

Functional Analysis (602, Real Analysis II)

Fall 2009

- Webpage
- Prerequisites: $\left\{ \begin{array}{l} \text{point-set topology (590),} \\ \text{real analysis (597)} \end{array} \right.$

From topology: $\left\{ \begin{array}{l} \text{metric spaces, compactness, completeness etc.} \\ \xrightarrow{\text{review e.g. [BS]}} \end{array} \right.$

From analysis: $\left\{ \begin{array}{l} \text{measure theory (Lebesgue measure, integral),} \\ \text{Hölder, Minkowski inequalities.} \\ \text{Some Fourier analysis.} \end{array} \right.$

Lecture 1

I. BANACH & HILBERT SPACES

Development of analysis :

numbers \rightarrow functions

{ numbers (before XVIIc)

functions (~~differential and integral calculus~~)
(derivative, integral)

↓
sequences of functions (Weierstrass etc.) - XIX.
convergence Series, e.g. Taylor, Fourier

↓
spaces of functions (functional analysis) - XX.

↓
? - XXI.

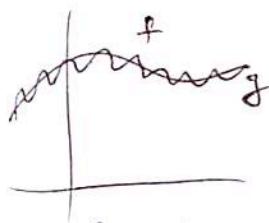
Why spaces of functions?

- Geometric view: look at functions as points in some "function space", or rather as vectors.

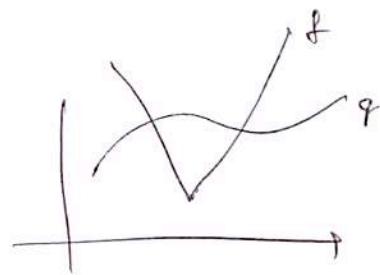


One can add functions, and multiply by scalars.
Hence a function space is a linear space.

- Further, one can envision a kind of distance between functions:



These two functions look "close" to each other

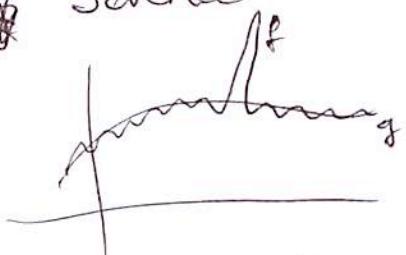


these not

- ~~Eg~~ One can define a distance e.g. by $\rho(f, g) = \sup_x |f(x) - g(x)|$.

~~This makes a function space metric space (called normed space).~~

- ~~Several natural choices of distances:~~



These f and g may look "close" even though $\rho(f, g)$ is large.

$$\rho'(f, g) = \int |f(x) - g(x)|^p dx.$$

would ~~be~~ make a better choice for a metric.

Different normed space.

- Advantages of looking at function spaces:

Consider all functions at once; soft arguments (origins - Diff Eq's)
These spaces are usually ∞ -dimensional, with complex geometry.

- Historical remarks (Banach & Polish school)

Linear spaces. [Lax] is a good source.

Examples:

- 1) ~~All real E~~ $F = \{ \text{all functions on } \mathbb{R}^n \rightarrow \mathbb{R} \}$. Huge.
- 2) $C[a,b] = \{ \text{all continuous real (or complex) valued functions on } [a,b] \rightarrow \mathbb{R} \}$.
- 3.5) $L_1^{[a,b]} = \{ \text{all integrable functions on } [a,b] \}$ or \mathbb{C} .

- 3) $P(x) = \{ \text{all polynomials in one variable} \}$
 - 4) \mathbb{R}^n and \mathbb{C}^n .
 - 5) $S = \{ \text{all sequences (of real numbers)} \}$
 - 6) $S^* = \{ \text{all sequences (of real numbers) with finite support} \}$
 - 7) $b_b = \{ \text{all bounded seq.} \}$
 - 8) $c_{\#} = \{ \text{all seq. convergent seq.} \}$
 - 9) $c_0 = \{ \text{all sequences converging to 0} \}$
- 3.5) ~~All solutions of a linear PDE in a given domain?~~

(1) - (3) are function spaces,

(4) is a f. d. space

(5) - (9) are sequence spaces: ~~stochastic~~

Def A subspace

Def (Subspace) A subset E_1 of a linear space E is a subspace of E if it is closed under linear operations in E .

Examples:

- 1) $P(x) \subset C[a,b] \subset L_1[a,b] \subset F$; $\left\{ \text{all subspaces} \right\}$
- 2) $S^* \subset c_0 \subset c \subset b_b \subset S$;

Exercise:

- (a) $\{0\}$ and X are linear subspaces of X
- (b) Intersection of ~~all~~ A collection of subspaces is a subspace.

