# **Summary**

**Joint Probability Distributions** If *X*, *Y* are random variables:

$$p(x,y) = \mathbb{P}(X = x, Y = y)$$
(joint mass function if X, Y discrete) $F(x,y) = \mathbb{P}(X \le x, Y \le y)$ (joint cumulative distribution function) $f(x,y) = \frac{\partial^2 F}{\partial x \partial y}$ (joint density, if X, Y continuous)

If  $A \subseteq \mathbb{R}^2$  then

$$\mathbb{P}((X,Y) \in A) = \begin{cases} \iint f(x,y) \, dx \, dy & \text{if } X, Y \text{ discrete} \\ \sum_{(x,y) \in A} p(x,y) & \text{if } X, Y \text{ continuous} \end{cases}$$

**Independence** *X*, *Y* independent  $\iff \exists g, h$  such that f(x, y) = g(x)h(y) on entirity of  $\mathbb{R}^2$ . In such a situation can choose  $g(x) = f_X(x)$  and  $h(y) = f_Y(y)$ . Corresponding result holds for discrete distributions.

## Marginal Mass/Density Functions

$$p_X(x) = \sum_y p(x,y) \qquad p_Y(y) = \sum_x p(x,y)$$
  
$$f_X(x) = \int_y f(x,y) \, dy \qquad f_Y(y) = \int_x f(x,y) \, dx$$

**Sums of Independent Variables** If *X*, *Y* are independent then

$$F_{X+Y}(a) = \mathbb{P}(X+Y \le a) = \iint_{x+y \le a} f_X(x) f_Y(y) \, \mathrm{d}x \, \mathrm{d}y = \int_{-\infty}^{\infty} F_X(a-y) f_Y(y) \, \mathrm{d}y$$

Convolution formula:

$$f_{X+Y}(a) = \int_{-\infty}^{\infty} f_X(a-y) f_Y(y) \, \mathrm{d}y$$

## **Conditional Mass/Density Functions**

$$p_{X|Y}(x|y) = \mathbb{P}(X = x|Y = y) = \frac{p(x,y)}{p_Y(y)}$$

$$f_{X|Y}(x|y) = \frac{f(x,y)}{f_Y(y)}$$
(only valid if  $p_Y(y) \neq 0$ )

**Change of Variables** If U = U(X, Y) and V = V(X, Y) are a change of variables and S, T are sets such that

$$(U,V) \in \mathcal{T} \iff (X,Y) \in \mathcal{S}$$

then

$$\iint_{\mathcal{S}} f_{X,Y}(x,y) \, \mathrm{d}x \, \mathrm{d}y = \mathbb{P}((X,Y) \in \mathcal{S}) = \mathbb{P}((U,V) \in \mathcal{T})$$
$$= \iint_{\mathcal{T}} f_{U,V}(u,v) \, \mathrm{d}u \, \mathrm{d}v$$
$$= \iint_{\mathcal{S}} f_{U,V}(u(x,y),v(x,y)) \left| \frac{\partial(u,v)}{\partial(x,y)} \right| \, \mathrm{d}x \, \mathrm{d}y$$

where  $\frac{\partial(u, v)}{\partial(x, y)} = J(x, y) = \det \begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix}$  is the Jacobian. It follows that  $f_{U,V}(u, v) = f_{X,Y}(x, y) |J(x, y)|^{-1}$ 

**Expectations** If g(X, Y) is any function, then

$$\mathbb{E}(g(X,Y)) = \iint g(x,y)f(x,y)\,\mathrm{d}x\,\mathrm{d}y \quad \text{or} \quad \sum_{x}\sum_{y}g(x,y)p(x,y)$$

- Linearity:  $\mathbb{E}(g(X) + h(Y)) = \mathbb{E}(g(X)) + \mathbb{E}(h(Y))$
- If *X*, *Y* independent, then  $\mathbb{E}(g(X)h(Y)) = \mathbb{E}(g(X))\mathbb{E}(h(Y))$
- Covariance:  $\operatorname{Cov}(X, Y) = \mathbb{E}\left[(X \mu_X)(Y \mu_Y)\right] = \mathbb{E}(XY) \mu_X \mu_Y$ , where  $\mu_X = \mathbb{E}(X)$ , etc.
- Independence  $\implies$  Cov(*X*, *Y*) = 0. Converse *false*.
- Correlation:  $\operatorname{Corr}(X, Y) = \rho(X, Y) = \frac{\operatorname{Cov}(X, Y)}{\sigma_X \sigma_Y}$
- Cauchy–Schwarz:  $-1 \le \rho \le 1$  with equality iff *X* and *Y* are linearly related. In such a case,

