtracting a supporting linear function with universal C^1 norm that $u(0) = 0$ and that $u \geq 0$. Write $x = (y, z)$ with $y \in \mathbb{R}^2$ and $z \in \mathbb{R}^{n-2}$. By Proposition 4.1 there exists $\delta > 0$ universal such that, after a rotation, $u > \delta$ on $\{|y| = 1/(2n)\} \cap B_1$. It follows that

$$u > w := \delta \left(2(n-2)|y|^2 - |z|^2 + \frac{1}{8} \right)$$

on the boundary of $B_{3/4} \cap \{|y| < 1/(2n)\}$. Notice also that w is 2-convex. The estimate (3) follows by applying Theorem 2.2 in the connected component of the set $\{u < w\}$ that contains the origin. \square

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