From linear algebra,

Def (dimension), ~~Theorem~~

- 1) Let $\{e_1, \dots, e_n\}$ be a maximal set of linearly ind. vectors in E . Then n is called the dimension of E (if no such system exists, $\dim E = \infty$).
2) The dimension is independent of a particular choice of the vectors.
3) $\forall x \in E$ can be written uniquely as a linear combin.
$$x = \sum_1^n a_i e_i, \quad a_i \in \mathbb{R}$$
 $\{e_1, \dots, e_n\}$ is called a basis of E .

Example: 1) F , $C[a,b]$, $L_1(a,b)$, $P(x)$ are ∞ -dimensional

2) $\dim P_n = n$; a basis is formed by the monomials $\{1, x, x^2, \dots, x^n\}$.

3) ~~all~~ $\dim \mathbb{R}^n = n$

4) all other sequence spaces discussed are ∞ -dim.

LECTURE 2

Quotient spaces

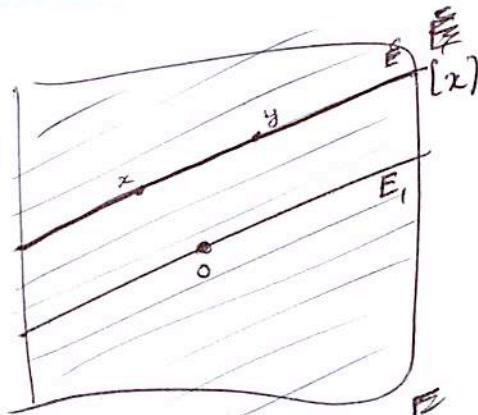
Let $E_1 \subset E$ subspace.

Consider the equivalence relation
on E :

$$x \sim y \stackrel{\text{def}}{\Rightarrow} x - y \in E_1.$$

$E/E_1 = \{ \text{equivalence classes } [x] \text{ of all } x \in E \}$,
or "cosets"

Observe that $[x] = x + E_1$



$$[x] = \{x + h, h \in E_1\}.$$

Ex

We can make E/E_1 into a linear space by defining the

$$[x] + [y] := [x+y]$$

$$\alpha[x] = [\alpha x].$$

Def E/E_1 is called the "quotient space".

dim E/E_1 is called the codimension of E ($\equiv \text{codim } E$).

~~Fact (from linear algebra)~~ If E is finite dimensional, $E \subset E_1 \rightarrow$
 $\dim E = \dim E_1 + \text{codim } E_1$

Example 1 Consider $C_0 \subset C$.

$$\text{Then codim}(C_0) = 1$$

$$\forall x \in C,$$

Example 2 $L^1[a, b]$ is formally defined as
the quotient space E/E_1 of $E = \{\text{all integrable functions}\}$
over $E_1 = \{\text{all functions supported on measure zero sets}\}$.
— allows to identify functions up to negligible sets.

2) $C_0 \subset C$. Then $\text{codim } C_0 = 1$

~~For $x \in C$: $x = y + z$, $y \in C_0$, $z = \text{constant sequence}$.~~

~~$x = y + \lambda \cdot e$, $y, \lambda \in C_0$~~

$\Rightarrow C_0^\perp =$

$\forall x \in C: x = a \mathbb{1} + z; a \in \mathbb{R}, z \in C_0$

uniquely

$\Rightarrow [x] = a[\mathbb{1}] + [z] = a[\mathbb{1}]$.

Linear operators

Def A map $A: E \rightarrow F$ between two linear spaces E and F is a ~~linea~~ called a linear operator (~~linear map~~) ~~if~~ (transformation, map)

If $A(ax + by) = aA(x) + bA(y)$ $\forall x, y \in E,$
often written as $aAx + bAy$ $\forall a, b \in \mathbb{R}$

Def $\ker(A) = \{x \in E : Ax = 0\}$
 $\text{Im}(A) = \{Ax : x \in E\}.$

Exercise A is one-to-one $\Rightarrow \ker A = \{0\}.$

Example (a) ~~$A(f) = f'$~~ , $A: P(x) \rightarrow P(x)$.

(b) ~~Embedding operator~~: $E_1 \subseteq E$

$$A: E_1 \xrightarrow{\cong} E : Ax = x$$

(c) Quotient map: $E_1 \subseteq E$

$$A: E \rightarrow E/E_1 : Ax = [x]$$

Exercise: {check linearity,
show that $\ker A = E_1$, $\text{Im } A = E/E_1$ (onto).

(d) Shift on ~~A~~ sequence space: $(Af)(k) = f(k+1), \forall f, \forall k \in \mathbb{Z}$