$$\frac{Y - \mu_Y}{\sigma_Y} = \pm \frac{X - \mu_X}{\sigma_X}$$

• Var  $\sum X_i = \sum \operatorname{Var} X_i + 2 \sum_{i \neq j} \operatorname{Cov}(X_i, X_j)$ If all  $X_i$  are pairwise independent, then  $\operatorname{Var} \sum X_i = \sum \operatorname{Var} X_i$ 

Bivariate Normal Distribution Joint density function

$$f(x,y) = \frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-\rho^2}} \exp\left\{-\frac{1}{2(1-\rho^2)} \left[\left(\frac{x-\mu_x}{\sigma_x}\right)^2 + \left(\frac{y-\mu_y}{\sigma_y}\right)^2 - 2\rho\left(\frac{x-\mu_x}{\sigma_X}\right)\left(\frac{y-\mu_y}{\sigma_y}\right)\right]\right\}$$

- *X*, *Y* independent iff  $\rho = 0$
- $X \sim N(\mu_X, \sigma_X^2)$   $Y \sim N(\mu_Y, \sigma_Y^2)$
- $Corr(X, Y) = \rho$

• 
$$X|Y = y \sim N\left(\mu_X + \rho\sigma_X \frac{y - \mu_Y}{\sigma_Y}, (1 - \rho^2)\sigma_X^2\right)$$

**Sample Mean and Variance** If  $X_1, ..., X_n$  are identically distributed random variables, then the *sample mean* is the random variable

$$\overline{X} = \frac{1}{n} \sum_{i=1}^{n} X_i$$

Idea: each  $X_i$  is the result of an independent trial/measurement from a large population. If population (each of the  $X_i$ 's distributions) has mean  $\mu$  and variance  $\sigma^2$ , then the sample mean may be used to estimate  $\mu$ :

 $\mathbb{E}(\overline{X}) = \mu$ 

The *sample variance* is the random variable

$$S^{2} = \frac{1}{n-1} \sum_{i=1}^{n} (X_{i} - \overline{X})^{2}$$

This estimates the population variance:  $\mathbb{E}(S^2) = \sigma^2$ . The larger the sample, the smaller the variance of the sample mean:

$$\operatorname{Var} \overline{X} = \frac{\sigma^2}{n}$$

**Conditional Expectations**  $\mathbb{E}(X|Y) = \mathbb{E}(X|Y = y)$  is a function of *y* Conditioning: for any *intermediate variable Y* 

$$\mathbb{E}(X) = \mathbb{E}(\mathbb{E}(X|Y)) = \int_{y} \mathbb{E}(X|Y=y) f_{Y}(y) \, \mathrm{d}y \quad \text{or} \quad \sum_{y} \mathbb{E}(X|Y=y) p_{Y}(y)$$

Idea: average of X equals the average over Y of all of the averages of X given Y.

**Prediction** If *X*, *Y* have finite variances, then the best linear predictor of *X* given Y = y is

$$X \approx g(y) = \mu_X + \rho \sigma_X \left(\frac{y - \mu_Y}{\sigma_Y}\right)$$

Among all linear functions of *Y*, the linear predictor minimizes the functional

$$\mathbb{E}\left[(X - g(Y))^2\right] \tag{(*)}$$

Among all functions of *Y*, the function which minimizes (\*) is

$$g(Y) = \mathbb{E}(X|Y)$$

**Conditional Variance** Var(X|Y) is also a function of Y = y. Indeed

$$\operatorname{Var}(X|Y = y) = \mathbb{E}\left(\left(X - \mathbb{E}(X|Y)\right)^2 | Y = y\right)$$
$$= \mathbb{E}\left(X^2 | Y = y\right) - \left(\mathbb{E}(X|Y = y)\right)^2$$

Can condition to compute variances

 $\operatorname{Var} X = \mathbb{E} \left( \operatorname{Var}(X|Y) \right) + \operatorname{Var} \left( \mathbb{E}(X|Y) \right)$ 

#### Moments

(*Raw*) Moments  $\mathbb{E}(X^n)$  where n = 1, 2, 3, ...

