

The inverse of A Matrix

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In This section, we investigate the matrix analogue of the reciprocal, or multiplicative inverse, of a nonzero number.

Recall $5^{-1} \cdot 5 = 1$ & $5 \cdot 5^{-1} = 1$.

In matrices, an $n \times n$ matrix A is said to be **invertible** if there is an $n \times n$ matrix C such that $CA = I_{n \times n}$ and $AC = I_{n \times n}$. matrix C in this case is the inverse of matrix A . C is uniquely determined by A . This unique inverse is denoted by A^{-1} . so:

$$AA^{-1} = A^{-1}A = I$$

Def.: A matrix that is not invertible is sometimes called a **singular matrix** and invertible matrix is called a nonsingular matrix.

Ex. If $A = \begin{bmatrix} 2 & 5 \\ -3 & -7 \end{bmatrix}$ and $C = \begin{bmatrix} -7 & -5 \\ 3 & 2 \end{bmatrix}$, show that $C = A^{-1}$.

$$AC = \begin{bmatrix} 2 & 5 \\ -3 & -7 \end{bmatrix} \begin{bmatrix} -7 & -5 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} -14+15 & -10+10 \\ 21-21 & 15-14 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$\Rightarrow A^{-1} = C$$

$$CA = \begin{bmatrix} -7 & -5 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 2 & 5 \\ -3 & -7 \end{bmatrix} = \begin{bmatrix} -14+15 & -35+35 \\ 6-6 & 15-14 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

Theorem: Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. If $ad - bc \neq 0$, Then A is invertible and $A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$. If $ad - bc = 0$, Then A is not invertible.

* $ad - bc$ is called the determinant of A .

$$\det A = ad - bc$$

Ex. Find inverse of $A = \begin{bmatrix} 3 & 4 \\ 5 & 6 \end{bmatrix}$.

$$\det A = 18 - 20 = -2 \quad \rightarrow \quad A^{-1} = -\frac{1}{2} \begin{bmatrix} 6 & -4 \\ -5 & 3 \end{bmatrix}$$

Theorem:

If A is an invertible $n \times n$ matrix, then for each $\vec{b}$ in $\mathbb{R}^n$, the eq. $A\vec{x} = \vec{b}$ has the unique solution $\vec{x} = A^{-1}\vec{b}$.

(This formula in reality is never used to solve systems of eqs. as row reduction of the augmented matrix $[A \ b]$ is almost always faster).

Ex. Use the inverse of the matrix A in the previous example to solve the system:

$$\begin{cases} 3x_1 + 4x_2 = 3 \\ 5x_1 + 6x_2 = 7 \end{cases} \quad \rightarrow \quad A\vec{x} = \vec{b} \Rightarrow \begin{bmatrix} 3 & 4 \\ 5 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 7 \end{bmatrix}$$

$$\Rightarrow \vec{x} = -\frac{1}{2} \begin{bmatrix} 6 & -4 \\ -5 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ 7 \end{bmatrix} \Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 18 - 28 \\ -15 + 21 \end{bmatrix}$$

$$= -\frac{1}{2} \begin{bmatrix} -10 \\ +6 \end{bmatrix} = \begin{bmatrix} 5 \\ -3 \end{bmatrix}$$

Theorem: * If A is an invertible matrix, then A^{-1} is invertible & $(A^{-1})^{-1} = A$

* If A & B are $n \times n$ invertible matrices, then so is AB and $(AB)^{-1} = B^{-1}A^{-1}$

* If A is an invertible matrix, then so is A^T , and the inverse of A^T is the transpose of A^{-1} . That is:

$$(A^T)^{-1} = (A^{-1})^T$$

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Elementary Matrices:

An elementary matrix is a matrix that is obtained by performing a single elementary row operation on an identity matrix.

- * The rows of an identity matrix can be multiplied by a number.
- * Multiple of a row may be added to another row
- * a row may be replaced by another row.

Ex. let $E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & 0 & 1 \end{bmatrix}$, $E_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 6 & 5 \end{bmatrix}$, and $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$.

Compute $E_1 A$, $E_2 A$, & $E_3 A$.

$$E_1 A = \begin{bmatrix} a & b & c \\ d & e & f \\ g-4a & h-4b & i-4c \end{bmatrix} \quad E_2 A = \begin{bmatrix} d & e & f \\ a & b & c \\ g & h & i \end{bmatrix} \quad E_3 A = \begin{bmatrix} a & b & c \\ d & e & f \\ 5g & 5h & 5i \end{bmatrix}$$

The take home message from the previous example is:

- * If an elementary operation is performed on an $m \times n$ matrix A , The resulting matrix can be written as EA , where the $m \times m$ matrix is created by performing the same row operation on I_m .

- * **Important** * Each elementary matrix is invertible. the inverse of E is the elementary matrix of the same type that transforms E back to I .

Ex. Find The inverse of $E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & 0 & 1 \end{bmatrix}$

To transform E_1 to I , we have added (4 times row 1) to row 3.

The elementary matrix that does this is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ +4 & 0 & 1 \end{bmatrix}$

Notice the difference in sign.

Very important Theorem:

An $n \times n$ matrix A is invertible iff (if and only if) A is row equivalent to I_n . It means, any sequence of elementary row operations that reduces A to I_n , transforms I_n into A^{-1} .

An Algorithm for finding A^{-1} :

The previous theorem provides a very useful technique to find A^{-1} for a matrix. If we form the augmented matrix $[A \ I]$ and by row operations we convert A to I , the same row operations will convert I to A^{-1} if the matrix A is invertible.

Ex. Find the inverse of matrix $A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 4 & -3 & 8 \end{bmatrix}$

$$[A \ I] = \begin{bmatrix} 0 & 1 & 2 & 1 & 0 & 0 \\ 1 & 0 & 3 & 0 & 1 & 0 \\ 4 & -3 & 8 & 0 & 0 & 1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 2 & 1 & 0 & 0 \\ 4 & -3 & 8 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 2 & 1 & 0 & 0 \\ 0 & -3 & -4 & 0 & -4 & 1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 3 & -4 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 & 0 & 1 & 0 \\ 0 & 1 & 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 3/2 & -2 & 1/2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & -9/2 & 7 & -3/2 \\ 0 & 1 & 0 & -2 & 4 & -1 \\ 0 & 0 & 1 & 3/2 & -2 & 1/2 \end{bmatrix} \Rightarrow A^{-1} = \begin{bmatrix} -9/2 & 7 & -3/2 \\ -2 & 4 & -1 \\ 3/2 & -2 & 1/2 \end{bmatrix}$$

You can double check your work by calculating AA^{-1} to see if you obtain I