(A) Rotation followed by a translation:

Sola: $R_{\theta} v+a=v$ (gums this is a
gut $v=\left(I-R_{\theta}\right)^{-1} a$ rotation)
$\left(I-R_{0}\right)$ is invertible.

Rofetz w around $u$ produces:

$$
R_{0}(w-v)+v
$$

why? $R_{t}(w)+a$


$$
\begin{aligned}
& =R_{\theta}(w-v)+R_{\theta} v+a \\
& =R_{\theta}(w-v)+R_{\theta}\left(I-R_{\theta}\right)^{-1} a+a \\
& =R_{\theta}(w-v)+\left(R_{\theta}-I\right)\left(I-R_{b}\right)^{+} a+\left(I-R_{\theta}\right)^{-1} a+a \\
& =R_{t}(w-v)-a+d^{+}+a=R(w-v)+v .
\end{aligned}
$$

(B) Central reflection followed by a translation:

This is NOT a REflection
Issue: I-M is Not invertible (Mors eigrnvahus an $7,-1)$
Excocose: Show Central reflections fix 2 lines:
a) The axis of $B f(c x t i o n$
b) The line $i$ to That $a$ ais thru 0 .

SPECIAL CASE: The dinction of translation is la to The axis of reflection-