*Central Moments*  $\mathbb{E}[(X - \mu)^n]$  where  $\mu = \mathbb{E}(X)$ 

Higher moments give more information on shape of a distribution: e.g. third central moment related to skewness of distribution.

General idea: know the moments, know the distribution (or at least can approximate to any accuracy)

**Moments of number of events which occur** Write  $X = \sum X_i$  where  $X_i$  is the indicator for an event. Then X is the number of events which occur.

Events:

$$\mathbb{E}(X) = \sum \mathbb{E}(X_i) = \sum \mathbb{P}(X_i = 1)$$

Pairs:

$$\mathbb{E}\binom{X}{2} = \sum_{i < j} \mathbb{E}(X_i X_j) = \sum_{i < j} \mathbb{P}(X_i = 1, X_j = 1)$$

Triples (etc.):

$$\mathbb{E}\binom{X}{3} = \sum_{i < j < k} \mathbb{E}(X_i X_j X_k) = \sum_{i < j < k} \mathbb{P}(X_i = 1, X_j = 1, X_k = 1)$$

Since  $\mathbb{E}\binom{X}{2} = \frac{1}{2} \left( \mathbb{E}(X^2) - \mathbb{E}(X) \right)$  can use to compute Variance.

**Moment generating functions**  $M_X(t) = \mathbb{E}(e^{tX}) = \sum_{n=0}^{\infty} \frac{\mathbb{E}(X^n)}{n!} t^n$ 

Recover raw moments:  $\mathbb{E}(X^n) = M_X^{(n)}(0)$ 

Independence: If *X*, *Y* independent then  $M_{X+Y}(t) = M_X(t)M_Y(t)$ 

#### **Limit Theorems**

Markov's inequality: if *X* is non-negative, then

$$\mathbb{P}(X \ge a) \le \frac{1}{a} \mathbb{E}(X)$$

Chebyshev's inequality: if *X* has finite mean  $\mu$  and variance  $\sigma^2$ , then

$$\mathbb{P}(|X-\mu| \ge k) \le \frac{\sigma^2}{k^2}$$

Typically the estimates provided by these inequalities are very poor.

**Weak law of large numbers** Probability that average is far-away from  $\mu$  goes to zero as  $n \to \infty$ . If  $X_1, X_2, \ldots$  are independent and identically distributed with mean  $\mu$  and finite variance  $\sigma^2$ , then, for all  $\varepsilon > 0$ 

$$\mathbb{P}\left(\left|\frac{X_1 + \dots + X_n}{n} - \mu\right| \ge \varepsilon\right) \le \frac{\sigma^2}{n\varepsilon^2} \underset{n \to \infty}{\longrightarrow} 0$$

Weak law still true when variance is infinite, but not so useful for estimating. Can use to answer questions such as:

How many measurements/trials needed in order to be p% sure that our average is within q% of the population mean?

**Central Limit Theorem** Loosely: If *X* has mean  $\mu$  and variance  $\sigma^2$  and can be viewed as the sum of a large number of independent variables, then *X* is approximately  $N(\mu, \sigma^2)$  distributed. A simpler, more precise version: Let  $X_1, X_2, \ldots$  be independent identically distributed variables with mean  $\mu$  and variance  $\sigma^2$ . Then

$$\mathbb{P}\left\{\frac{X_1 + \dots + X_n - n\mu}{\sigma\sqrt{n}} \le a\right\} = \mathbb{P}\left\{\frac{1}{\sigma/\sqrt{n}}(\overline{X} - \mu) \le a\right\} \underset{n \to \infty}{\longrightarrow} \Phi(a)$$

Alternatively:

- $X_1 + X_2 + \cdots + X_n$  is approximately  $N(n\mu, n\sigma^2)$  for large *n*
- The sample mean  $\overline{X}$  is approximately  $N(\mu, \frac{\sigma^2}{n})$  distributed for large *n*.

**Strong Law of Large Numbers** If  $X_1, \ldots$  are independent identically distributed random variables then

$$\mathbb{P}\left(\lim_{n\to\infty}\frac{X_1+\cdots+X_n}{n}=\mu\right)=1$$

Intuitively: the long term frequency of an event happening given many repeated trials equals the probability of said event happening.